

TLC271, TLC271A, TLC271B  
LinCMOS™ PROGRAMMABLE LOW-POWER  
OPERATIONAL AMPLIFIERS

SLOS090C – NOVEMBER 1987 – REVISED AUGUST 1997

- **Input Offset Voltage Drift . . . Typically 0.1  $\mu$ V/Month, Including the First 30 Days**
- **Wide Range of Supply Voltages Over Specified Temperature Range:**  
 $0^{\circ}\text{C}$  to  $70^{\circ}\text{C}$  . . . 3 V to 16 V  
 $-40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$  . . . 4 V to 16 V  
 $-55^{\circ}\text{C}$  to  $125^{\circ}\text{C}$  . . . 5 V to 16 V
- **Single-Supply Operation**
- **Common-Mode Input Voltage Range Extends Below the Negative Rail (C-Suffix and I-Suffix Types)**
- **Low Noise . . . 25 nV/ $\sqrt{\text{Hz}}$  Typically at  $f = 1 \text{ kHz}$  (High-Bias Mode)**
- **Output Voltage Range includes Negative Rail**
- **High Input Impedance . . .  $10^{12} \Omega$  Typ**
- **ESD-Protection Circuitry**
- **Small-Outline Package Option Also Available in Tape and Reel**
- **Designed-In Latch-Up Immunity**

#### description

The TLC271 operational amplifier combines a wide range of input offset voltage grades with low offset voltage drift and high input impedance. In addition, the TLC271 offers a bias-select mode that allows the user to select the best combination of power dissipation and ac performance for a particular application. These devices use Texas Instruments silicon-gate LinCMOS™ technology, which provides offset voltage stability far exceeding the stability available with conventional metal-gate processes.

#### AVAILABLE OPTIONS

TA	$V_{IO\text{max}}$ AT $25^{\circ}\text{C}$	PACKAGE			
		SMALL OUTLINE (D)	CHIP CARRIER (FK)	CERAMIC DIP (JG)	PLASTIC DIP (P)
$0^{\circ}\text{C}$ to $70^{\circ}\text{C}$	2 mV 5 mV 10 mV	TLC271BCD TLC271ACD TLC271CD	—	—	TLC271BCP TLC271ACP TLC271CP
$-40^{\circ}\text{C}$ to $85^{\circ}\text{C}$	2 mV 5 mV 10 mV	TLC271BID TLC271AID TLC271ID	—	—	TLC271BIP TLC271AIP TLC271IP
$-55^{\circ}\text{C}$ to $125^{\circ}\text{C}$	10 mV	TLC271MD	TLC271MFK	TLC271MJG	TLC271MP

The D package is available taped and reeled. Add R suffix to the device type (e.g., TLC271BCDR).



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**8DEVICE FEATURES**

PARAMETER†	BIAS-SELECT MODE			UNIT
	HIGH	MEDIUM	LOW	
P <sub>D</sub>	3375	525	50	µW
SR	3.6	0.4	0.03	V/µs
V <sub>n</sub>	25	32	68	nV/√Hz
B <sub>1</sub>	1.7	0.5	0.09	MHz
A <sub>VD</sub>	23	170	480	V/mV

† Typical at V<sub>DD</sub> = 5 V, T<sub>A</sub> = 25°C

**description (continued)**

Using the bias-select option, these cost-effective devices can be programmed to span a wide range of applications that previously required BiFET, NFET or bipolar technology. Three offset voltage grades are available (C-suffix and I-suffix types), ranging from the low-cost TLC271 (10 mV) to the TLC271B (2 mV) low-offset version. The extremely high input impedance and low bias currents, in conjunction with good common-mode rejection and supply voltage rejection, make these devices a good choice for new state-of-the-art designs as well as for upgrading existing designs.

In general, many features associated with bipolar technology are available in LinCMOS™ operational amplifiers, without the power penalties of bipolar technology. General applications such as transducer interfacing, analog calculations, amplifier blocks, active filters, and signal buffering are all easily designed with the TLC271. The devices also exhibit low-voltage single-supply operation, making them ideally suited for remote and inaccessible battery-powered applications. The common-mode input voltage range includes the negative rail.

A wide range of packaging options is available, including small-outline and chip-carrier versions for high-density system applications.

The device inputs and output are designed to withstand –100-mA surge currents without sustaining latch-up.

The TLC271 incorporates internal ESD-protection circuits that prevent functional failures at voltages up to 2000 V as tested under MIL-STD-883C, Method 3015.2; however, care should be exercised in handling these devices as exposure to ESD may result in the degradation of the device parametric performance.

The C-suffix devices are characterized for operation from 0°C to 70°C. The I-suffix devices are characterized for operation from –40°C to 85°C. The M-suffix devices are characterized for operation over the full military temperature range of –55°C to 125°C.

**bias-select feature**

The TLC271 offers a bias-select feature that allows the user to select any one of three bias levels depending on the level of performance desired. The tradeoffs between bias levels involve ac performance and power dissipation (see Table 1).



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## bias-select feature (continued)

Table 1. Effect of Bias Selection on Performance

TYPICAL PARAMETER VALUES $T_A = 25^\circ\text{C}$ , $V_{DD} = 5 \text{ V}$		MODE			UNIT
		HIGH BIAS $R_L = 10 \text{ k}\Omega$	MEDIUM BIAS $R_L = 100 \text{ k}\Omega$	LOW BIAS $R_L = 1 \text{ M}\Omega$	
$P_D$	Power dissipation	3.4	0.5	0.05	mW
SR	Slew rate	3.6	0.4	0.03	V/ $\mu\text{s}$
$V_n$	Equivalent input noise voltage at $f = 1 \text{ kHz}$	25	32	68	nV/ $\sqrt{\text{Hz}}$
$B_1$	Unity-gain bandwidth	1.7	0.5	0.09	MHz
$\phi_m$	Phase margin	46°	40°	34°	
$A_{VD}$	Large-signal differential voltage amplification	23	170	480	V/mV

## bias selection

Bias selection is achieved by connecting the bias select pin to one of three voltage levels (see Figure 1). For medium-bias applications, it is recommended that the bias select pin be connected to the midpoint between the supply rails. This procedure is simple in split-supply applications, since this point is ground. In single-supply applications, the medium-bias mode necessitates using a voltage divider as indicated in Figure 1. The use of large-value resistors in the voltage divider reduces the current drain of the divider from the supply line. However, large-value resistors used in conjunction with a large-value capacitor require significant time to charge up to the supply midpoint after the supply is switched on. A voltage other than the midpoint can be used if it is within the voltages specified in Figure 1.

## bias selection (continued)

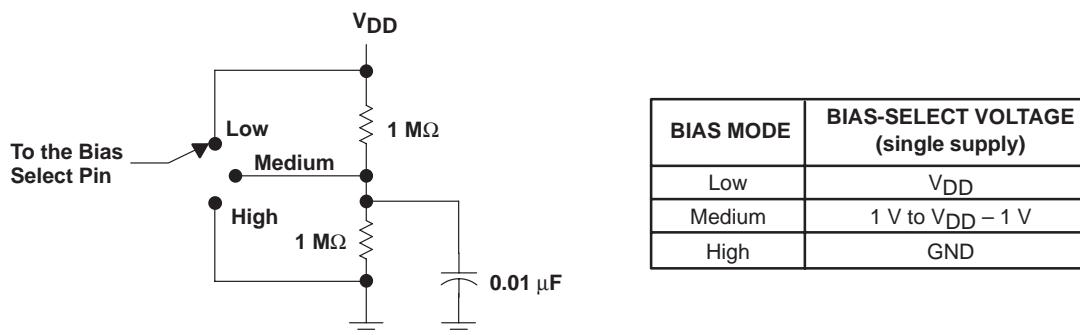


Figure 1. Bias Selection for Single-Supply Applications

## high-bias mode

In the high-bias mode, the TLC271 series features low offset voltage drift, high input impedance, and low noise. Speed in this mode approaches that of BiFET devices but at only a fraction of the power dissipation. Unity-gain bandwidth is typically greater than 1 MHz.

## medium-bias mode

The TLC271 in the medium-bias mode features low offset voltage drift, high input impedance, and low noise. Speed in this mode is similar to general-purpose bipolar devices but power dissipation is only a fraction of that consumed by bipolar devices.

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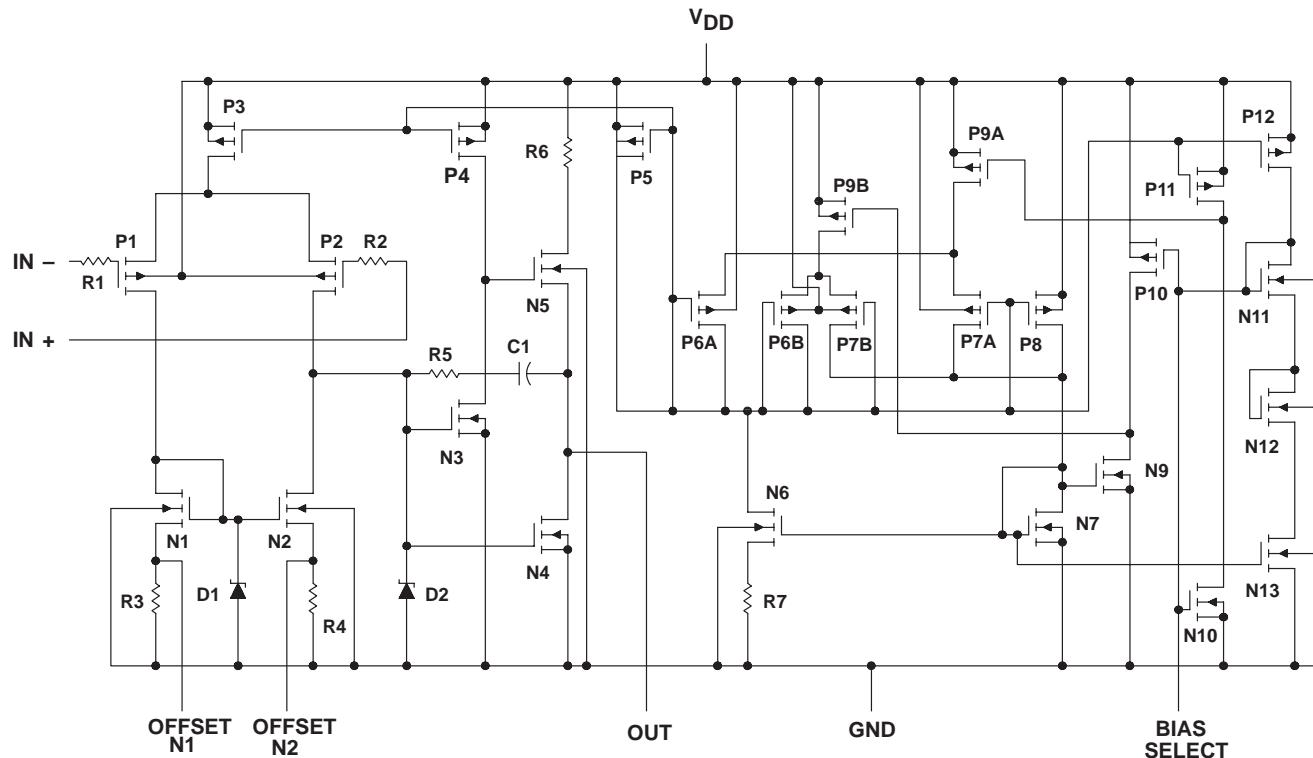
## low-bias mode

In the low-bias mode, the TLC271 features low offset voltage drift, high input impedance, extremely low power consumption, and high differential voltage gain.

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## equivalent schematic



**absolute maximum ratings over operating free-air temperature (unless otherwise noted)†**

Supply voltage, $V_{DD}$ (see Note 1)	.....	18 V
Differential input voltage, $V_{ID}$ (see Note 2)	.....	$\pm V_{DD}$
Input voltage range, $V_I$ (any input)	.....	-0.3 V to $V_{DD}$
Input current, $I_I$	.....	$\pm 5$ mA
Output current, $I_O$	.....	$\pm 30$ mA
Duration of short-circuit current at (or below) 25°C (see Note 3)	.....	Unlimited
Continuous total dissipation	.....	See Dissipation Rating Table
Operating free-air temperature, $T_A$ : C suffix	.....	0°C to 70°C
I suffix	.....	-40°C to 85°C
M suffix	.....	-55°C to 125°C
Storage temperature range	.....	-65°C to 150°C
Case temperature for 60 seconds: FK package	.....	260°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds: D or P package	.....	260°C
Lead temperature 1,6 mm (1/16 inch) from case for 60 seconds: JG package	.....	300°C

† Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. All voltage values, except differential voltages, are with respect to network ground.

2. Differential voltages are at IN+ with respect to IN-.

3. The output may be shorted to either supply. Temperature and/or supply voltages must be limited to ensure that the maximum dissipation rating is not exceeded (see application section).

**DISSIPATION RATING TABLE**

PACKAGE	$T_A \leq 25^\circ\text{C}$ POWER RATING	DERATING FACTOR ABOVE $T_A = 25^\circ\text{C}$	$T_A = 70^\circ\text{C}$ POWER RATING		$T_A = 85^\circ\text{C}$ POWER RATING		$T_A = 125^\circ\text{C}$ POWER RATING	
			MIN	MAX	MIN	MAX	MIN	MAX
D	725 mW	5.8 mW/°C	464 mW		377 mW		145 mW	
FK	1375 mW	11.0 mW/°C	880 mW		715 mW		275 mW	
JG	1050 mW	8.4 mW/°C	672 mW		546 mW		210 mW	
P	1000 mW	8.0 mW/°C	640 mW		520 mW		200 mW	

**recommended operating conditions**

		C SUFFIX		I SUFFIX		M SUFFIX		UNIT
		MIN	MAX	MIN	MAX	MIN	MAX	
Supply voltage, $V_{DD}$		3	16	4	16	5	16	V
Common-mode input voltage, $V_{IC}$	$V_{DD} = 5\text{ V}$	-0.2	3.5	-0.2	3.5	0	3.5	V
	$V_{DD} = 10\text{ V}$	-0.2	8.5	-0.2	8.5	0	8.5	
Operating free-air temperature, $T_A$		0	70	-40	85	-55	125	°C

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**HIGH-BIAS MODE**

**electrical characteristics at specified free-air temperature (unless otherwise noted)**

PARAMETER		TEST CONDITIONS	TA <sup>†</sup>	TLC271C, TLC271AC, TLC271BC						UNIT	
				V <sub>DD</sub> = 5 V			V <sub>DD</sub> = 10 V				
				MIN	TYP	MAX	MIN	TYP	MAX		
V <sub>IO</sub>	Input offset voltage	V <sub>O</sub> = 1.4 V, V <sub>IC</sub> = 0 V, R <sub>S</sub> = 50 Ω, R <sub>L</sub> = 10 kΩ	25°C	1.1	10		1.1	10		mV	
			Full range		12			12			
			25°C	0.9	5		0.9	5			
			Full range		6.5			6.5			
			25°C	0.34	2		0.39	2			
			Full range		3			3			
αV <sub>IO</sub>	Average temperature coefficient of input offset voltage		25°C to 70°C	1.8			2			μV/°C	
I <sub>IO</sub>	Input offset current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.1			0.1			pA	
			70°C	7	300		7	300			
I <sub>IB</sub>	Input bias current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.6			0.7			pA	
			70°C	40	600		50	600			
V <sub>ICR</sub>	Common-mode input voltage range (see Note 5)		25°C	-0.2 to 4	-0.3 to 4.2		-0.2 to 9	-0.3 to 9.2		V	
			Full range	-0.2 to 3.5			-0.2 to 8.5			V	
			25°C	3.2	3.8		8	8.5		V	
			0°C	3	3.8		7.8	8.5			
V <sub>OH</sub>	High-level output voltage	V <sub>ID</sub> = 100 mV, R <sub>L</sub> = 10 kΩ	70°C	3	3.8		7.8	8.4			
			25°C	0	50		0	50		mV	
			0°C	0	50		0	50			
V <sub>OL</sub>	Low-level output voltage	V <sub>ID</sub> = -100 mV, I <sub>OL</sub> = 0	70°C	0	50		0	50		mV	
			25°C	5	23		10	36		V/mV	
			0°C	4	27		7.5	42			
AVD	Large-signal differential voltage amplification	R <sub>L</sub> = 10 kΩ, See Note 6	70°C	4	20		7.5	32		V/mV	
			25°C	65	80		65	85			
			0°C	60	84		60	88			
CMRR	Common-mode rejection ratio	V <sub>IC</sub> = V <sub>ICR</sub> min	70°C	60	85		60	88		dB	
			25°C	65	95		65	95			
			0°C	60	94		60	94			
k <sub>SVR</sub>	Supply-voltage rejection ratio (ΔV <sub>DD</sub> /ΔV <sub>IO</sub> )	V <sub>DD</sub> = 5 V to 10 V V <sub>O</sub> = 1.4 V	70°C	60	96		60	96		dB	
			25°C	-1.4			-1.9				
			0°C	675	1600		950	2000			
I <sub>DD</sub>	Supply current	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2, No load	0°C	775	1800		1125	2200		μA	
			70°C	575	1300		750	1700			

<sup>†</sup> Full range is 0°C to 70°C.

- NOTES: 4. The typical values of input bias current and input offset current below 5 pA were determined mathematically.  
 5. This range also applies to each input individually.  
 6. At V<sub>DD</sub> = 5 V, V<sub>O</sub> = 0.25 V to 2 V; at V<sub>DD</sub> = 10 V, V<sub>O</sub> = 1 V to 6 V.



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### HIGH-BIAS MODE

**electrical characteristics at specified free-air temperature (unless otherwise noted)**

PARAMETER		TEST CONDITIONS	TA <sup>†</sup>	TLC271I, TLC271AI, TLC271BI						UNIT	
				V <sub>DD</sub> = 5 V			V <sub>DD</sub> = 10 V				
				MIN	TYP	MAX	MIN	TYP	MAX		
V <sub>IO</sub>	Input offset voltage	V <sub>O</sub> = 1.4 V, V <sub>IC</sub> = 0 V, R <sub>S</sub> = 50 Ω, R <sub>L</sub> = 10 kΩ	25°C	1.1	10		1.1	10		mV	
			Full range		13			13			
			25°C	0.9	5		0.9	5			
			Full range		7			7			
			25°C	0.34	2		0.39	2			
			Full range		3.5			3.5			
α <sub>VIO</sub>	Average temperature coefficient of input offset voltage		25°C to 85°C	1.8			2			μV/°C	
I <sub>IO</sub>	Input offset current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.1			0.1			pA	
			85°C	24	1000		26	1000			
I <sub>IB</sub>	Input bias current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.6			0.7			pA	
			85°C	200	2000		220	2000			
V <sub>ICR</sub>	Common-mode input voltage range (see Note 5)		25°C	-0.2 to 4	-0.3 to 4.2		-0.2 to 9	-0.3 to 9.2		V	
			Full range	-0.2 to 3.5			-0.2 to 8.5			V	
V <sub>OH</sub>	High-level output voltage	V <sub>ID</sub> = 100 mV, R <sub>L</sub> = 10 kΩ	25°C	3.2	3.8		8	8.5		V	
			-40°C	3	3.8		7.8	8.5			
			85°C	3	3.8		7.8	8.5			
V <sub>OL</sub>	Low-level output voltage	V <sub>ID</sub> = -100 mV, I <sub>OL</sub> = 0	25°C	0	50		0	50		mV	
			-40°C	0	50		0	50			
			85°C	0	50		0	50			
A <sub>VD</sub>	Large-signal differential voltage amplification	R <sub>L</sub> = 10 kΩ, See Note 6	25°C	5	23		10	36		V/mV	
			-40°C	3.5	32		7	46			
			85°C	3.5	19		7	31			
CMRR	Common-mode rejection ratio	V <sub>IC</sub> = V <sub>ICRmin</sub>	25°C	65	80		65	85		dB	
			-40°C	60	81		60	87			
			85°C	60	86		60	88			
k <sub>SVR</sub>	Supply-voltage rejection ratio (ΔV <sub>DD</sub> /ΔV <sub>IO</sub> )	V <sub>DD</sub> = 5 V to 10 V V <sub>O</sub> = 1.4 V	25°C	65	95		65	95		dB	
			-40°C	60	92		60	92			
			85°C	60	96		60	96			
I <sub>I(SEL)</sub>	Input current (BIAS SELECT)	V <sub>I(SEL)</sub> = 0	25°C	-1.4			-1.9			μA	
I <sub>DD</sub>	Supply current	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2, No load	25°C	675	1600		950	2000		μA	
			-40°C	950	2200		1375	2500			
			85°C	525	1200		725	1600			

<sup>†</sup> Full range is -40°C to 85°C.

- NOTES: 4. The typical values of input bias current and input offset current below 5 pA were determined mathematically.  
5. This range also applies to each input individually.  
6. At V<sub>DD</sub> = 5 V, V<sub>O</sub> = 0.25 V to 2 V; at V<sub>DD</sub> = 10 V, V<sub>O</sub> = 1 V to 6 V.

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**HIGH-BIAS MODE**

**electrical characteristics at specified free-air temperature (unless otherwise noted)**

PARAMETER	TEST CONDITIONS	TA <sup>†</sup>	TLC271M						UNIT	
			V <sub>DD</sub> = 5 V			V <sub>DD</sub> = 10 V				
			MIN	TYP	MAX	MIN	TYP	MAX		
V <sub>IO</sub> Input offset voltage	V <sub>O</sub> = 1.4 V, V <sub>IC</sub> = 0 V, R <sub>S</sub> = 50 Ω, R <sub>L</sub> = 10 kΩ	25°C	1.1	10		1.1	10		mV	
		Full range		12			12			
αV <sub>IO</sub> Average temperature coefficient of input offset voltage		25°C to 125°C		2.1			2.2		μV/°C	
I <sub>IO</sub> Input offset current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.1			0.1			pA	
		125°C	1.4	15		1.8	15		nA	
I <sub>IB</sub> Input bias current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.6			0.7			pA	
		125°C	9	35		10	35		nA	
V <sub>ICR</sub> Common-mode input voltage range (see Note 5)		25°C	0 to 4	-0.3 to 4.2		0 to 9	-0.3 to 9.2		V	
		Full range	0 to 3.5		0 to 8.5				V	
		25°C	3.2	3.8		8	8.5		V	
		-55°C	3	3.8		7.8	8.5			
V <sub>OH</sub> High-level output voltage	V <sub>ID</sub> = 100 mV, R <sub>L</sub> = 10 kΩ	125°C	3	3.8		7.8	8.4			
		25°C	0	50		0	50		mV	
		-55°C	0	50		0	50			
V <sub>OL</sub> Low-level output voltage	V <sub>ID</sub> = -100 mV, I <sub>OL</sub> = 0	125°C	0	50		0	50		mV	
		25°C	5	23		10	36			
		-55°C	3.5	35		7	50			
AVD Large-signal differential voltage amplification	R <sub>L</sub> = 10 kΩ, See Note 6	125°C	3.5	16		7	27		V/mV	
		25°C	65	80		65	85			
		-55°C	60	81		60	87			
CMRR Common-mode rejection ratio	V <sub>IC</sub> = V <sub>ICRmin</sub>	125°C	60	84		60	86		dB	
		25°C	65	95		65	95			
		-55°C	60	90		60	90			
k <sub>SVR</sub> Supply-voltage rejection ratio (ΔV <sub>DD</sub> /ΔV <sub>IO</sub> )	V <sub>DD</sub> = 5 V to 10 V V <sub>O</sub> = 1.4 V	125°C	60	97		60	97		dB	
I <sub>I(SEL)</sub> Input current (BIAS SELECT)	V <sub>I(SEL)</sub> = 0	25°C		-1.4			-1.9		μA	
-55°C										
I <sub>DD</sub> Supply current	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2, No load	125°C	475	1100		625	1400		μA	
		25°C	675	1600		950	2000			
		-55°C	1000	2500		1475	3000			

<sup>†</sup> Full range is -55°C to 125°C.

- NOTES: 4. The typical values of input bias current and input offset current below 5 pA were determined mathematically.  
 5. This range also applies to each input individually.  
 6. At V<sub>DD</sub> = 5 V, V<sub>O</sub> = 0.25 V to 2 V; at V<sub>DD</sub> = 10 V, V<sub>O</sub> = 1 V to 6 V.



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### HIGH-BIAS MODE

**operating characteristics at specified free-air temperature,  $V_{DD} = 5\text{ V}$**

PARAMETER	TEST CONDITIONS	TA	TLC271C, TLC271AC, TLC271BC			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 10\text{ k}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	3.6		V/ $\mu\text{s}$
			0°C	4		
			70°C	3		
		$V_I(\text{PP}) = 2.5\text{ V}$	25°C	2.9		
			0°C	3.1		
			70°C	2.5		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	25		nV/ $\sqrt{\text{Hz}}$
$B_{\text{OM}}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 10\text{ k}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	320		kHz
			0°C	340		
			70°C	260		
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	25°C	1.7		MHz
			0°C	2		
			70°C	1.3		
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ ,	$f = B_1$ , See Figure 100	25°C	46°		
			0°C	47°		
			70°C	44°		

**operating characteristics at specified free-air temperature,  $V_{DD} = 10\text{ V}$**

PARAMETER	TEST CONDITIONS	TA	TLC271C, TLC271AC, TLC271BC			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 10\text{ k}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	5.3		V/ $\mu\text{s}$
			0°C	5.9		
			70°C	4.3		
		$V_I(\text{PP}) = 5.5\text{ V}$	25°C	4.6		
			0°C	5.1		
			70°C	3.8		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	25		nV/ $\sqrt{\text{Hz}}$
$B_{\text{OM}}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 10\text{ k}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	200		kHz
			0°C	220		
			70°C	140		
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	25°C	2.2		MHz
			0°C	2.5		
			70°C	1.8		
$\phi_m$ Phase margin	$f = B_1$ , $C_L = 20\text{ pF}$ ,	$V_I = 10\text{ mV}$ , See Figure 100	25°C	49°		
			0°C	50°		
			70°C	46°		

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**HIGH-BIAS MODE**

**operating characteristics at specified free-air temperature,  $V_{DD} = 5\text{ V}$**

PARAMETER	TEST CONDITIONS	$T_A$	TLC271I, TLC271AI, TLC271BI			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 10\text{ k}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	3.6		V/ $\mu\text{s}$
			-40°C	4.5		
			85°C	2.8		
			25°C	2.9		
		$V_I(\text{PP}) = 2.5\text{ V}$	-40°C	3.5		
			85°C	2.3		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	25		nV/ $\sqrt{\text{Hz}}$
$B_{\text{OM}}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 10\text{ k}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	320		kHz
			-40°C	380		
			85°C	250		
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	25°C	1.7		MHz
			-40°C	2.6		
			85°C	1.2		
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ ,	$f = B_1$ , See Figure 100	25°C	46°		
			-40°C	49°		
			85°C	43°		

**operating characteristics at specified free-air temperature,  $V_{DD} = 10\text{ V}$**

PARAMETER	TEST CONDITIONS	$T_A$	TLC271I, TLC271AI, TLC271BI			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 10\text{ k}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	5.3		V/ $\mu\text{s}$
			-40°C	6.8		
			85°C	4		
			25°C	4.6		
		$V_I(\text{PP}) = 5.5\text{ V}$	-40°C	5.8		
			85°C	3.5		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	25		nV/ $\sqrt{\text{Hz}}$
$B_{\text{OM}}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 10\text{ k}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	200		kHz
			-40°C	260		
			85°C	130		
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	25°C	2.2		MHz
			-40°C	3.1		
			85°C	1.7		
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ ,	$f = B_1$ , See Figure 100	25°C	49°		
			-40°C	52°		
			85°C	46°		

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### HIGH-BIAS MODE

**operating characteristics at specified free-air temperature,  $V_{DD} = 5\text{ V}$**

PARAMETER	TEST CONDITIONS	TA	TLC271M			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 10\text{ k}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	3.6		V/ $\mu\text{s}$
			-55°C	4.7		
		$V_I(\text{PP}) = 2.5\text{ V}$	125°C	2.3		
			25°C	2.9		
			-55°C	3.7		
			125°C	2		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	25		nV/ $\sqrt{\text{Hz}}$
$B_{\text{OM}}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 10\text{ k}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	320		kHz
			-55°C	400		
			125°C	230		
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	25°C	1.7		MHz
			-55°C	2.9		
			125°C	1.1		
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ ,	$f = B_1$ , See Figure 100	25°C	46°		
			-55°C	49°		
			125°C	41°		

**operating characteristics at specified free-air temperature,  $V_{DD} = 10\text{ V}$**

PARAMETER	TEST CONDITIONS	TA	TLC271M			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 10\text{ k}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	5.3		V/ $\mu\text{s}$
			-55°C	7.1		
		$V_I(\text{PP}) = 5.5\text{ V}$	125°C	3.1		
			25°C	4.6		
			-55°C	6.1		
			125°C	2.7		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	25		nV/ $\sqrt{\text{Hz}}$
$B_{\text{OM}}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 10\text{ k}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	200		kHz
			-55°C	280		
			125°C	110		
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	25°C	2.2		MHz
			-55°C	3.4		
			125°C	1.6		
$\phi_m$ Phase margin	$f = B_1$ ,	$V_I = 10\text{ mV}$ , See Figure 100	25°C	49°		
			-55°C	52°		
			125°C	44°		

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**TYPICAL CHARACTERISTICS (HIGH-BIAS MODE)**

**Table of Graphs**

			<b>FIGURE</b>
$V_{IO}$	Input offset voltage	Distribution	2, 3
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$V_{OH}$	High-level output voltage	vs High-level output current vs Supply voltage vs Free-air temperature	6, 7 8 9
$V_{OL}$	Low-level output voltage	vs Common-mode input voltage vs Differential input voltage vs Free-air temperature vs Low-level output current	10, 11 12 13 14, 15
$A_{VD}$	Large-signal differential voltage amplification	vs Supply voltage vs Free-air temperature vs Frequency	16 17 28, 29
$I_{IB}$	Input bias current	vs Free-air temperature	18
$I_{IO}$	Input offset current	vs Free-air temperature	18
$V_{IC}$	Common-mode input voltage	vs Supply voltage	19
$I_{DD}$	Supply current	vs Supply voltage vs Free-air temperature	20 21
SR	Slew rate	vs Supply voltage vs Free-air temperature	22 23
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$V_{O(PP)}$	Maximum peak-to-peak output voltage	vs Frequency	25
$B_1$	Unity-gain bandwidth	vs Free-air temperature vs Supply voltage	26 27
$A_{VD}$	Large-signal differential voltage amplification	vs Frequency	28, 29
$\phi_m$	Phase margin	vs Supply voltage vs Free-air temperature vs Capacitive load	30 31 32
$V_n$	Equivalent input noise voltage	vs Frequency	33
	Phase shift	vs Frequency	28, 29

### TYPICAL CHARACTERISTICS (HIGH-BIAS MODE)†

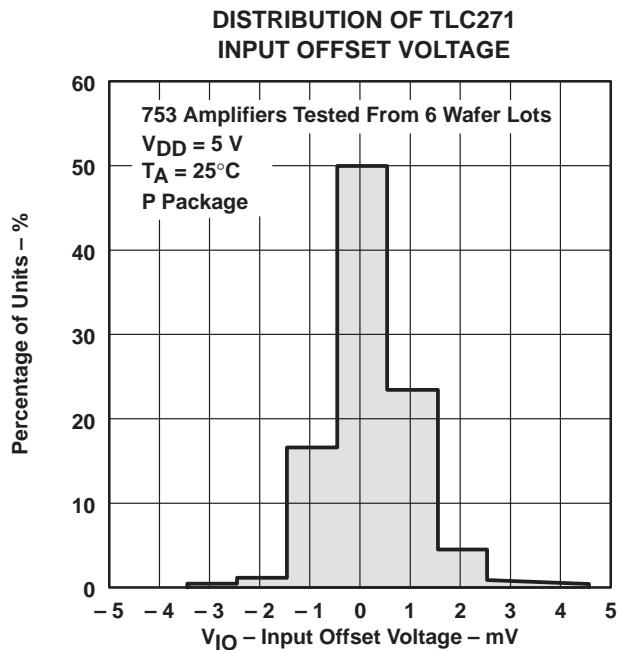


Figure 2

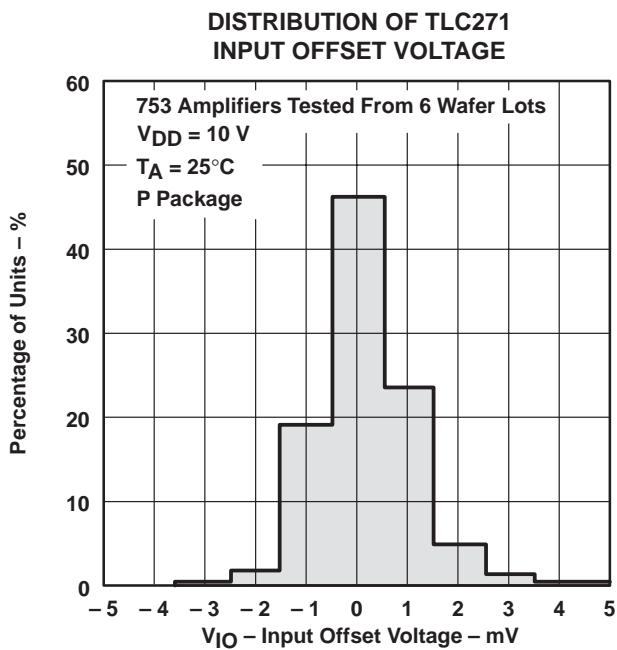


Figure 3

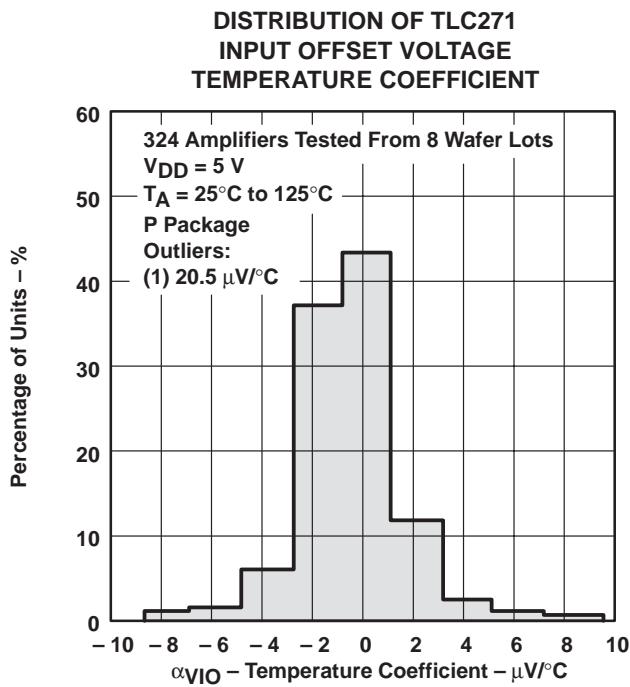


Figure 4

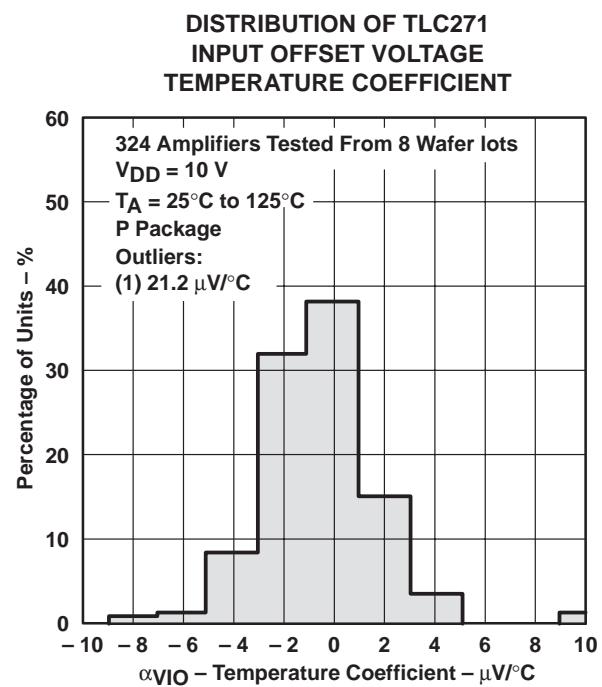


Figure 5

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (HIGH-BIAS MODE)†**

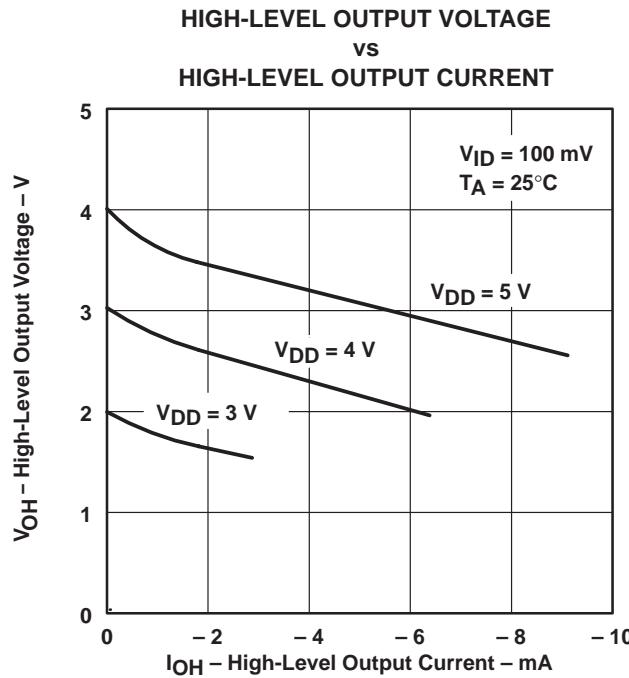


Figure 6

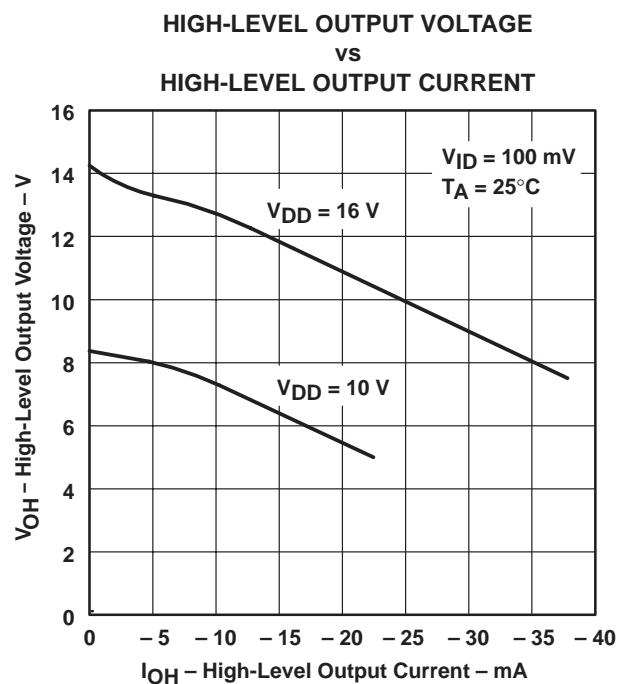


Figure 7

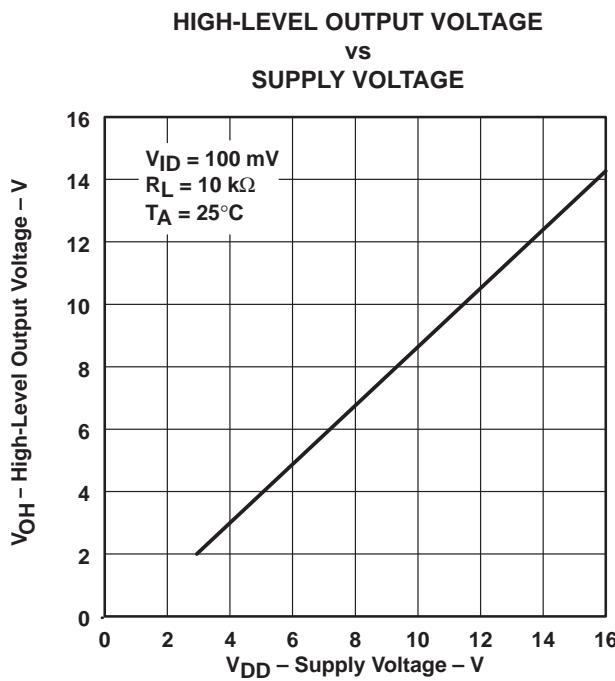


Figure 8

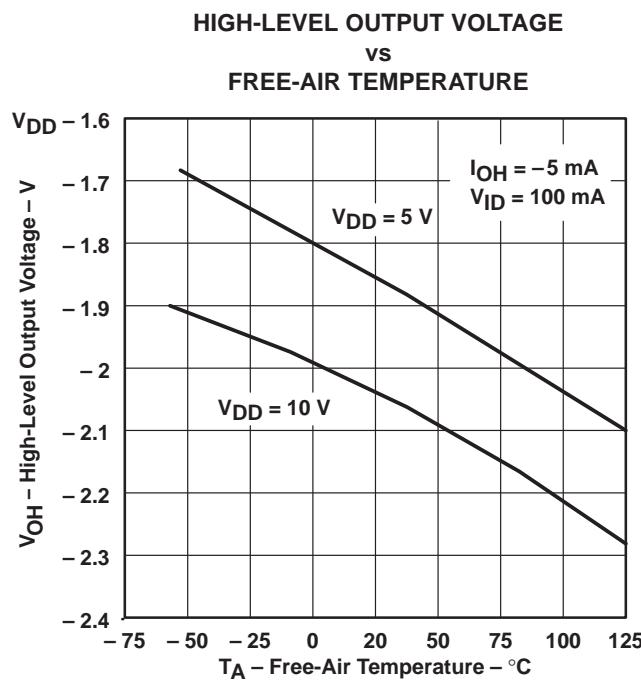


Figure 9

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

### TYPICAL CHARACTERISTICS (HIGH-BIAS MODE)†

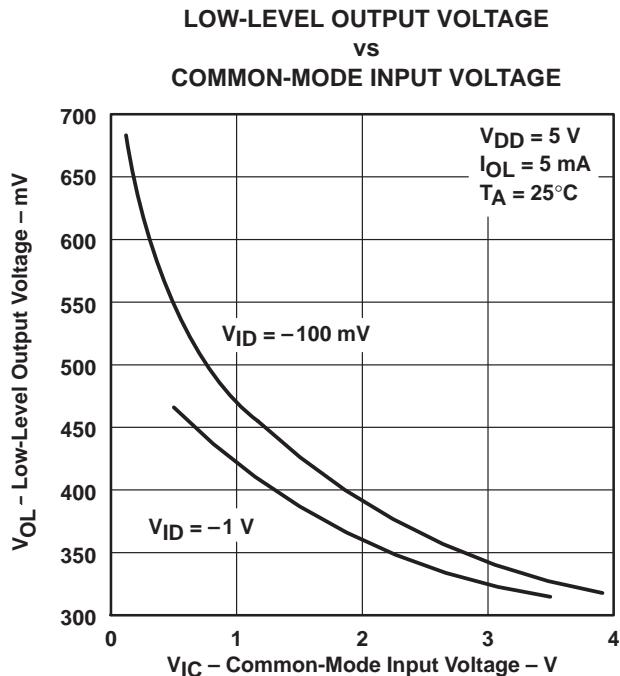


Figure 10

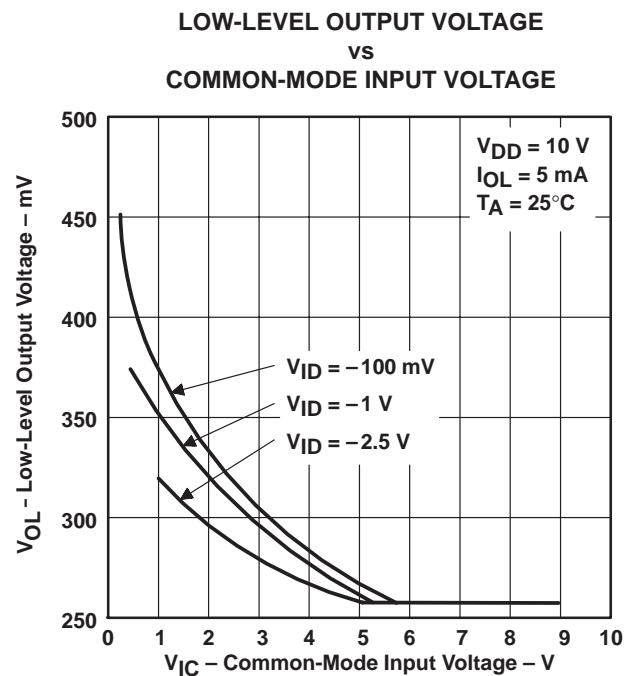


Figure 11

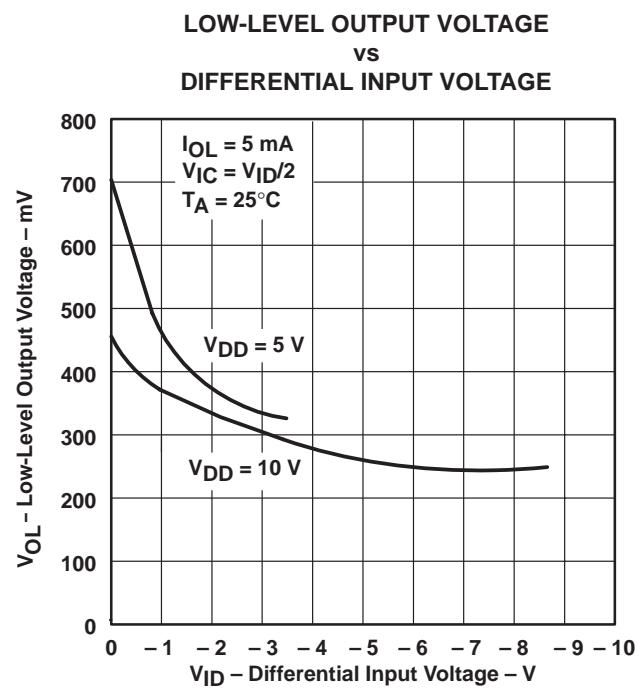


Figure 12

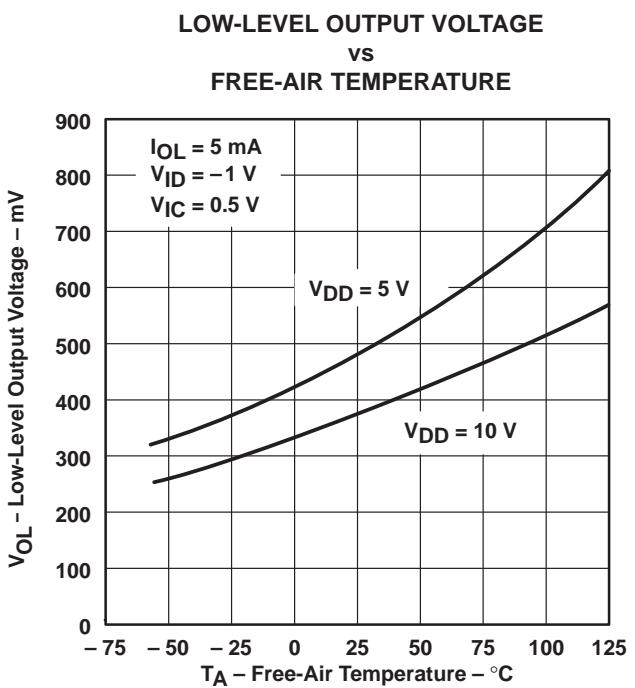


Figure 13

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (HIGH-BIAS MODE)†**

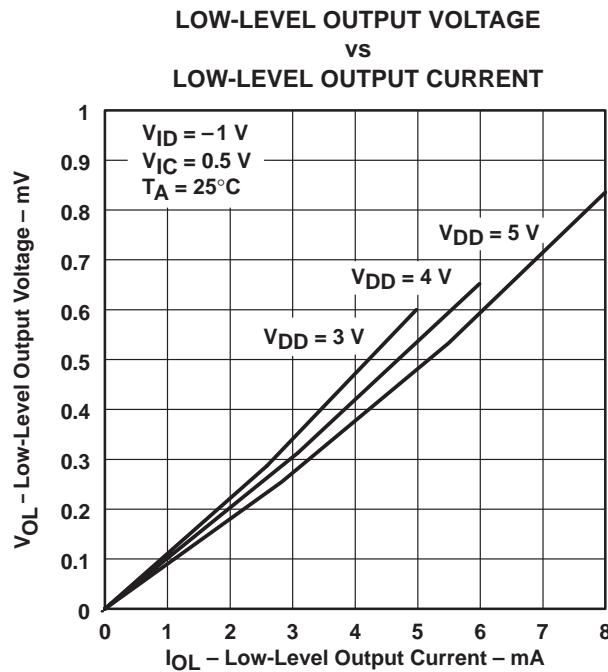


Figure 14

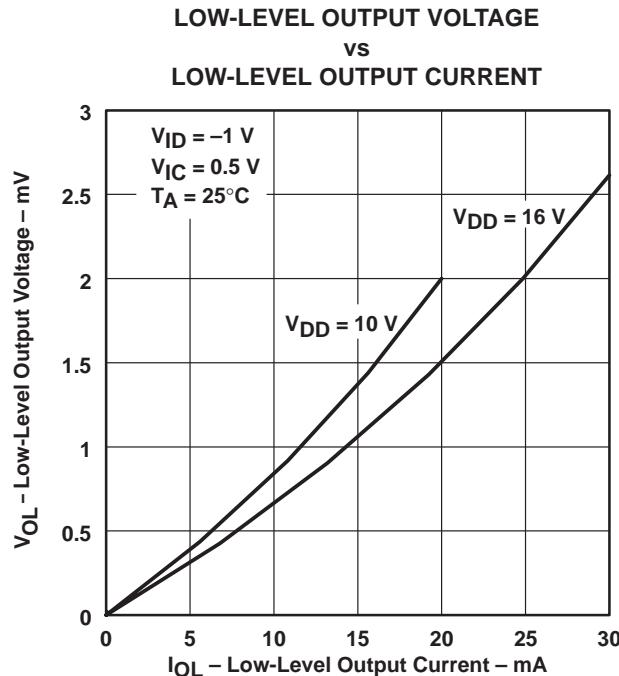


Figure 15

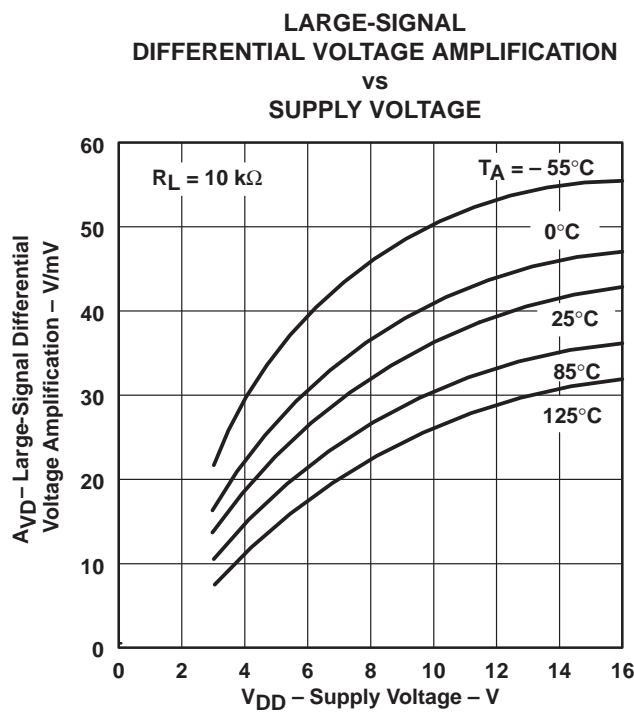


Figure 16

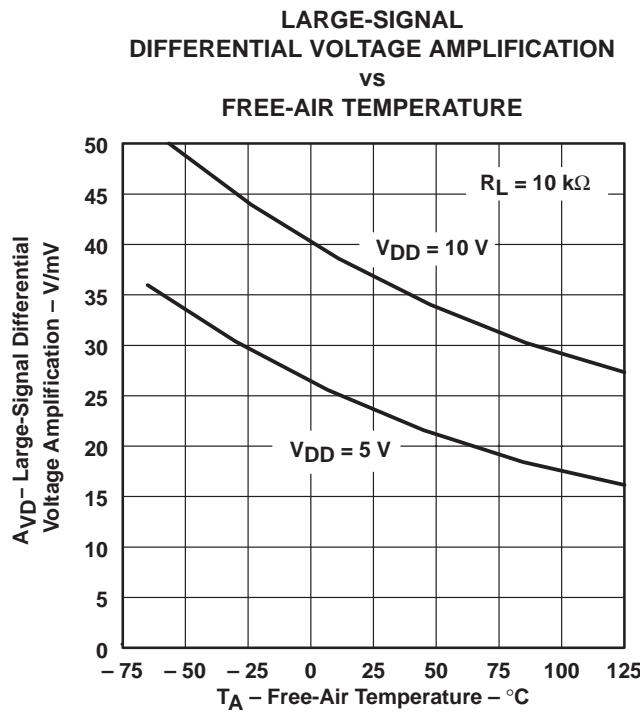
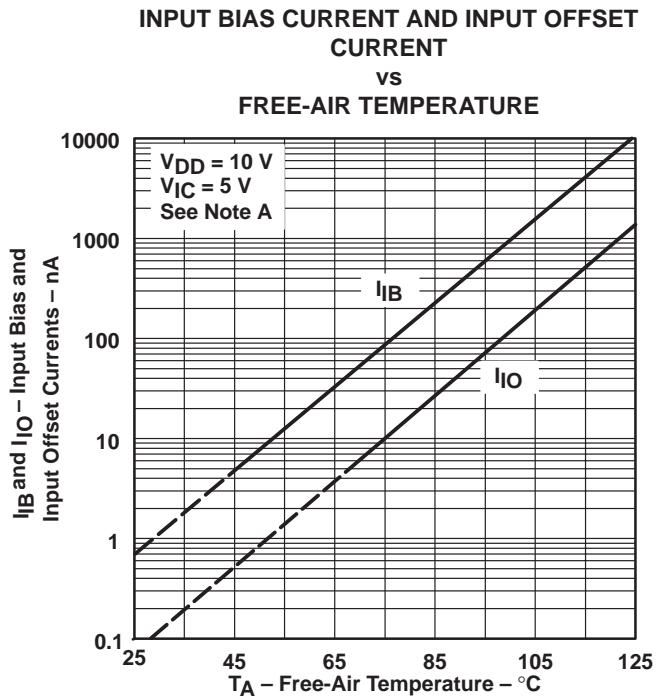


Figure 17

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

### TYPICAL CHARACTERISTICS (HIGH-BIAS MODE)†



NOTE A: The typical values of input bias current and input offset current below 5 pA were determined mathematically.

Figure 18

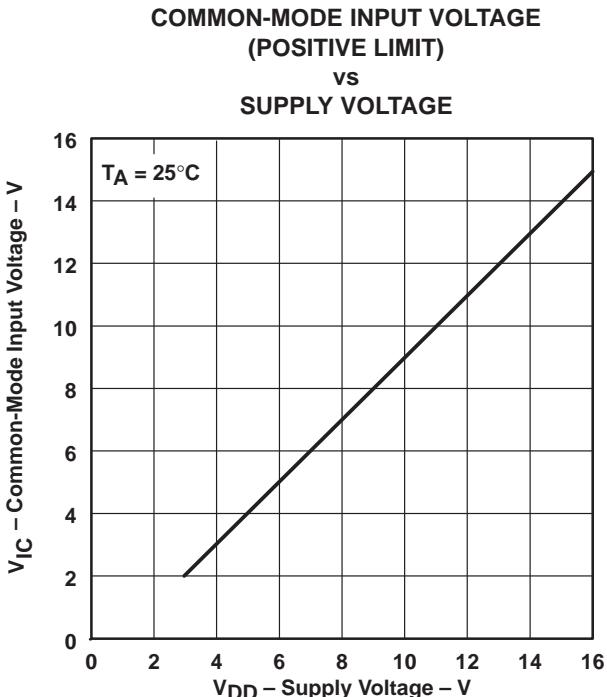


Figure 19

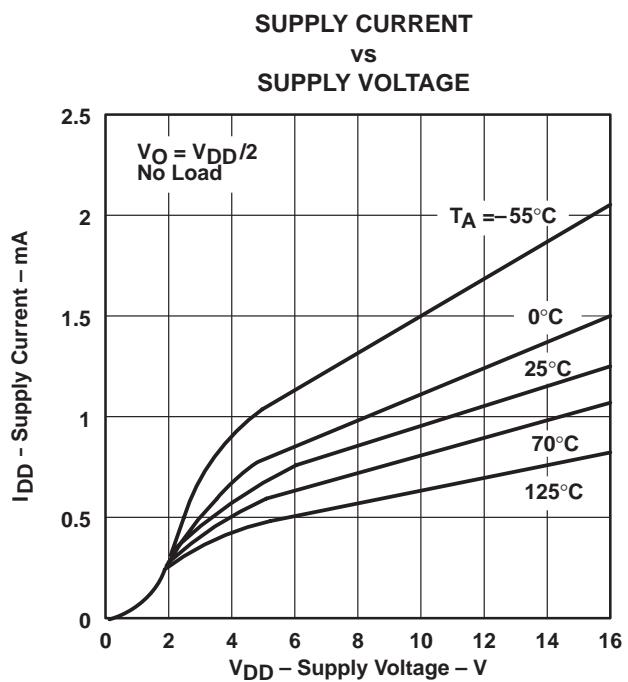


Figure 20

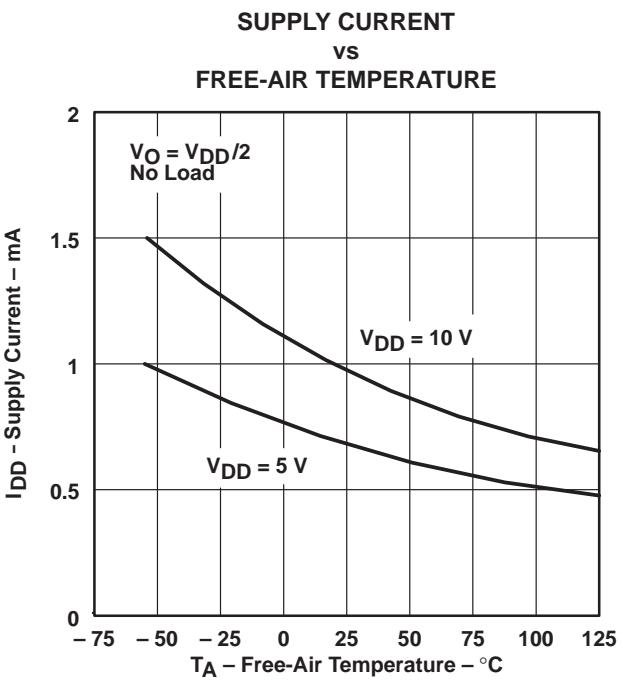


Figure 21

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (HIGH-BIAS MODE)†**

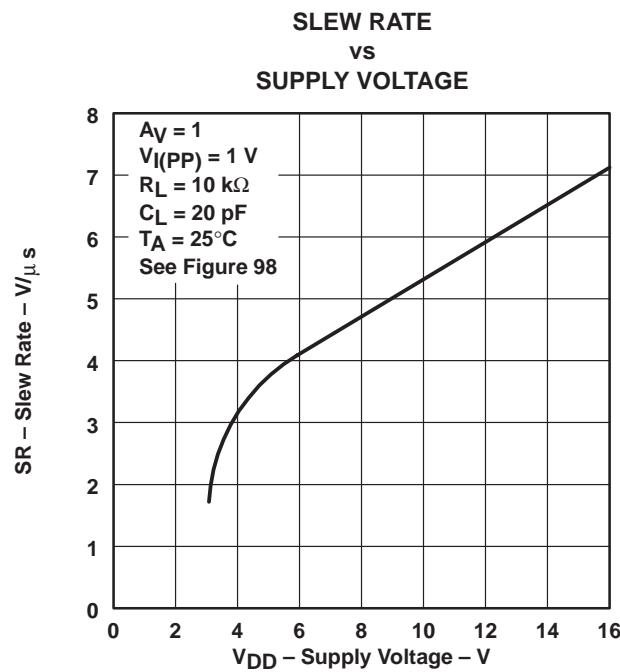


Figure 22

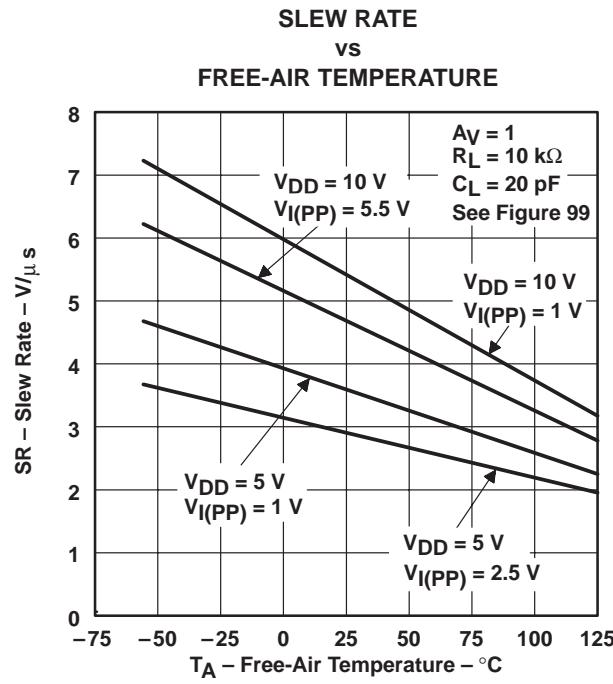


Figure 23

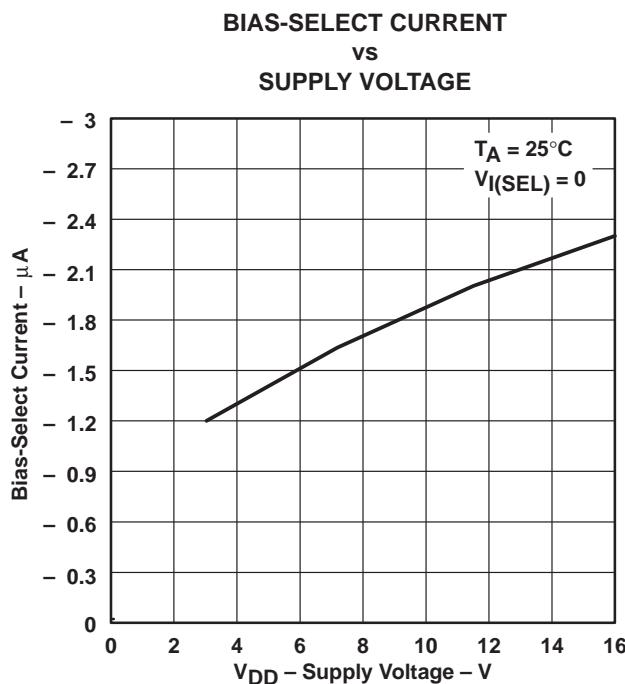


Figure 24

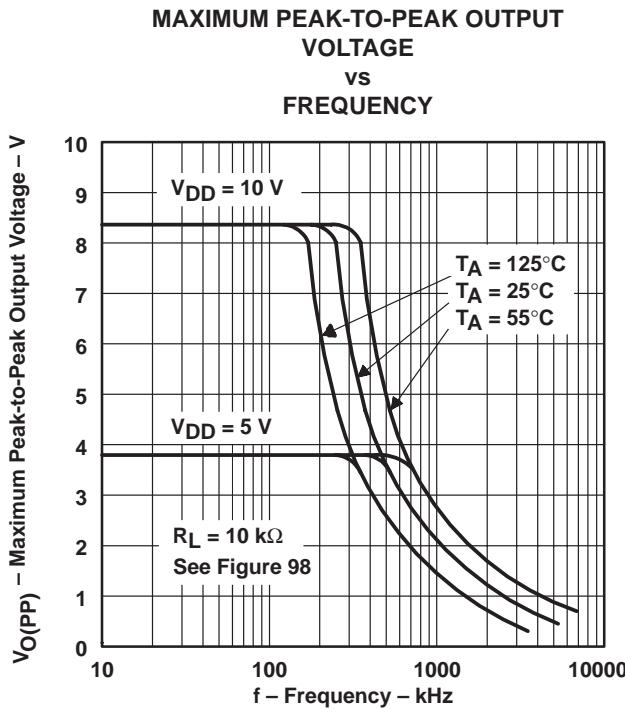


Figure 25

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

### TYPICAL CHARACTERISTICS (HIGH-BIAS MODE)†

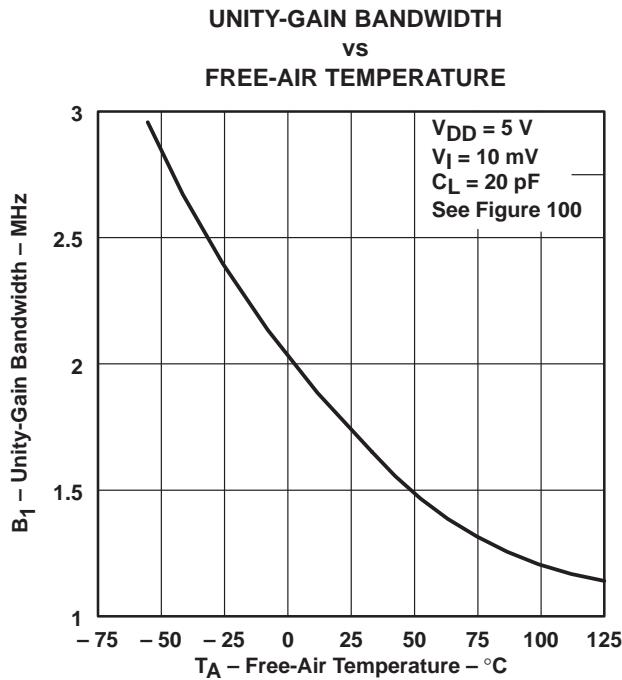


Figure 26

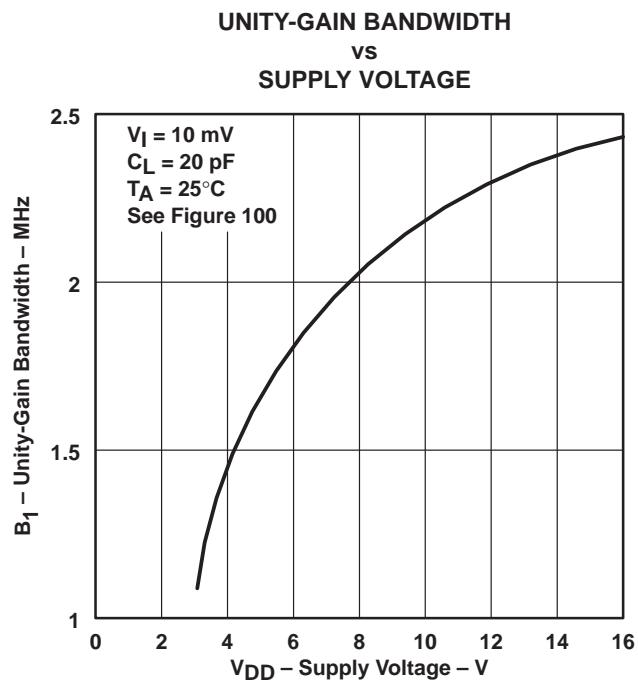


Figure 27

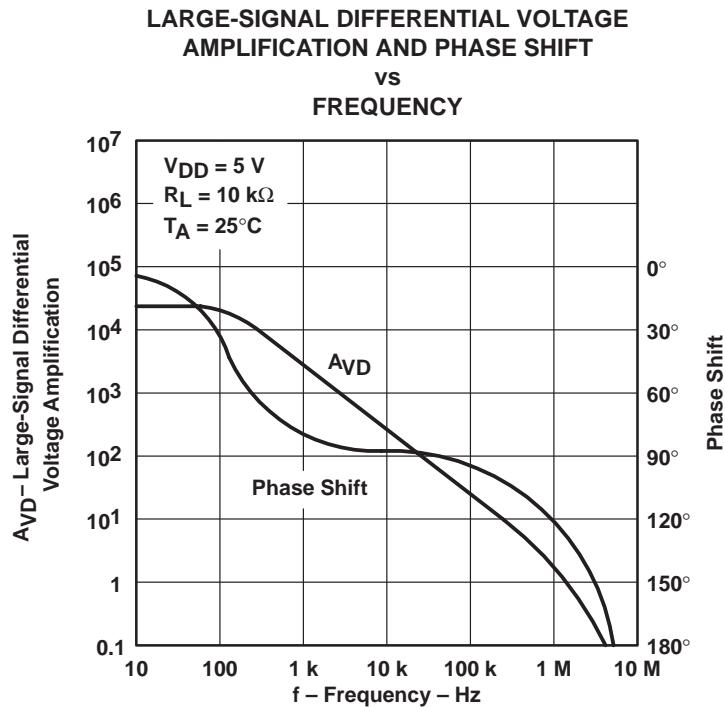


Figure 28

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (HIGH-BIAS MODE)†**

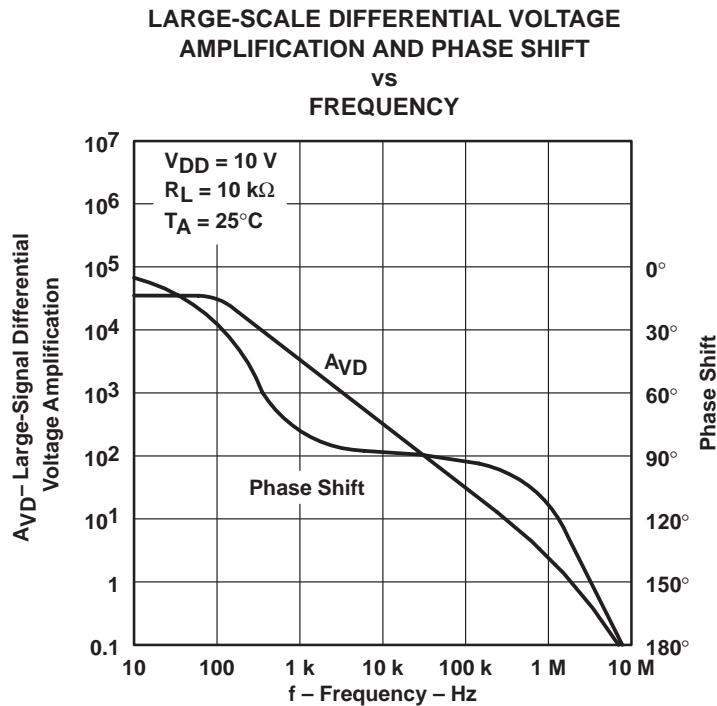


Figure 29

**PHASE MARGIN  
vs  
SUPPLY VOLTAGE**

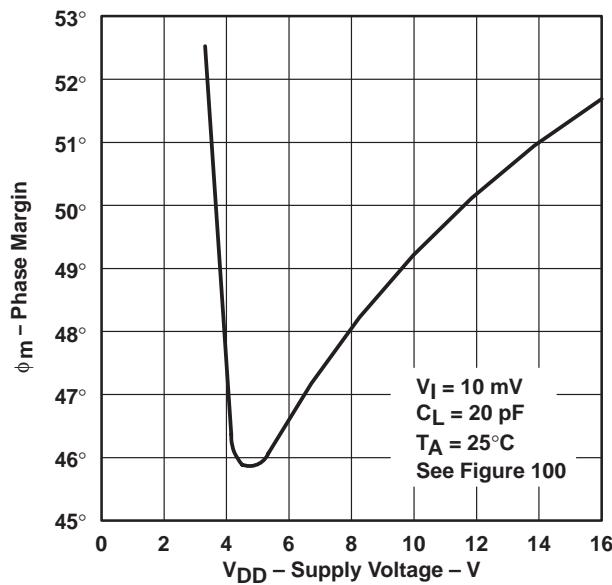


Figure 30

**PHASE MARGIN  
vs  
FREE-AIR TEMPERATURE**

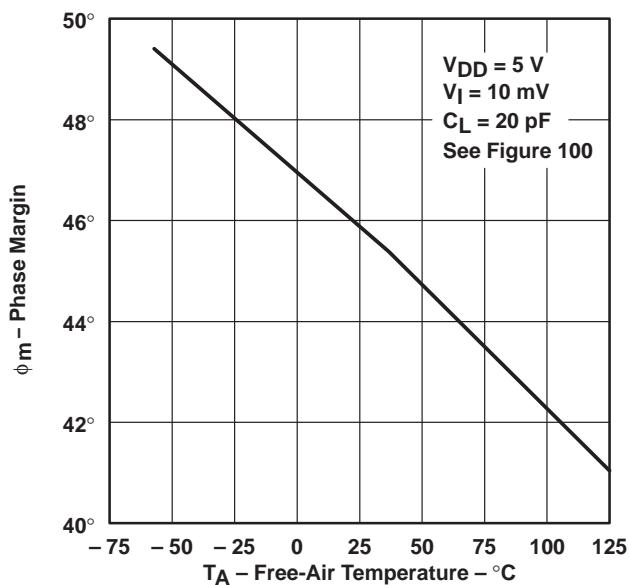
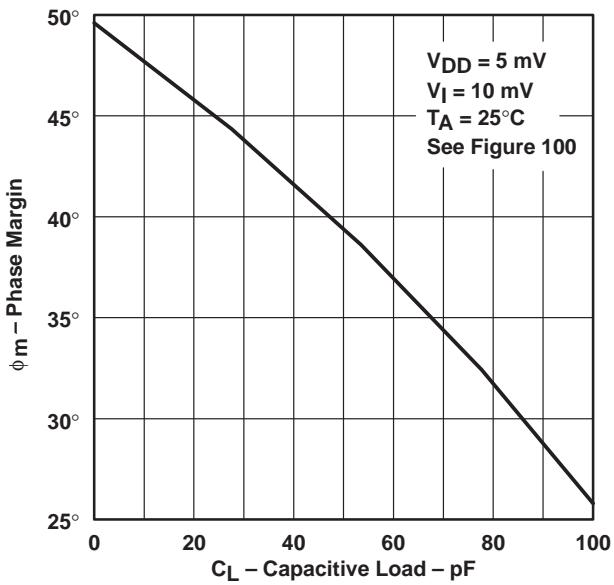


Figure 31

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

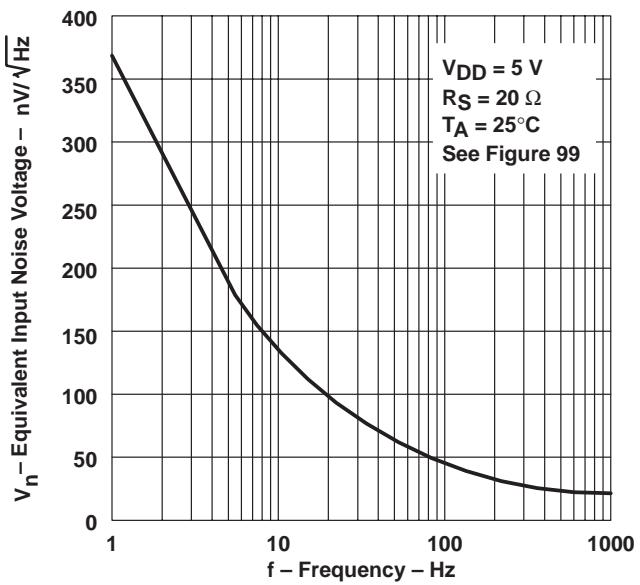
**TYPICAL CHARACTERISTICS (HIGH-BIAS MODE)†**

**PHASE MARGIN  
vs  
CAPACITIVE LOAD**



**Figure 32**

**EQUIVALENT NOISE VOLTAGE  
vs  
FREQUENCY**



**Figure 33**

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**MEDIUM-BIAS MODE**

**electrical characteristics at specified free-air temperature (unless otherwise noted)**

PARAMETER		TEST CONDITIONS	T <sub>A</sub> <sup>†</sup>	TLC271C, TLC271AC, TLC271BC						UNIT	
				V <sub>DD</sub> = 5 V			V <sub>DD</sub> = 10 V				
				MIN	TYP	MAX	MIN	TYP	MAX		
V <sub>IO</sub>	Input offset voltage	V <sub>O</sub> = 1.4 V, V <sub>IC</sub> = 0 R <sub>S</sub> = 50 Ω, R <sub>I</sub> = 100 kΩ	25°C	1.1	10		1.1	10		mV	
			Full range		12			12			
			25°C	0.9	5		0.9	5			
			Full range		6.5			6.5			
			25°C	0.25	2		0.26	2			
			Full range		3			3			
αV <sub>IO</sub>	Average temperature coefficient of input offset voltage		25°C to 70°C	1.7			2.1			µV/°C	
I <sub>IO</sub>	Input offset current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.1			0.1			pA	
			70°C	7	300		7	300			
I <sub>IB</sub>	Input bias current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.6			0.7			pA	
			70°C	40	600		50	600			
V <sub>ICR</sub>	Common-mode input voltage range (see Note 5)		25°C	-0.2 to 4	-0.3 to 4.2		-0.2 to 9	-0.3 to 9.2		V	
			Full range	-0.2 to 3.5			-0.2 to 8.5			V	
			25°C	3.2	3.9		8	8.7		V	
			0°C	3	3.9		7.8	8.7			
V <sub>OL</sub>	Low-level output voltage	V <sub>ID</sub> = -100 mV, R <sub>L</sub> = 100 kΩ	70°C	3	4		7.8	8.7			
			25°C	0	50		0	50		mV	
			0°C	0	50		0	50			
AVD	Large-signal differential voltage amplification	R <sub>L</sub> = 100 kΩ, See Note 6	70°C	0	50		0	50		V/mV	
			25°C	25	170		25	275			
			0°C	15	200		15	320			
CMRR	Common-mode rejection ratio	V <sub>IC</sub> = V <sub>ICRmin</sub>	70°C	15	140		15	230		dB	
			25°C	65	91		65	94			
			0°C	60	91		60	94			
k <sub>SVR</sub>	Supply-voltage rejection ratio (ΔV <sub>DD</sub> /ΔV <sub>IO</sub> )	V <sub>DD</sub> = 5 V to 10 V V <sub>O</sub> = 1.4 V	70°C	60	92		60	94		dB	
			25°C	70	93		70	93			
			0°C	60	92		60	92			
I <sub>I(SEL)</sub>	Input current (BIAS SELECT)	V <sub>I(SEL)</sub> = V <sub>DD</sub> /2	70°C	60	94		60	94		nA	
			25°C	-130			-160				
I <sub>DD</sub>	Supply current	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2, No load	25°C	105	280		143	300		µA	
			0°C	125	320		173	400			
			70°C	85	220		110	280			

<sup>†</sup> Full range is 0°C to 70°C.

- NOTES: 4. The typical values of input bias current and input offset current below 5 pA were determined mathematically.  
 5. This range also applies to each input individually.  
 6. At V<sub>DD</sub> = 5 V, V<sub>O</sub> = 0.25 V to 2 V; at V<sub>DD</sub> = 10 V, V<sub>O</sub> = 1 V to 6 V.



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**MEDIUM-BIAS MODE**

**electrical characteristics at specified free-air temperature (unless otherwise noted)**

PARAMETER		TEST CONDITIONS	TA <sup>†</sup>	TLC271I, TLC271AI, TLC271BI						UNIT	
				V <sub>DD</sub> = 5 V			V <sub>DD</sub> = 10 V				
				MIN	TYP	MAX	MIN	TYP	MAX		
V <sub>IO</sub>	Input offset voltage	V <sub>O</sub> = 1.4 V, V <sub>IC</sub> = 0 V, R <sub>S</sub> = 50 Ω, R <sub>L</sub> = 100 kΩ	25°C	1.1	10		1.1	10		mV	
			Full range		13			13			
			25°C	0.9	5		0.9	5			
			Full range		7			7			
			25°C	0.25	2		0.26	2			
			Full range		3.5			3.5			
αV <sub>IO</sub>	Average temperature coefficient of input offset voltage		25°C to 85°C	1.7			2.1			μV/°C	
I <sub>IO</sub>	Input offset current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.1			0.1			pA	
			85°C	24	1000		26	1000			
I <sub>IB</sub>	Input bias current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.6			0.7			pA	
			85°C	200	2000		220	2000			
V <sub>ICR</sub>	Common-mode input voltage range (see Note 5)		25°C	-0.2 to 4	-0.3 to 4.2		-0.2 to 9	-0.3 to 9.2		V	
			Full range	-0.2 to 3.5	-0.2 to 8.5		-0.2 to 8.5	-0.2 to 8.5		V	
V <sub>OH</sub>	High-level output voltage	V <sub>ID</sub> = 100 mV, R <sub>L</sub> = 100 kΩ	25°C	3.2	3.9		8	8.7		V	
			-40°C	3	3.9		7.8	8.7			
			85°C	3	4		7.8	8.7			
V <sub>OL</sub>	Low-level output voltage	V <sub>ID</sub> = -100 mV, I <sub>OL</sub> = 0	25°C	0	50		0	50		mV	
			-40°C	0	50		0	50			
			85°C	0	50		0	50			
AVD	Large-signal differential voltage amplification	R <sub>L</sub> = 100 kΩ, See Note 6	25°C	25	170		25	275		V/mV	
			-40°C	15	270		15	390			
			85°C	15	130		15	220			
CMRR	Common-mode rejection ratio	V <sub>IC</sub> = V <sub>ICRmin</sub>	25°C	65	91		65	94		dB	
			-40°C	60	90		60	93			
			85°C	60	90		60	94			
k <sub>SVR</sub>	Supply-voltage rejection ratio ( $\Delta V_{DD}/\Delta V_{IO}$ )	V <sub>DD</sub> = 5 V to 10 V V <sub>O</sub> = 1.4 V	25°C	70	93		70	93		dB	
			-40°C	60	91		60	91			
			85°C	60	94		60	94			
I <sub>I(SEL)</sub>	Input current (BIAS SELECT)	V <sub>I(SEL)</sub> = V <sub>DD</sub> /2	25°C	-130			-160			nA	
I <sub>DD</sub>	Supply current	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2, No load	25°C	105	280		143	300		μA	
			-40°C	158	400		225	450			
			85°C	80	200		103	260			

<sup>†</sup> Full range is -40°C to 85°C.

- NOTES: 4. The typical values of input bias current and input offset current below 5 pA were determined mathematically.  
5. This range also applies to each input individually.  
6. At V<sub>DD</sub> = 5 V, V<sub>O</sub> = 0.25 V to 2 V; at V<sub>DD</sub> = 10 V, V<sub>O</sub> = 1 V to 6 V.

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**MEDIUM-BIAS MODE**

**electrical characteristics at specified free-air temperature (unless otherwise noted)**

PARAMETER	TEST CONDITIONS	TA <sup>†</sup>	TLC271M						UNIT	
			V <sub>DD</sub> = 5 V			V <sub>DD</sub> = 10 V				
			MIN	TYP	MAX	MIN	TYP	MAX		
V <sub>IO</sub> Input offset voltage	V <sub>O</sub> = 1.4 V, V <sub>IC</sub> = 0 V, R <sub>S</sub> = 50 Ω, R <sub>L</sub> = 100 kΩ	25°C	1.1	10		1.1	10		mV	
		Full range			12			12		
α <sub>VIO</sub> Average temperature coefficient of input offset voltage		25°C to 125°C		1.7			2.1		μV/°C	
I <sub>IO</sub> Input offset current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.1			0.1			pA	
		125°C	1.4	15		1.8	15		nA	
I <sub>IB</sub> Input bias current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.6			0.7			pA	
		125°C	9	35		10	35		nA	
V <sub>ICR</sub> Common-mode input voltage range (see Note 5)		25°C	0 to 4	-0.3 to 4.2		0 to 9	-0.3 to 9.2		V	
		Full range	0 to 3.5			0 to 8.5			V	
V <sub>OH</sub> High-level output voltage	V <sub>ID</sub> = 100 mV, R <sub>L</sub> = 100 kΩ	25°C	3.2	3.9		8	8.7		V	
		-55°C	3	3.9		7.8	8.6			
		125°C	3	4		7.8	8.6			
V <sub>OL</sub> Low-level output voltage	V <sub>ID</sub> = -100 mV, I <sub>OL</sub> = 0	25°C	0	50		0	50		mV	
		-55°C	0	50		0	50			
		125°C	0	50		0	50			
AVD Large-signal differential voltage amplification	R <sub>L</sub> = 10 kΩ See Note 6	25°C	25	170		25	275		V/mV	
		-55°C	15	290		15	420			
		125°C	15	120		15	190			
CMRR Common-mode rejection ratio	V <sub>IC</sub> = V <sub>ICRmin</sub>	25°C	65	91		65	94		dB	
		-55°C	60	89		60	93			
		125°C	60	91		60	93			
k <sub>SVR</sub> Supply-voltage rejection ratio (ΔV <sub>DD</sub> /ΔV <sub>IO</sub> )	V <sub>DD</sub> = 5 V to 10 V V <sub>O</sub> = 1.4 V	25°C	70	93		70	93		dB	
		-55°C	60	91		60	91			
		125°C	60	94		60	94			
I <sub>I(SEL)</sub> Input current (BIAS SELECT)	V <sub>I(SEL)</sub> = V <sub>DD</sub> /2	25°C	-130			-160			nA	
I <sub>DD</sub> Supply current	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2, No load	25°C	105	280		143	300		μA	
		-55°C	170	440		245	500			
		125°C	70	180		90	240			

<sup>†</sup> Full range is -55°C to 125°C.

- NOTES: 4. The typical values of input bias current and input offset current below 5 pA were determined mathematically.  
 5. This range also applies to each input individually.  
 6. At V<sub>DD</sub> = 5 V, V<sub>O</sub> = 0.25 V to 2 V; at V<sub>DD</sub> = 10 V, V<sub>O</sub> = 1 V to 6 V.



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### MEDIUM-BIAS MODE

**operating characteristics at specified free-air temperature,  $V_{DD} = 5\text{ V}$**

PARAMETER	TEST CONDITIONS	$T_A$	TLC271C, TLC271AC, TLC271BC			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 100\text{ k}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	25°C	0.43			V/ $\mu\text{s}$
		0°C	0.46			
		70°C	0.36			
		25°C	0.40			
		0°C	0.43			
		70°C	0.34			
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	32		nV/ $\sqrt{\text{Hz}}$
$B_{OM}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 100\text{ k}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	55		kHz
			0°C	60		
			70°C	50		
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	25°C	525		kHz
			0°C	600		
			70°C	400		
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ ,	$f = B_1$ , See Figure 100	25°C	40°		
			0°C	41°		
			70°C	39°		

**operating characteristics at specified free-air temperature,  $V_{DD} = 10\text{ V}$**

PARAMETER	TEST CONDITIONS	$T_A$	TLC271C, TLC271AC, TLC271BC			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 100\text{ k}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	25°C	0.62			V/ $\mu\text{s}$
		0°C	0.67			
		70°C	0.51			
		25°C	0.56			
		0°C	0.61			
		70°C	0.46			
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	32		nV/ $\sqrt{\text{Hz}}$
$B_{OM}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 100\text{ k}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	35		kHz
			0°C	40		
			70°C	30		
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	25°C	635		kHz
			0°C	710		
			70°C	510		
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ ,	$f = B_1$ , See Figure 100	25°C	43°		
			0°C	44°		
			70°C	42°		

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**MEDIUM-BIAS MODE****operating characteristics at specified free-air temperature,  $V_{DD} = 5\text{ V}$** 

PARAMETER	TEST CONDITIONS	TA	TLC271I, TLC271AI, TLC271BI			UNIT		
			MIN	TYP	MAX			
SR Slew rate at unity gain	RL = 100 kΩ, CL = 20 pF, See Figure 98	VI(PP) = 1 V	25°C	0.43		V/μs		
			-40°C	0.51				
			85°C	0.35				
		VI(PP) = 2.5 V	25°C	0.40				
			-40°C	0.48				
			85°C	0.32				
Vn Equivalent input noise voltage	f = 1 kHz, See Figure 99	RS = 20 Ω,	25°C	32		nV/√Hz		
BOM Maximum output-swing bandwidth	VO = VOH, RL = 100 kΩ, See Figure 98	CL = 20 pF,	25°C	55		kHz		
B1 Unity-gain bandwidth	VI = 10 mV, See Figure 100	CL = 20 pF,	-40°C	75				
			85°C	45				
			25°C	525		MHz		
φm Phase margin	VI = 10 mV, CL = 20 pF, See Figure 100	f = B1,	-40°C	770				
			85°C	370				
			25°C	40°				
φm Phase margin			-40°C	43°				
			85°C	38°				

**operating characteristics at specified free-air temperature,  $V_{DD} = 10\text{ V}$** 

PARAMETER	TEST CONDITIONS	TA	TLC271I, TLC271AI, TLC271BI			UNIT		
			MIN	TYP	MAX			
SR Slew rate at unity gain	RL = 100 kΩ, CL = 20 pF, See Figure 98	VI(PP) = 1 V	25°C	0.62		V/μs		
			-40°C	0.77				
			85°C	0.47				
		VI(PP) = 5.5 V	25°C	0.56				
			-40°C	0.70				
			85°C	0.44				
Vn Equivalent input noise voltage	f = 1 kHz, See Figure 99	RS = 20 Ω,	25°C	32		nV/√Hz		
BOM Maximum output-swing bandwidth	VO = VOH,3 RL = 100 kΩ, See Figure 98	CL = 20 pF,	25°C	35		kHz		
B1 Unity-gain bandwidth	VI = 10 mV, See Figure 100	CL = 20 pF,	-40°C	45				
			85°C	25				
			25°C	635		kHz		
B1 Unity-gain bandwidth			-40°C	880				
			85°C	480				
			25°C	43°				
φm Phase margin	VI = 10 mV, CL = 20 pF, See Figure 100	f = B1,	-40°C	46°				
			85°C	41°				

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**MEDIUM-BIAS MODE**

**operating characteristics at specified free-air temperature,  $V_{DD} = 5\text{ V}$**

PARAMETER	TEST CONDITIONS	TA	TLC271M			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 100\text{ k}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	0.43		V/ $\mu\text{s}$
			-55°C	0.54		
		$V_I(\text{PP}) = 2.5\text{ V}$	125°C	0.29		
			25°C	0.40		
		$V_O = V_{OH}$ , $R_L = 100\text{ k}\Omega$ , See Figure 98	-55°C	0.50		
			125°C	0.28		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	32		nV/ $\sqrt{\text{Hz}}$
B <sub>OM</sub> Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 100\text{ k}\Omega$ , See Figure 98	$C_L = 20\text{ pF}$ ,	25°C	55		kHz
B <sub>1</sub> Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	-55°C	80		
			125°C	40		
			25°C	525		kHz
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ , See Figure 100	$f = B_1$ , See Figure 100	-55°C	850		
			125°C	330		
			25°C	40°		
			-55°C	43°		
			125°C	36°		

**operating characteristics at specified free-air temperature,  $V_{DD} = 10\text{ V}$**

PARAMETER	TEST CONDITIONS	TA	TLC271M			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 100\text{ k}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	0.62		V/ $\mu\text{s}$
			-55°C	0.81		
		$V_I(\text{PP}) = 5.5\text{ V}$	125°C	0.38		
			25°C	0.56		
		$V_O = V_{OH}$ , $R_L = 100\text{ k}\Omega$ , See Figure 98	-55°C	0.73		
			125°C	0.35		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	32		nV/ $\sqrt{\text{Hz}}$
B <sub>OM</sub> Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 100\text{ k}\Omega$ , See Figure 98	$C_L = 20\text{ pF}$ ,	25°C	35		kHz
B <sub>1</sub> Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	-55°C	50		
			125°C	20		
			25°C	635		kHz
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ , See Figure 100	$f = B_1$ , See Figure 100	-55°C	960		
			125°C	440		
			25°C	43°		
			-55°C	47°		
			125°C	39°		

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**TYPICAL CHARACTERISTICS (MEDIUM-BIAS MODE)**

**Table of Graphs**

			<b>FIGURE</b>
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$V_{OH}$	High-level output voltage	vs High-level output current vs Supply voltage vs Free-air temperature	38, 39 40 41
$V_{OL}$	Low-level output voltage	vs Common-mode input voltage vs Differential input voltage vs Free-air temperature vs Low-level output current	42, 43 44 45 46, 47
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$V_n$	Equivalent input noise voltage	vs Frequency	65
	Phase shift	vs Frequency	60, 61

### TYPICAL CHARACTERISTICS (MEDIUM-BIAS MODE)†

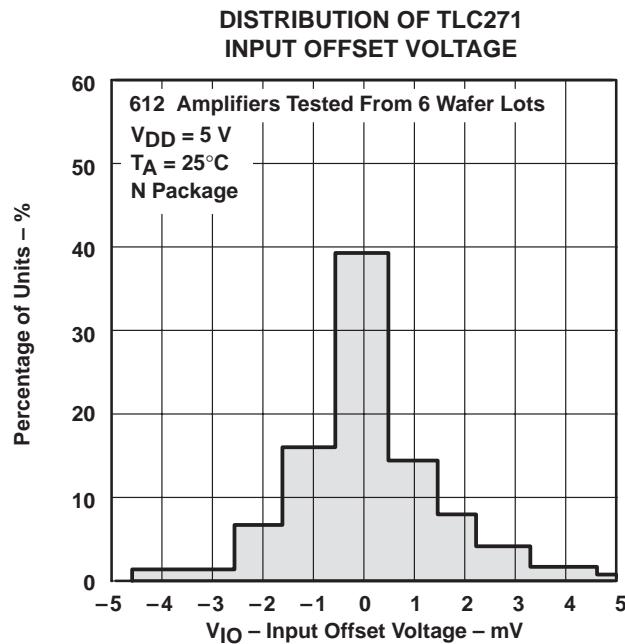


Figure 34

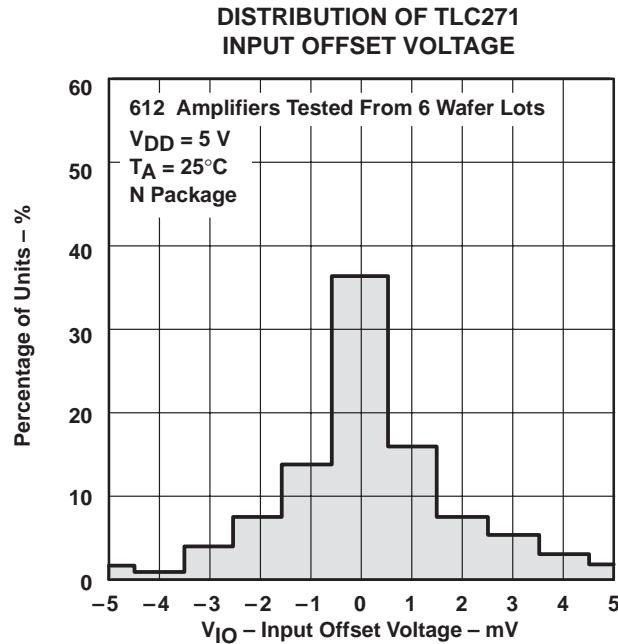


Figure 35

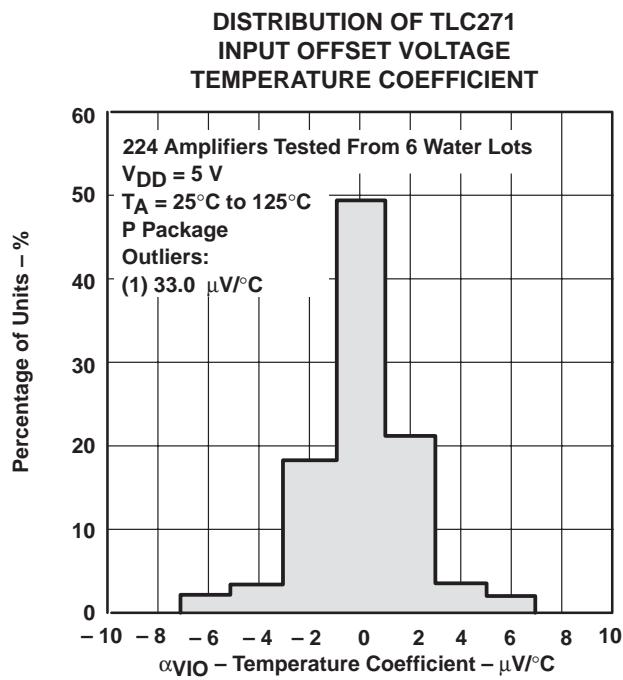


Figure 36

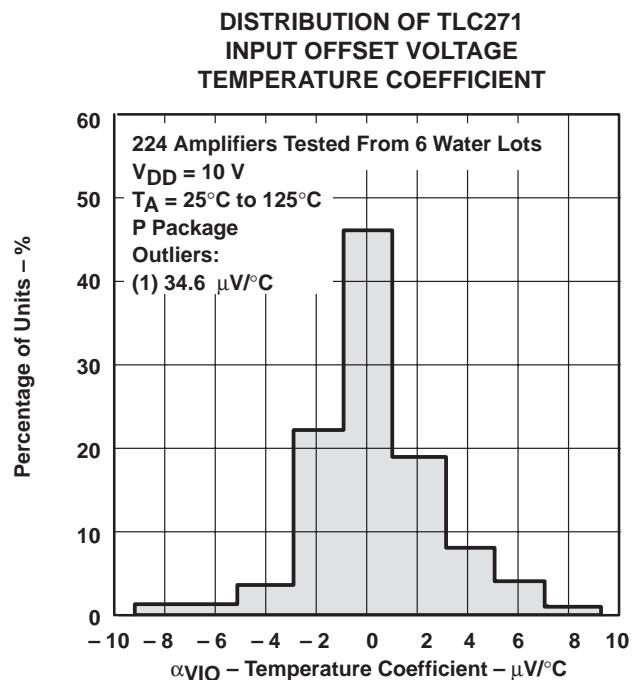


Figure 37

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (MEDIUM-BIAS MODE)†**

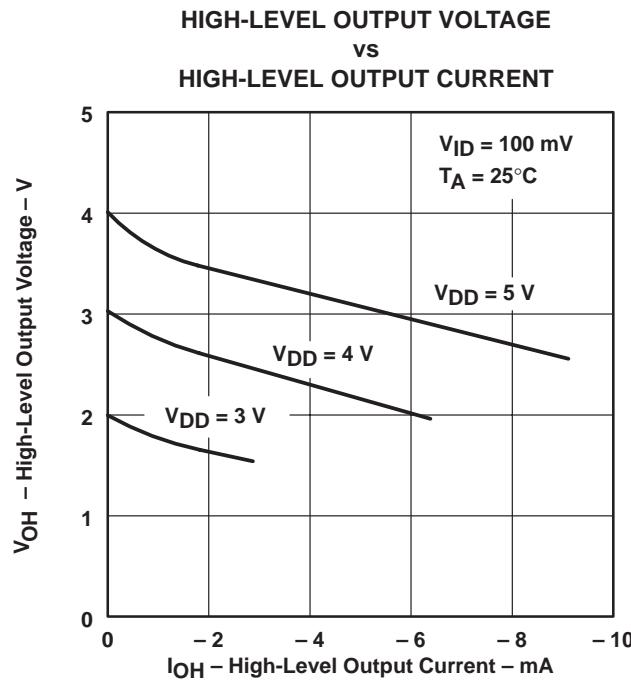


Figure 38

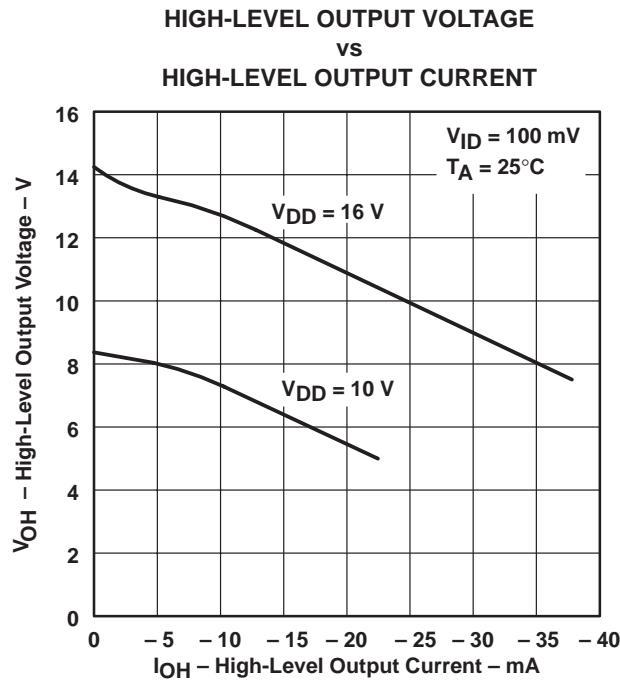


Figure 39

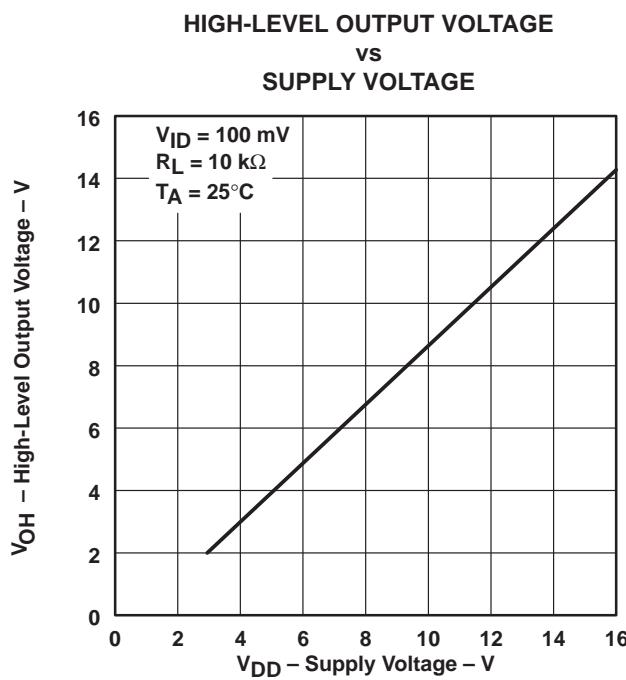


Figure 40

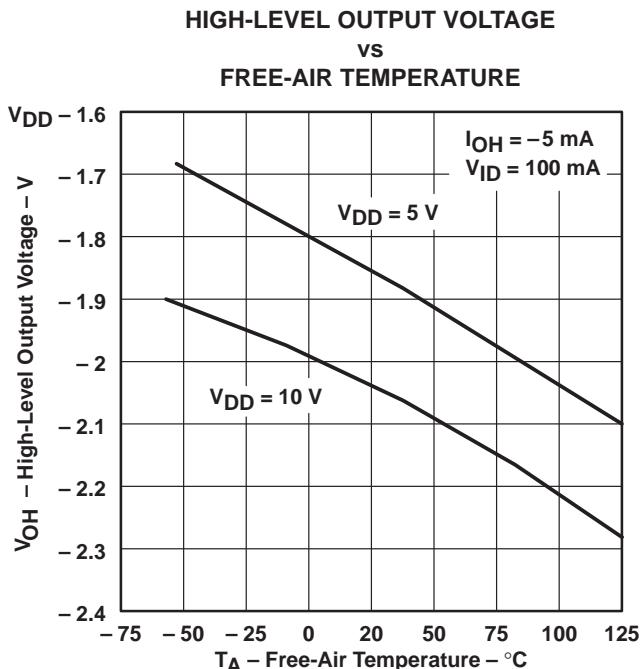


Figure 41

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

### TYPICAL CHARACTERISTICS (MEDIUM-BIAS MODE)†

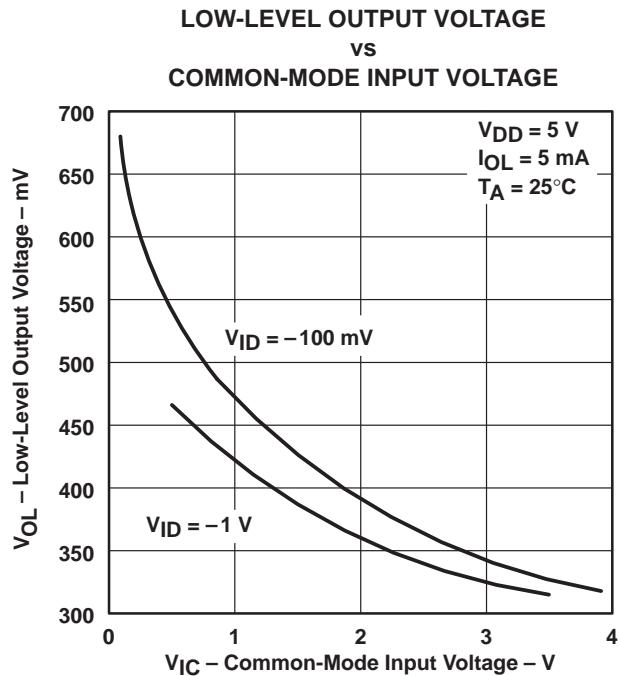


Figure 42

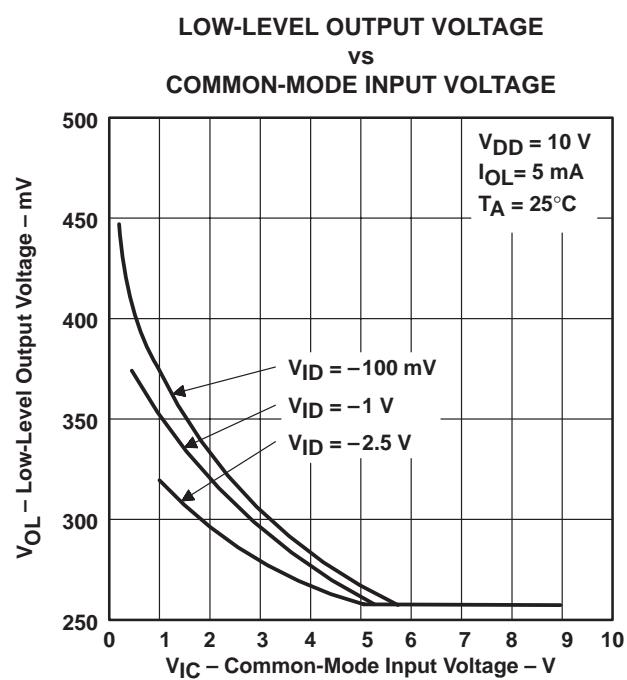


Figure 43

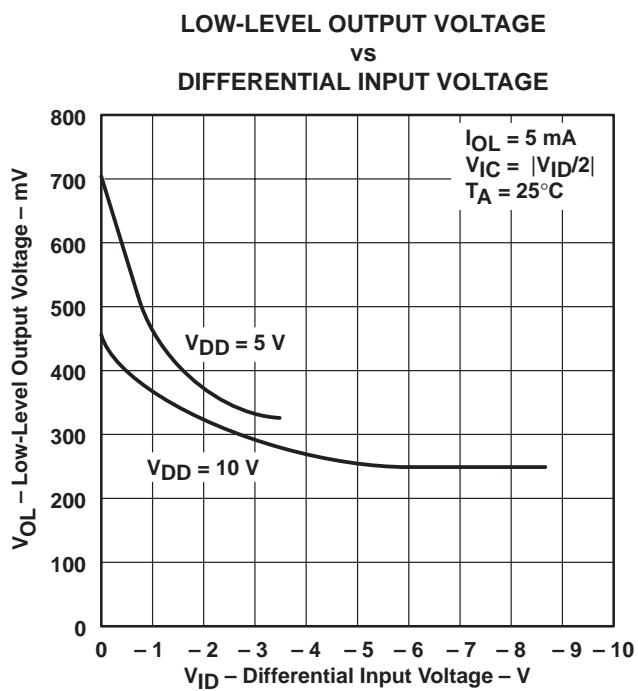


Figure 44

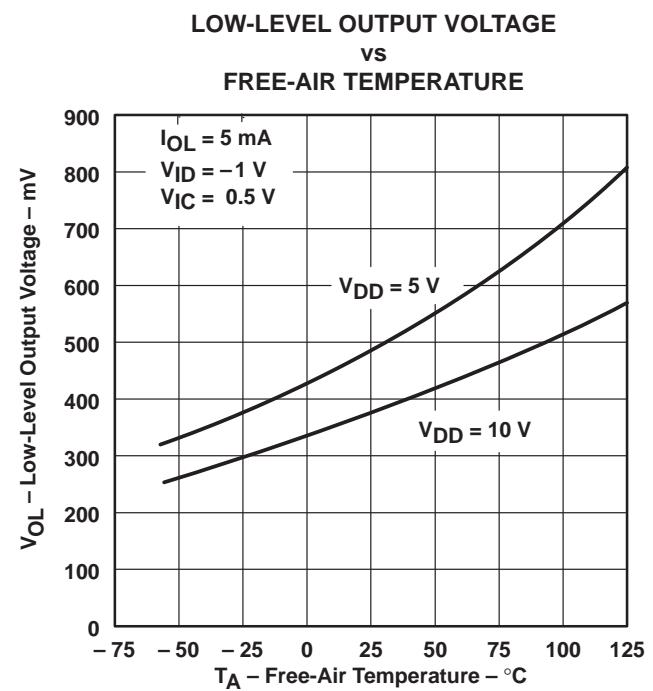


Figure 45

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (MEDIUM-BIAS MODE)†**

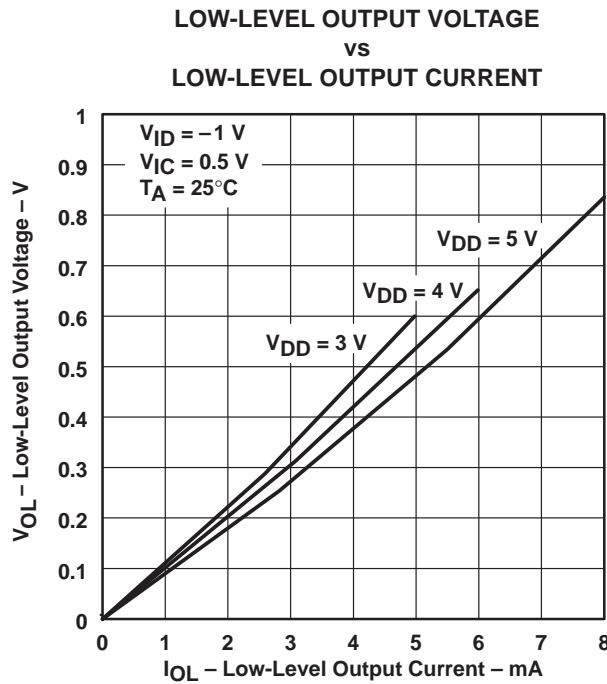


Figure 46

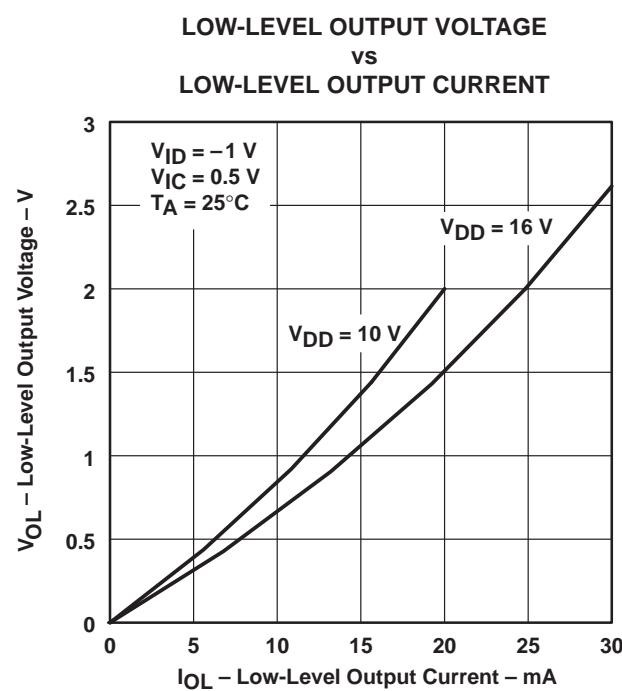


Figure 47

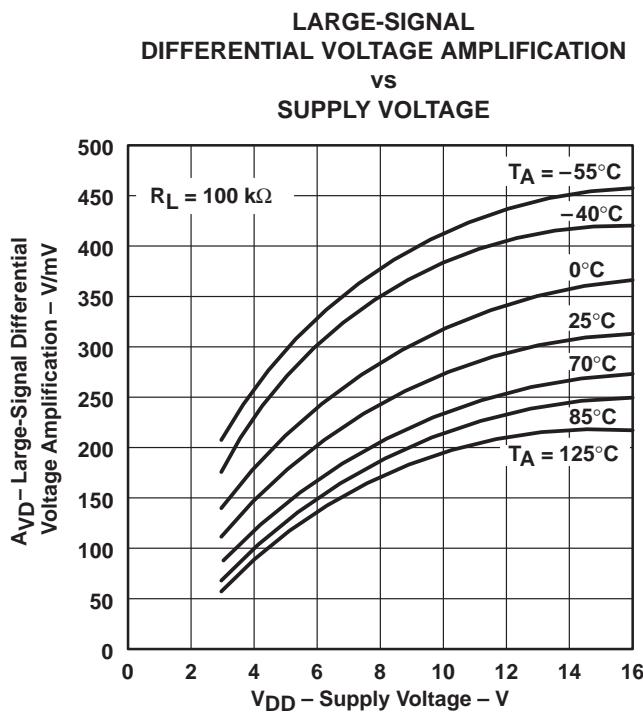


Figure 48

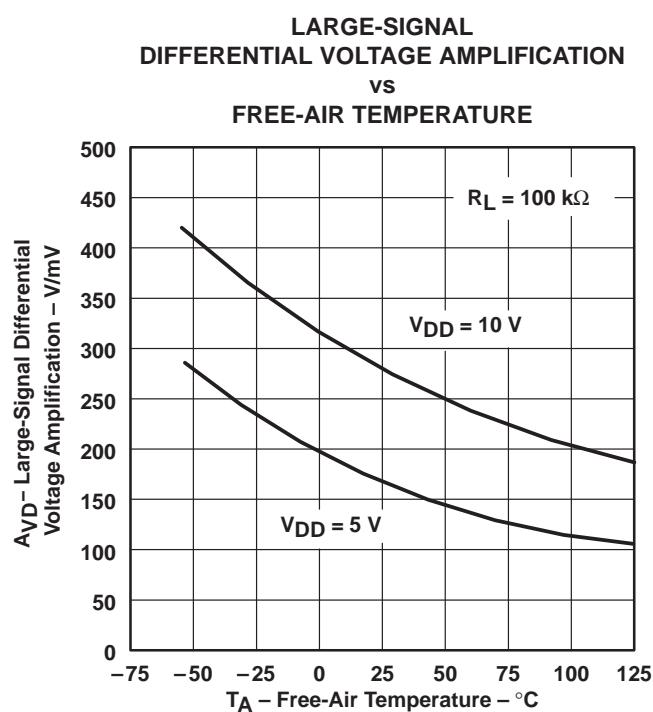
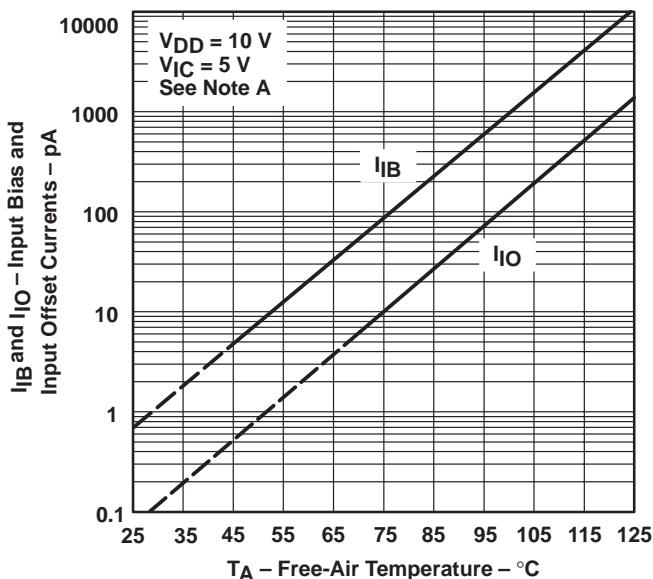


Figure 49

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

### TYPICAL CHARACTERISTICS (MEDIUM-BIAS MODE)†

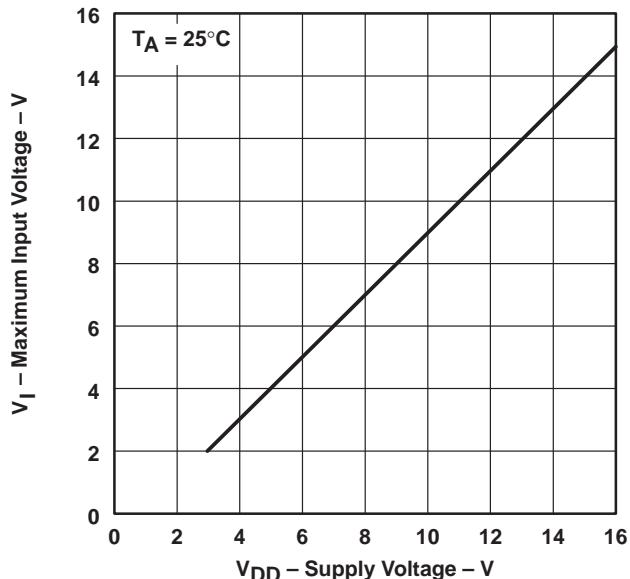
**INPUT BIAS CURRENT AND INPUT OFFSET  
 CURRENT  
 VS  
 FREE-AIR TEMPERATURE**



NOTE A: The typical values of input bias current and input offset current below 5 pA were determined mathematically.

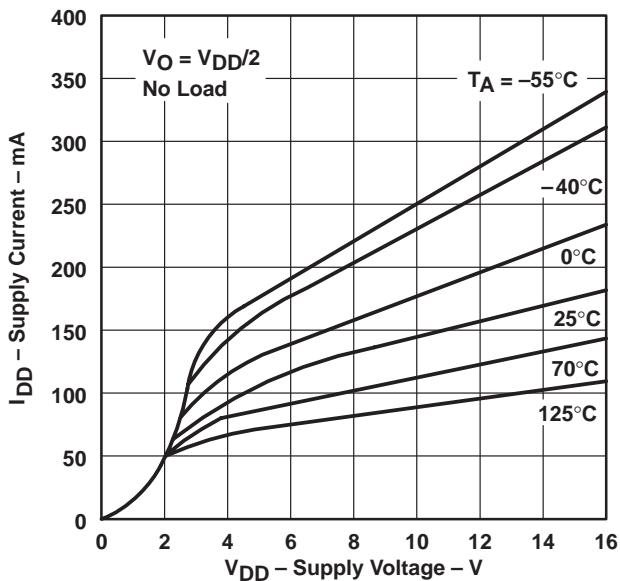
**Figure 50**

**MAXIMUM INPUT VOLTAGE  
 VS  
 SUPPLY VOLTAGE**



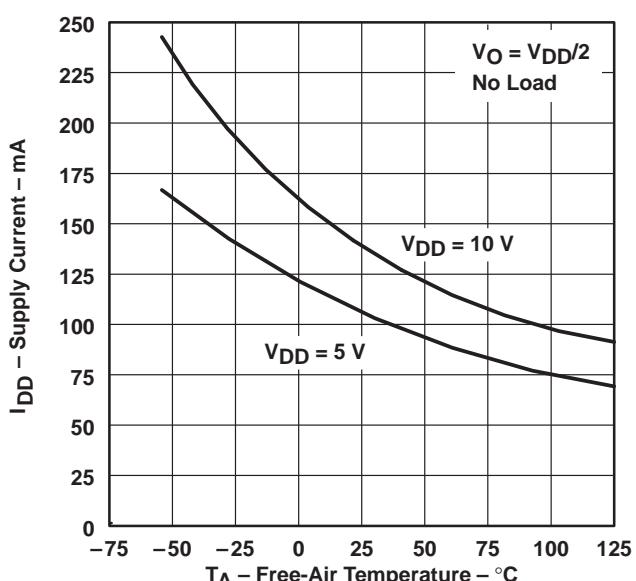
**Figure 51**

**SUPPLY CURRENT  
 VS  
 SUPPLY VOLTAGE**



**Figure 52**

**SUPPLY CURRENT  
 VS  
 FREE-AIR TEMPERATURE**



**Figure 53**

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (MEDIUM-BIAS MODE)†**

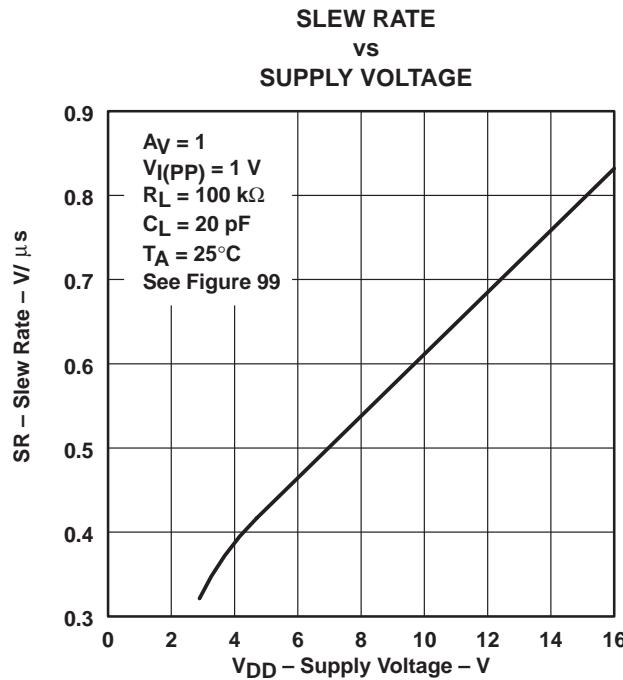


Figure 54

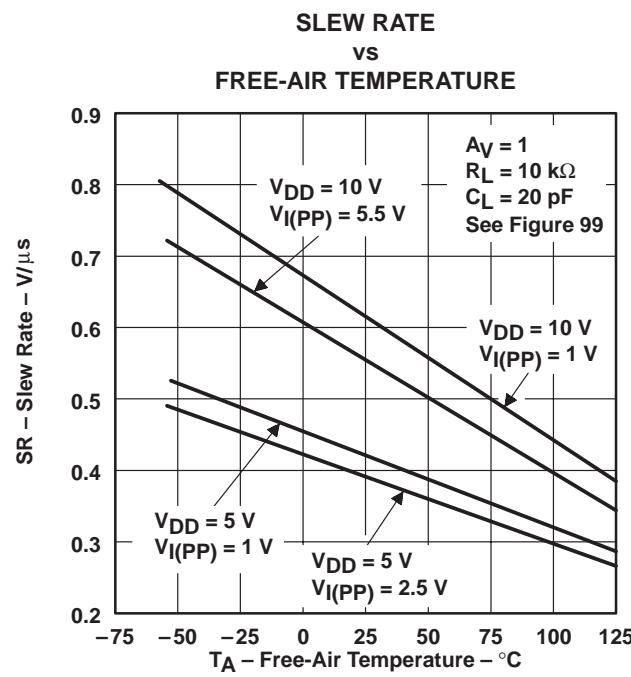


Figure 55

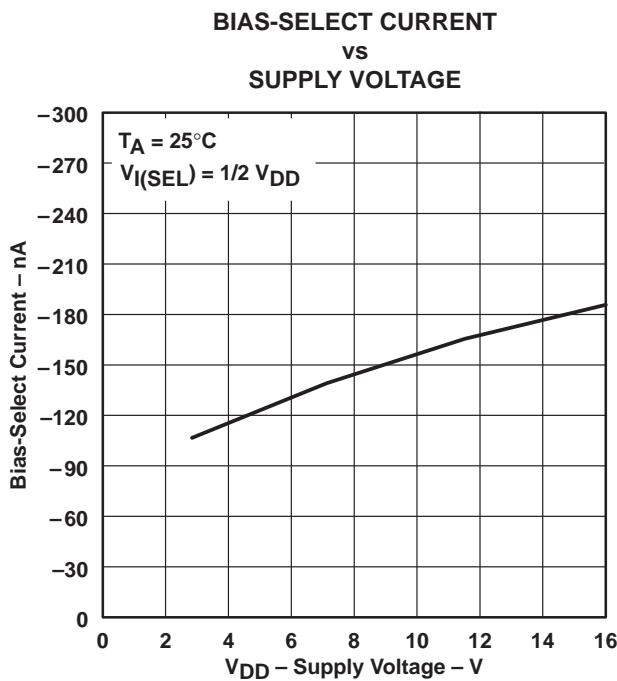


Figure 56

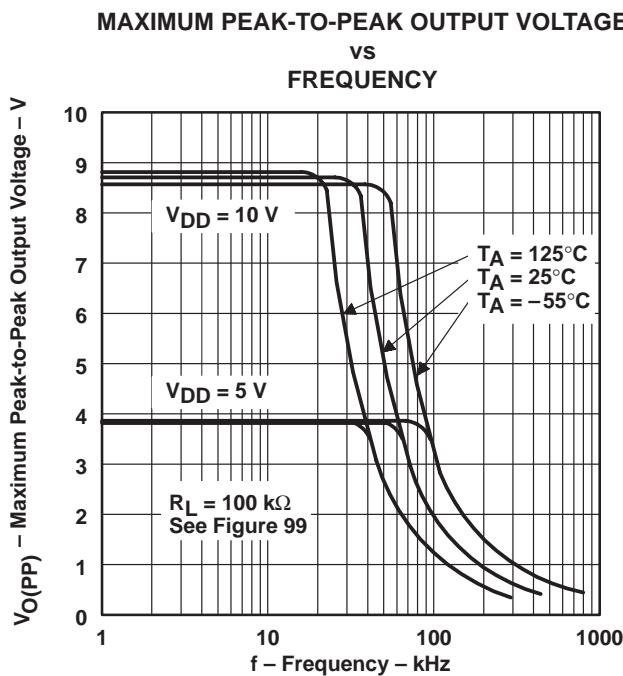


Figure 57

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

### TYPICAL CHARACTERISTICS (MEDIUM-BIAS MODE)†

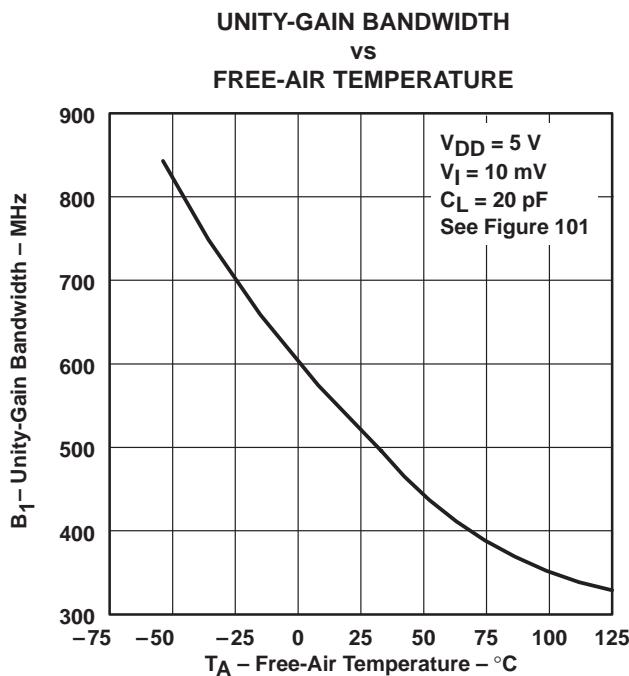


Figure 58

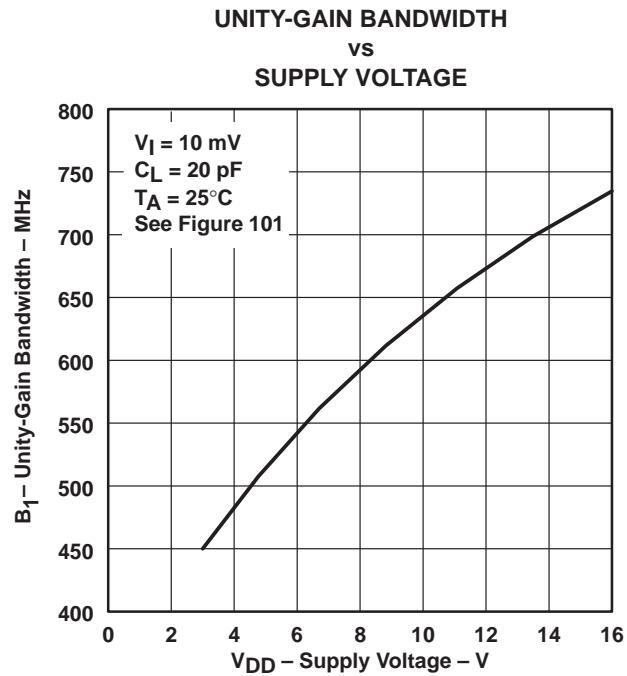


Figure 59

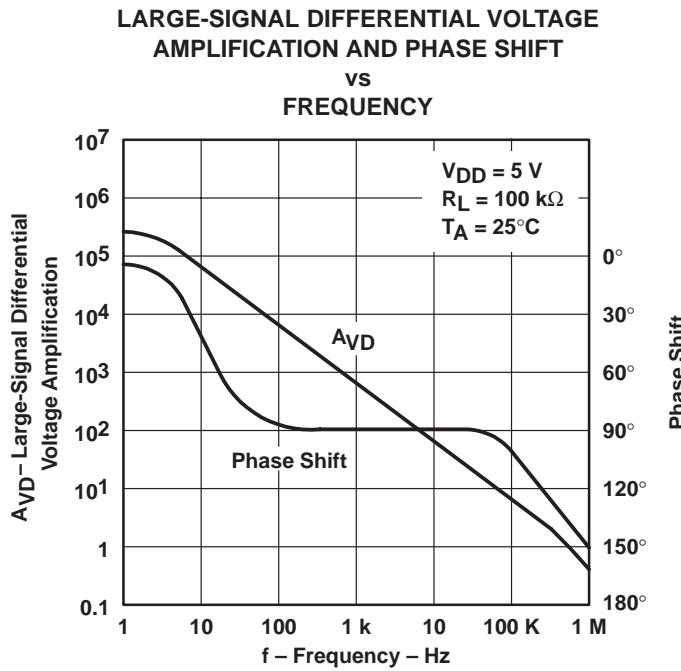


Figure 60

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (MEDIUM-BIAS MODE)†**

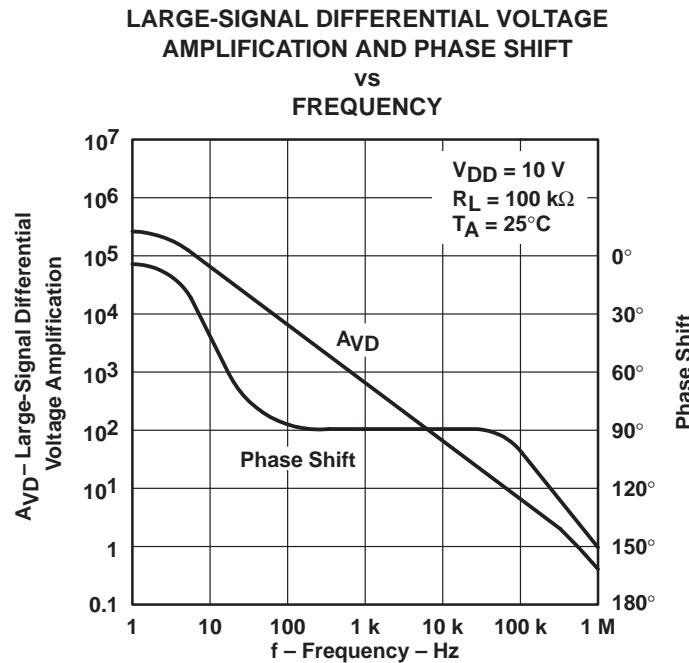


Figure 61

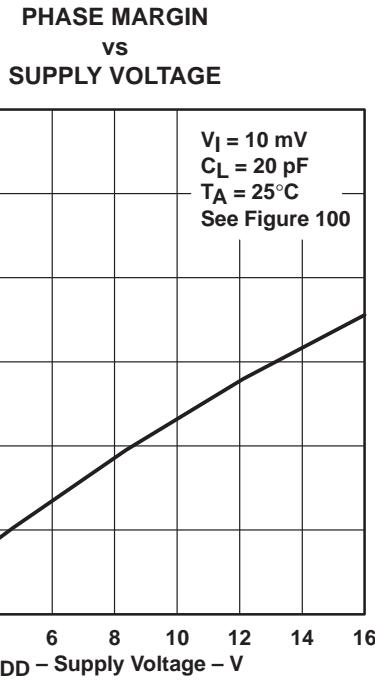


Figure 62

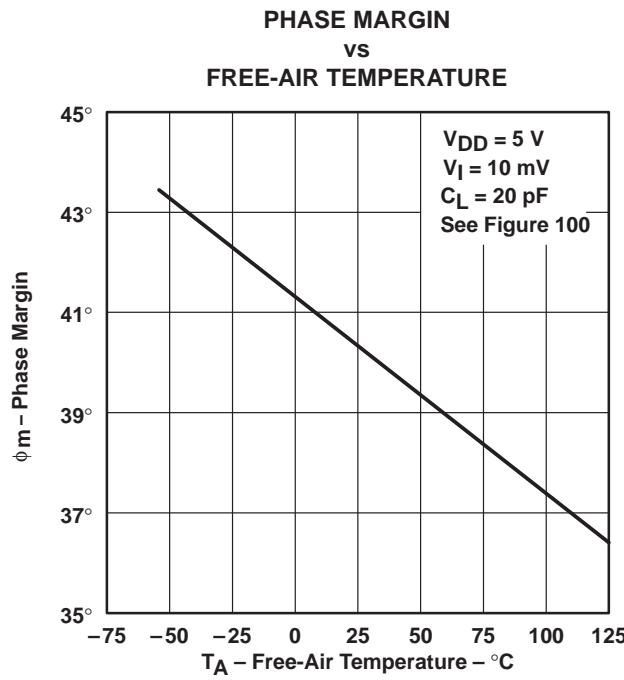
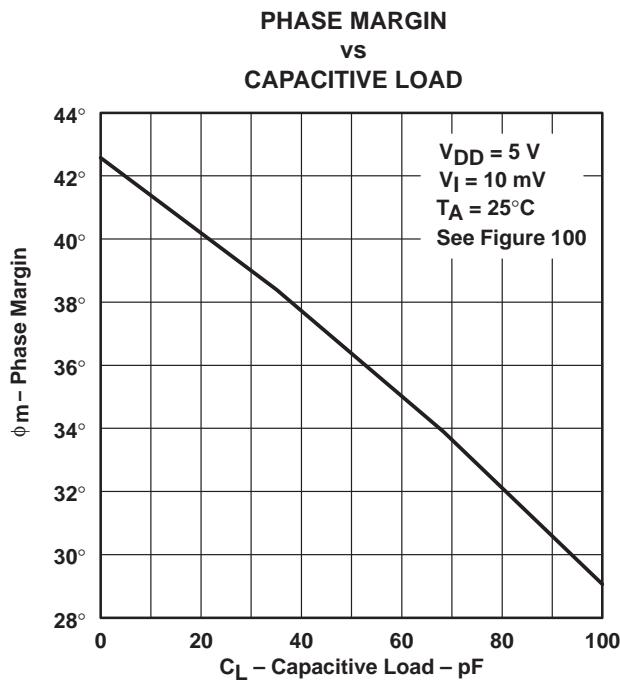


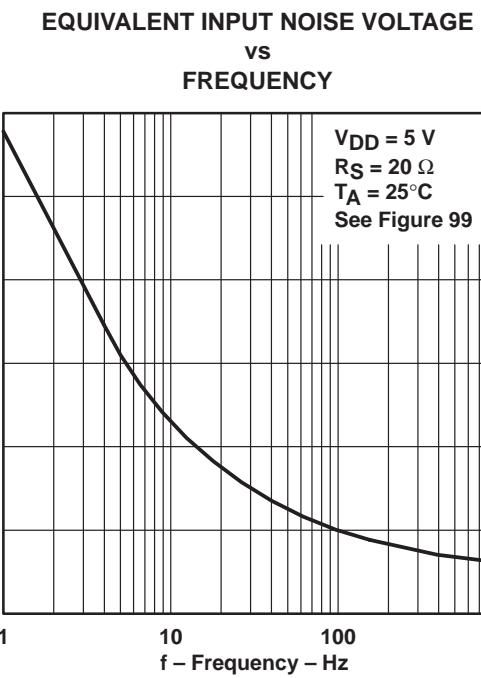
Figure 63

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

### TYPICAL CHARACTERISTICS (MEDIUM-BIAS MODE)†



**Figure 64**



**Figure 65**

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**LOW-BIAS MODE**

**electrical characteristics at specified free-air temperature (unless otherwise noted)**

PARAMETER		TEST CONDITIONS	TA <sup>†</sup>	TLC271C, TLC271AC, TLC271BC						UNIT	
				V <sub>DD</sub> = 5 V			V <sub>DD</sub> = 10 V				
				MIN	_TYP	MAX	MIN	_TYP	MAX		
V <sub>IO</sub>	Input offset voltage	V <sub>O</sub> = 1.4 V, V <sub>IC</sub> = 0 V, R <sub>S</sub> = 50 Ω, R <sub>I</sub> = 1 MΩ	25°C  Full range  25°C  Full range  25°C  Full range	1.1	10		1.1	10		mV	
					12			12			
				0.9	5		0.9	5			
					6.5			6.5			
				0.24	2		0.26	2			
					3			3			
αV <sub>IO</sub>	Average temperature coefficient of input offset voltage		25°C to 70°C	1.1			1			µV/°C	
I <sub>IO</sub>	Input offset current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.1			0.1			pA	
			70°C	7 300			8 300				
I <sub>IB</sub>	Input bias current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.6			0.7			pA	
			70°C	40 600			50 600				
V <sub>ICR</sub>	Common-mode input voltage range (see Note 5)		25°C	-0.2 to 4	-0.3 to 4.2		-0.2 to 9	-0.3 to 9.2		V	
			Full range	-0.2 to 3.5			-0.2 to 8.5			V	
V <sub>OH</sub>	High-level output voltage	V <sub>ID</sub> = 100 mV, R <sub>L</sub> = 1 MΩ	25°C	3.2	4.1		8	8.9		V	
			0°C	3	4.1		7.8	8.9			
			70°C	3	4.2		7.8	8.9			
V <sub>OL</sub>	Low-level output voltage	V <sub>ID</sub> = -100 mV, I <sub>OL</sub> = 0	25°C	0 50			0 50			mV	
			0°C	0 50			0 50				
			70°C	0 50			0 50				
AVD	Large-signal differential voltage amplification	R <sub>L</sub> = 1 MΩ, See Note 6	25°C	50	520		50	870		V/mV	
			0°C	50	700		50	1030			
			70°C	50	380		50	660			
CMRR	Common-mode rejection ratio	V <sub>IC</sub> = V <sub>ICR</sub> min	25°C	65	94		65	97		dB	
			0°C	60	95		60	97			
			70°C	60	95		60	97			
k <sub>SVR</sub>	Supply-voltage rejection ratio (ΔV <sub>DD</sub> /ΔV <sub>IO</sub> )	V <sub>DD</sub> = 5 V to 10 V V <sub>O</sub> = 1.4 V	25°C	70	97		70	97		dB	
			0°C	60	97		60	97			
			70°C	60	98		60	98			
I <sub>I(SEL)</sub>	Input current (BIAS SELECT)	V <sub>I(SEL)</sub> = V <sub>DD</sub>	25°C	65			95			nA	
I <sub>DD</sub>	Supply current	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2, No load	25°C	10 17			14 23			µA	
			0°C	12 21			18 33				
			70°C	8 14			11 20				

<sup>†</sup> Full range is 0°C to 70°C.

NOTES: 4. The typical values of input bias current and input offset current below 5 pA were determined mathematically.

5. This range also applies to each input individually.

6. At V<sub>DD</sub> = 5 V, V<sub>O</sub> = 0.25 V to 2 V; at V<sub>DD</sub> = 10 V, V<sub>O</sub> = 1 V to 6 V.



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### LOW-BIAS MODE

**electrical characteristics at specified free-air temperature (unless otherwise noted)**

PARAMETER		TEST CONDITIONS	TA <sup>†</sup>	TLC271I, TLC271AI, TLC271BI						UNIT	
				V <sub>DD</sub> = 5 V			V <sub>DD</sub> = 10 V				
				MIN	TYP	MAX	MIN	TYP	MAX		
V <sub>IO</sub>	Input offset voltage	V <sub>O</sub> = 1.4 V, V <sub>IC</sub> = 0 V, R <sub>S</sub> = 50 Ω, R <sub>L</sub> = 1 MΩ	25°C	1.1	10		1.1	10		mV	
			Full range		13			13			
			25°C	0.9	5		0.9	5			
			Full range		7			7			
			25°C	0.24	2		0.26	2			
			Full range		3.5			3.5			
α <sub>VIO</sub>	Average temperature coefficient of input offset voltage		25°C to 85°C	1.1			1			μV/°C	
I <sub>IO</sub>	Input offset current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.1			0.1			pA	
			85°C	24	1000		26	1000			
I <sub>IB</sub>	Input bias current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.6			0.7			pA	
			85°C	200	2000		220	2000			
V <sub>ICR</sub>	Common-mode input voltage range (see Note 5)		25°C	-0.2 to 4	-0.3 to 4.2		-0.2 to 9	-0.3 to 9.2		V	
			Full range	-0.2 to 3.5			-0.2 to 8.5			V	
			25°C	3	4.1		8	8.9		V	
			-40°C	3	4.1		7.8	8.9			
V <sub>OL</sub>	Low-level output voltage	V <sub>ID</sub> = 100 mV, R <sub>L</sub> = 1 MΩ	85°C	3	4.2		7.8	8.9			
			25°C	0	50		0	50		mV	
			-40°C	0	50		0	50			
			85°C	0	50		0	50			
A <sub>VD</sub>	Large-signal differential voltage amplification	R <sub>L</sub> = 1 MΩ See Note 6	25°C	50	520		50	870		V/mV	
			-40°C	50	900		50	1550			
			85°C	50	330		50	585			
			25°C	65	94		65	97		dB	
CMRR	Common-mode rejection ratio	V <sub>IC</sub> = V <sub>ICRmin</sub>	-40°C	60	95		60	97			
			85°C	60	95		60	98			
			25°C	70	97		70	97		dB	
k <sub>SVR</sub>	Supply-voltage rejection ratio ( $\Delta V_{DD}/\Delta V_{IO}$ )	V <sub>DD</sub> = 5 V to 10 V V <sub>O</sub> = 1.4 V	-40°C	60	97		60	97			
			85°C	60	98		60	98			
I <sub>I(SEL)</sub>	Input current (BIAS SELECT)	V <sub>I(SEL)</sub> = V <sub>DD</sub>	25°C	65			95			nA	
I <sub>DD</sub>	Supply current	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2, No load	25°C	10	17		14	23		μA	
			-40°C	16	27		25	43			
			85°C	17	13		10	18			

<sup>†</sup> Full range is -40 to 85°C.

NOTES: 4. The typical values of input bias current and input offset current below 5 pA were determined mathematically.

5. This range also applies to each input individually.

6. At V<sub>DD</sub> = 5 V, V<sub>O</sub> = 0.25 V to 2 V; at V<sub>DD</sub> = 10 V, V<sub>O</sub> = 1 V to 6 V.

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**LOW-BIAS MODE**

**electrical characteristics at specified free-air temperature (unless otherwise noted)**

PARAMETER	TEST CONDITIONS	TA <sup>†</sup>	TLC271M						UNIT	
			V <sub>DD</sub> = 5 V			V <sub>DD</sub> = 10 V				
			MIN	TYP	MAX	MIN	TYP	MAX		
V <sub>IO</sub> Input offset voltage	V <sub>O</sub> = 1.4 V, V <sub>IC</sub> = 0 V, R <sub>S</sub> = 50 Ω, R <sub>L</sub> = 1 MΩ	25°C	1.1	10		1.1	10		mV	
		Full range		12			12			
α <sub>VIO</sub> Average temperature coefficient of input offset voltage		25°C to 125°C	1.4			1.4			μV/°C	
I <sub>IO</sub> Input offset current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.1			0.1			pA	
		125°C	1.4	15		1.8	15		nA	
I <sub>IB</sub> Input bias current (see Note 4)	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2	25°C	0.6			0.7			pA	
		125°C	9	35		10	35		nA	
V <sub>ICR</sub> Common-mode input voltage range (see Note 5)		25°C	0 to 4	-0.3 to 4.2		0 to 9	-0.3 to 9.2		V	
		Full range	0 to 3.5			0 to 8.5			V	
V <sub>OH</sub> High-level output voltage	V <sub>ID</sub> = 100 mV, R <sub>L</sub> = 1 MΩ	25°C	3.2	4.1		8	8.9		V	
		-55°C	3	4.1		7.8	8.8			
		125°C	3	4.2		7.8	9			
V <sub>OL</sub> Low-level output voltage	V <sub>ID</sub> = -100 mV, I <sub>OL</sub> = 0	25°C	0	50		0	50		mV	
		-55°C	0	50		0	50			
		125°C	0	50		0	50			
AVD Large-signal differential voltage amplification	R <sub>L</sub> = 1 MΩ, See Note 6	25°C	50	520		50	870		V/mV	
		-55°C	25	1000		25	1775			
		125°C	25	200		25	380			
CMRR Common-mode rejection ratio	V <sub>IC</sub> = V <sub>ICRmin</sub>	25°C	65	94		65	97		dB	
		-55°C	60	95		60	97			
		125°C	60	85		60	91			
k <sub>SVR</sub> Supply-voltage rejection ratio (ΔV <sub>DD</sub> /ΔV <sub>IO</sub> )	V <sub>DD</sub> = 5 V to 10 V V <sub>O</sub> = 1.4 V	25°C	70	97		70	97		dB	
		-55°C	60	97		60	97			
		125°C	60	98		60	98			
I <sub>I(SEL)</sub> Input current (BIAS SELECT)	V <sub>I(SEL)</sub> = V <sub>DD</sub>	25°C	65			95			nA	
I <sub>DD</sub> Supply current	V <sub>O</sub> = V <sub>DD</sub> /2, V <sub>IC</sub> = V <sub>DD</sub> /2, No load	25°C	10	17		14	23		μA	
		-55°C	17	30		28	48			
		125°C	7	12		9	15			

<sup>†</sup> Full range is -55°C to 125°C.

- NOTES: 4. The typical values of input bias current and input offset current below 5 pA were determined mathematically.  
 5. This range also applies to each input individually.  
 6. At V<sub>DD</sub> = 5 V, V<sub>O</sub> = 0.25 V to 2 V; at V<sub>DD</sub> = 10 V, V<sub>O</sub> = 1 V to 6 V.



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### LOW-BIAS MODE

**operating characteristics at specified free-air temperature,  $V_{DD} = 5\text{ V}$**

PARAMETER	TEST CONDITIONS	$T_A$	TLC271C, TLC271AC, TLC271BC			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 1\text{ M}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	25°C	0.03			V/ $\mu\text{s}$
		0°C	0.04			
		70°C	0.03			
		25°C	0.03			
	$V_I(\text{PP}) = 2.5\text{ V}$	0°C	0.03			V/ $\mu\text{s}$
		70°C	0.02			
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	68		nV/ $\sqrt{\text{Hz}}$
$B_{\text{OM}}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 1\text{ M}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	5		kHz
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	0°C	6		
			70°C	4.5		
			25°C	85		kHz
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ , See Figure 100	$f = B_1$ ,	0°C	100		
			70°C	65		
			25°C	34°		kHz
			0°C	36°		
			70°C	30°		

**operating characteristics at specified free-air temperature,  $V_{DD} = 10\text{ V}$**

PARAMETER	TEST CONDITIONS	$T_A$	TLC271C, TLC271AC, TLC271BC			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 1\text{ M}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	25°C	0.05			V/ $\mu\text{s}$
		0°C	0.05			
		70°C	0.04			
	$V_I(\text{PP}) = 5.5\text{ V}$	25°C	0.04			
		0°C	0.05			kHz
		70°C	0.04			
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	68		nV/ $\sqrt{\text{Hz}}$
$B_{\text{OM}}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 1\text{ M}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	1		kHz
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	0°C	1.3		
			70°C	0.9		
			25°C	110		kHz
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ , See Figure 100	$f = B_1$ ,	0°C	125		
			70°C	90		
			25°C	38°		kHz
			0°C	40°		
			70°C	34°		

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**LOW-BIAS MODE**

**operating characteristics at specified free-air temperature,  $V_{DD} = 5\text{ V}$**

PARAMETER	TEST CONDITIONS	$T_A$	TLC271I, TLC271AI, TLC271BI			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 1\text{ M}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	0.03		V/ $\mu\text{s}$
			-40°C	0.04		
			85°C	0.03		
		$V_I(\text{PP}) = 2.5\text{ V}$	25°C	0.03		
			-40°C	0.04		
			85°C	0.02		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	68		nV/ $\sqrt{\text{Hz}}$
$B_{OM}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 1\text{ M}\Omega$ , See Figure 98	$C_L = 20\text{ pF}$ , See Figure 98	25°C	5		kHz
			-40°C	7		
			85°C	4		
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ , See Figure 100	25°C	85		MHz
			-40°C	130		
			85°C	55		
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ , See Figure 100	$f = B_1$ , See Figure 100	25°C	34°		
			-40°C	38°		
			85°C	28°		

**operating characteristics at specified free-air temperature,  $V_{DD} = 10\text{ V}$**

PARAMETER	TEST CONDITIONS	$T_A$	TLC271C, TLC271AC, TLC271BC			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 1\text{ M}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	0.05		V/ $\mu\text{s}$
			-40°C	0.06		
			85°C	0.03		
		$V_I(\text{PP}) = 5.5\text{ V}$	25°C	0.04		
			-40°C	0.05		
			85°C	0.03		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	68		nV/ $\sqrt{\text{Hz}}$
$B_{OM}$ Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 1\text{ M}\Omega$ , See Figure 98	$C_L = 20\text{ pF}$ , See Figure 98	25°C	1		kHz
			-40°C	1.4		
			85°C	0.8		
$B_1$ Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ , See Figure 100	25°C	110		MHz
			-40°C	155		
			85°C	80		
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ , See Figure 100	$f = B_1$ , See Figure 100	25°C	38°		
			-40°C	42°		
			85°C	32°		

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### LOW-BIAS MODE

**operating characteristics at specified free-air temperature,  $V_{DD} = 5\text{ V}$**

PARAMETER	TEST CONDITIONS	TA	TLC271M			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 1\text{ M}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	0.03		V/ $\mu\text{s}$
			-55°C	0.04		
		$V_I(\text{PP}) = 2.5\text{ V}$	125°C	0.02		
			25°C	0.03		
			-55°C	0.04		
			125°C	0.02		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	68		nV/ $\sqrt{\text{Hz}}$
B <sub>OM</sub> Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 1\text{ M}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	5		kHz
B <sub>1</sub> Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	-55°C	8		
			125°C	3		
			25°C	85		kHz
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ , See Figure 100	$f = B_1$ ,	-55°C	140		
			125°C	45		
			25°C	34°		
			-55°C	39°		
			125°C	25°		

**operating characteristics at specified free-air temperature,  $V_{DD} = 10\text{ V}$**

PARAMETER	TEST CONDITIONS	TA	TLC271M			UNIT
			MIN	TYP	MAX	
SR Slew rate at unity gain	$R_L = 1\text{ M}\Omega$ , $C_L = 20\text{ pF}$ , See Figure 98	$V_I(\text{PP}) = 1\text{ V}$	25°C	0.05		V/ $\mu\text{s}$
			-55°C	0.06		
		$V_I(\text{PP}) = 5.5\text{ V}$	125°C	0.03		
			25°C	0.04		
			-55°C	0.06		
			125°C	0.03		
$V_n$ Equivalent input noise voltage	$f = 1\text{ kHz}$ , See Figure 99	$R_S = 20\text{ }\Omega$ ,	25°C	68		nV/ $\sqrt{\text{Hz}}$
B <sub>OM</sub> Maximum output-swing bandwidth	$V_O = V_{OH}$ , $R_L = 1\text{ M}\Omega$ ,	$C_L = 20\text{ pF}$ , See Figure 98	25°C	1		kHz
B <sub>1</sub> Unity-gain bandwidth	$V_I = 10\text{ mV}$ , See Figure 100	$C_L = 20\text{ pF}$ ,	-55°C	1.5		
			125°C	0.7		
			25°C	110		kHz
$\phi_m$ Phase margin	$V_I = 10\text{ mV}$ , $C_L = 20\text{ pF}$ , See Figure 100	$f = B_1$ ,	-55°C	165		
			125°C	70		
			25°C	38°		
			-55°C	43°		
			125°C	29°		

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**TYPICAL CHARACTERISTICS (LOW-BIAS MODE)**

**Table of Graphs**

			<b>FIGURE</b>
$V_{IO}$	Input offset voltage	Distribution	66, 67
$\alpha V_{IO}$	Temperature coefficient	Distribution	68, 69
$V_{OH}$	High-level output voltage	vs High-level output current vs Supply voltage vs Free-air temperature	70, 71 72 73
$V_{OL}$	Low-level output voltage	vs Common-mode input voltage vs Differential input voltage vs Free-air temperature vs Low-level output current	74, 75 76 77 78, 79
$A_{VD}$	Large-signal differential voltage amplification	vs Supply voltage vs Free-air temperature vs Frequency	80 81 92, 93
$I_{IB}$	Input bias current	vs Free-air temperature	82
$I_{IO}$	Input offset current	vs Free-air temperature	82
$V_I$	Maximum input voltage	vs Supply voltage	83
$I_{DD}$	Supply current	vs Supply voltage vs Free-air temperature	84 85
SR	Slew rate	vs Supply voltage vs Free-air temperature	86 87
	Bias-select current	vs Supply voltage	88
$V_{O(PP)}$	Maximum peak-to-peak output voltage	vs Frequency	89
$B_1$	Unity-gain bandwidth	vs Free-air temperature vs Supply voltage	90 91
$\phi_m$	Phase margin	vs Supply voltage vs Free-air temperature vs Capacitive load	94 95 96
$V_n$	Equivalent input noise voltage	vs Frequency	97
	Phase shift	vs Frequency	92, 93

### TYPICAL CHARACTERISTICS (LOW-BIAS MODE)†

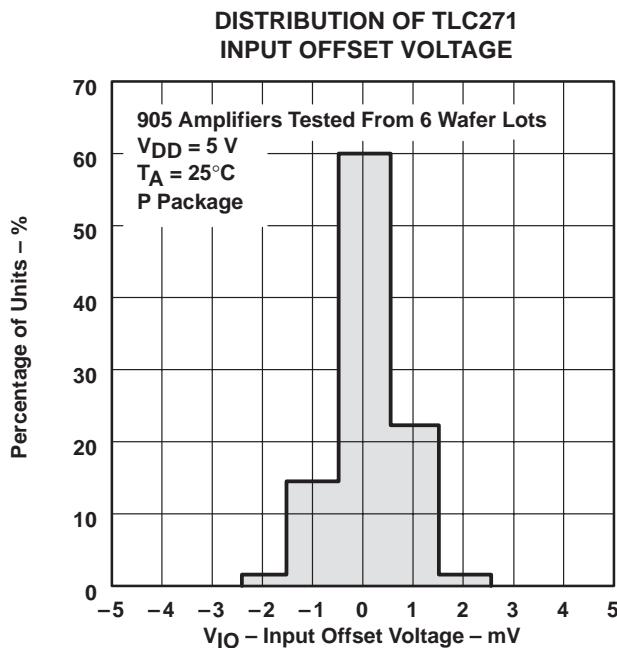


Figure 66

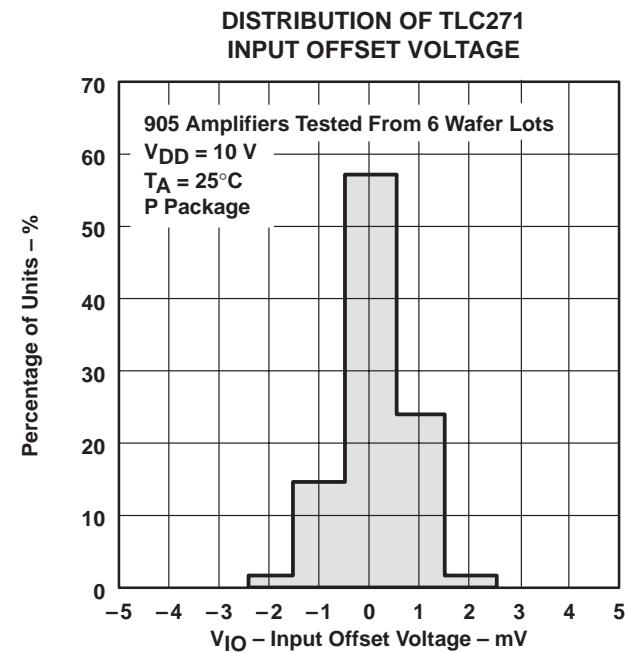


Figure 67

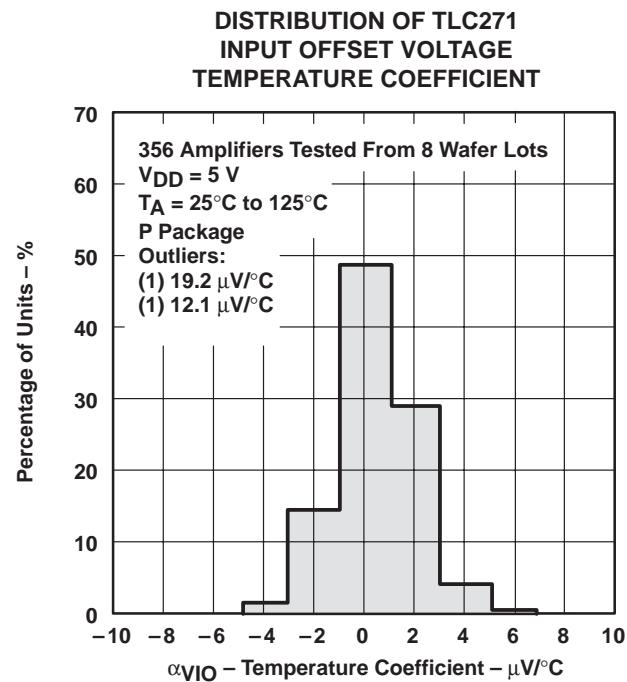


Figure 68

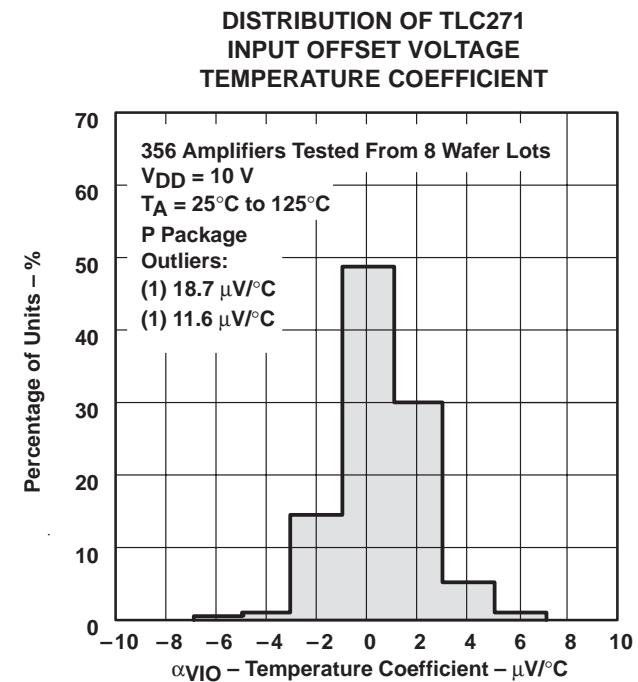


Figure 69

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (LOW-BIAS MODE)†**

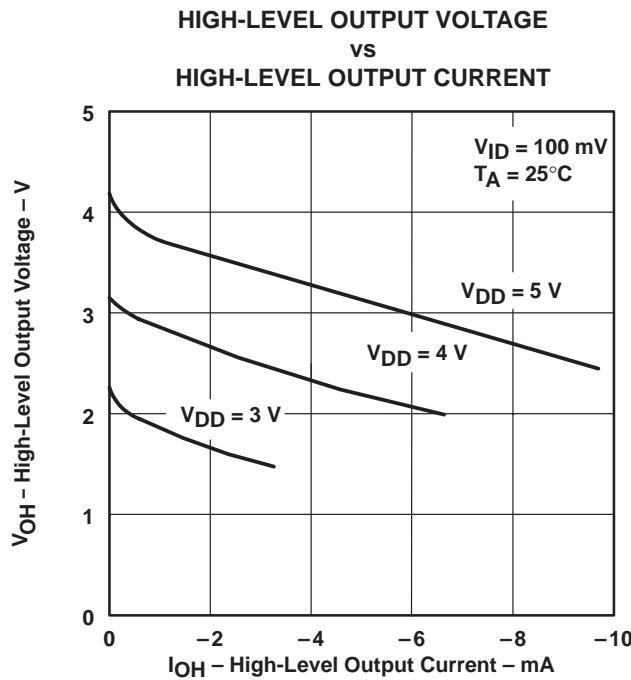


Figure 70

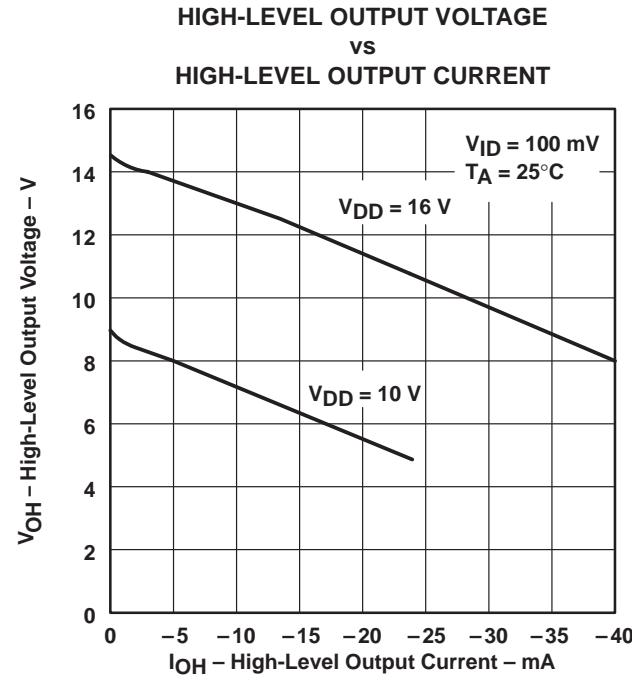


Figure 71

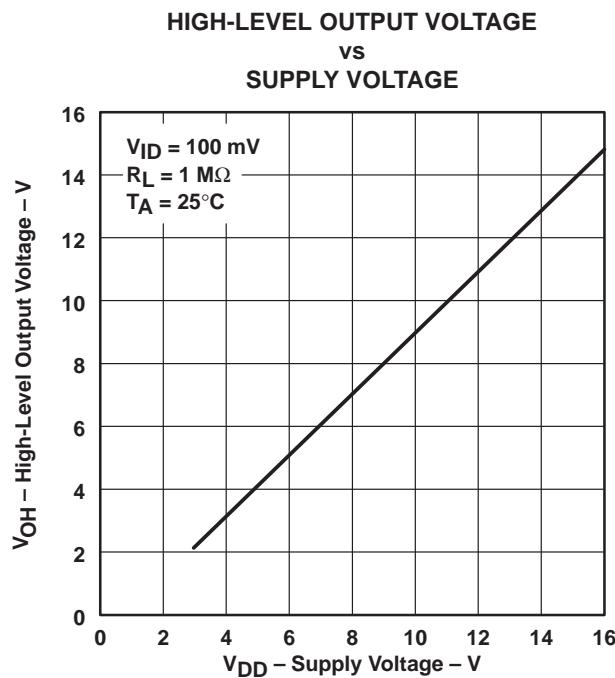


Figure 72

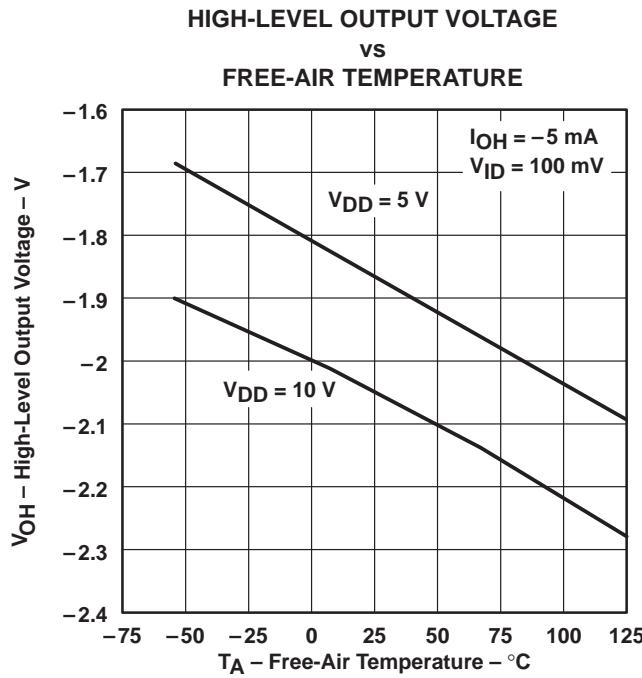


Figure 73

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

### TYPICAL CHARACTERISTICS (LOW-BIAS MODE)†

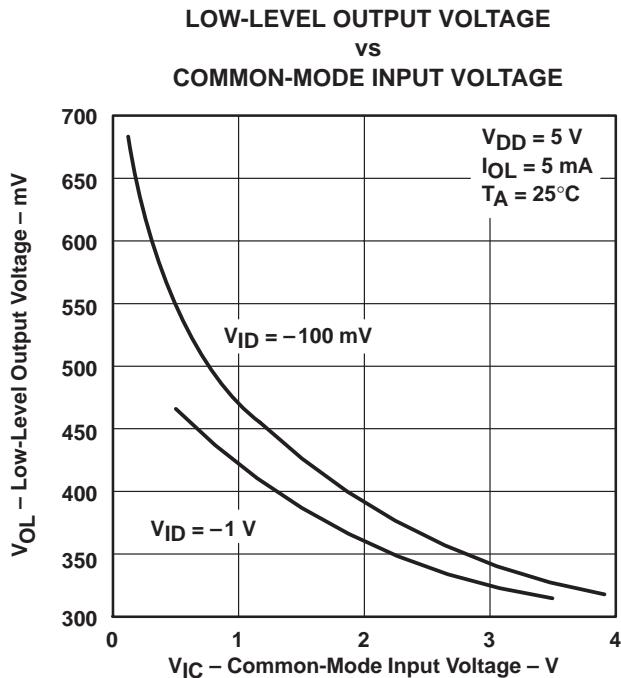


Figure 74

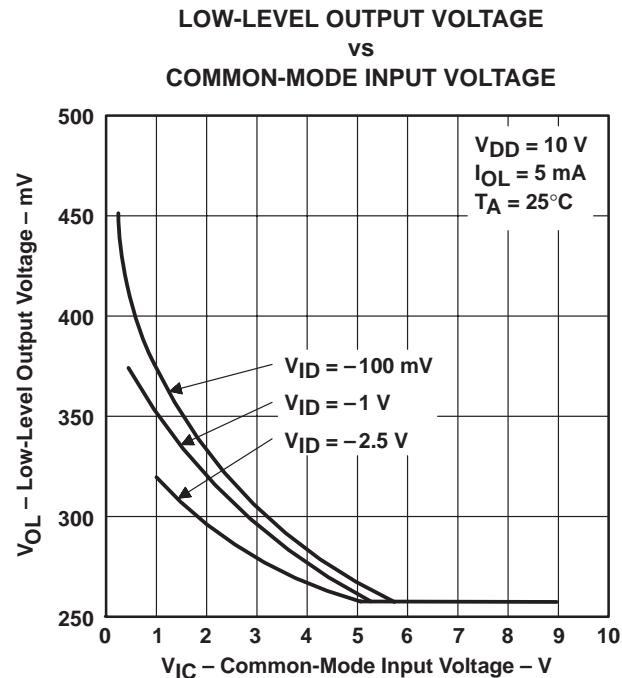


Figure 75

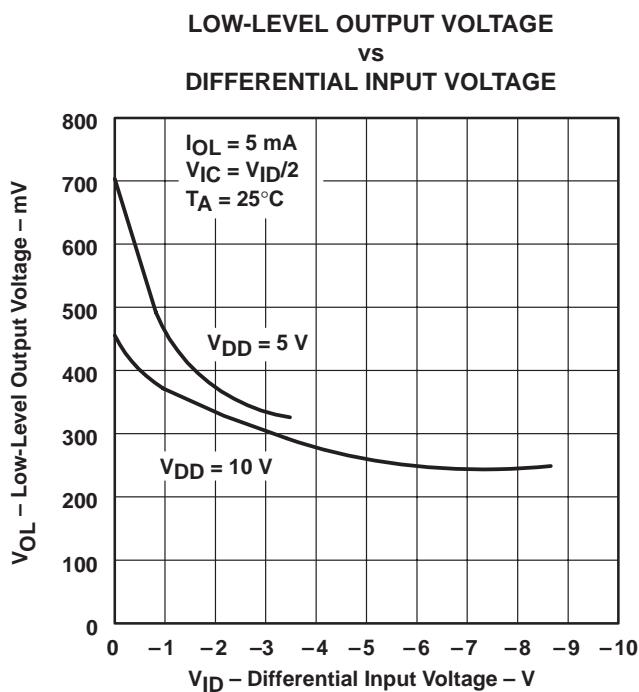


Figure 76

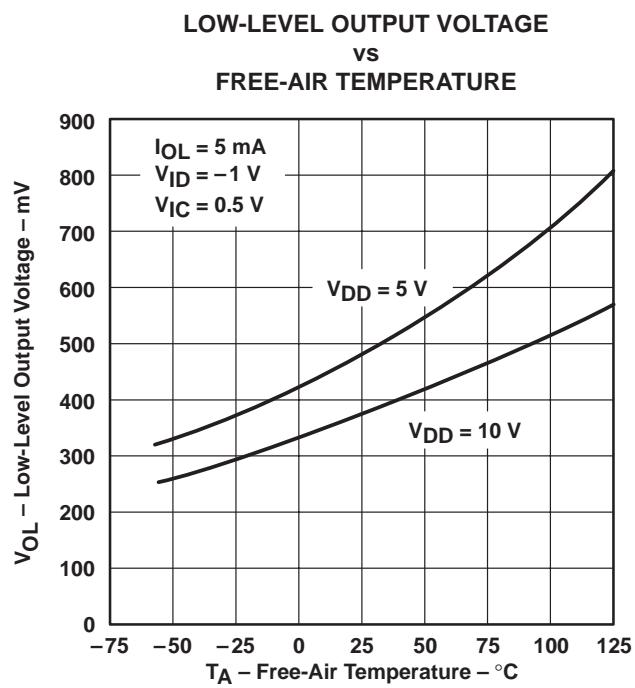


Figure 77

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (LOW-BIAS MODE)†**

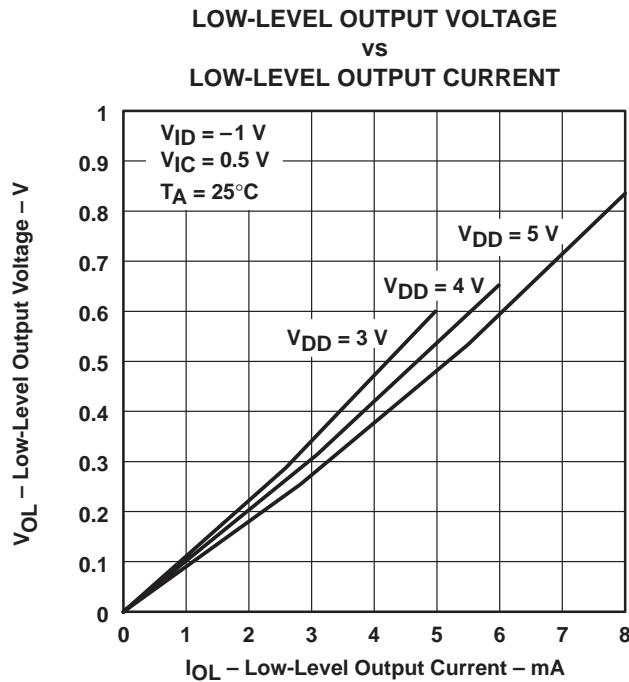


Figure 78

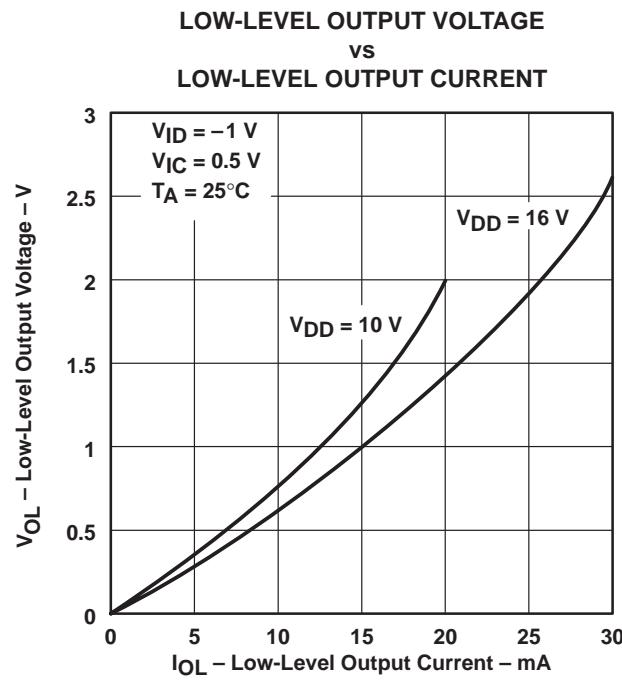


Figure 79

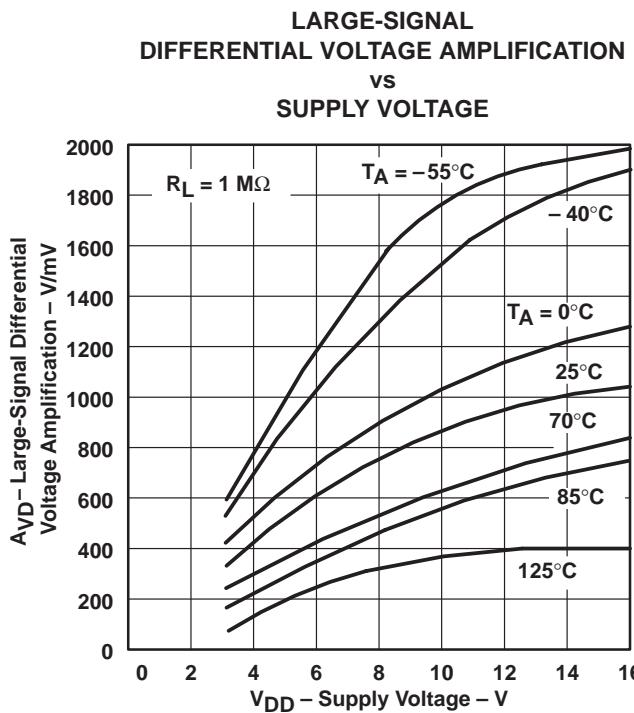


Figure 80

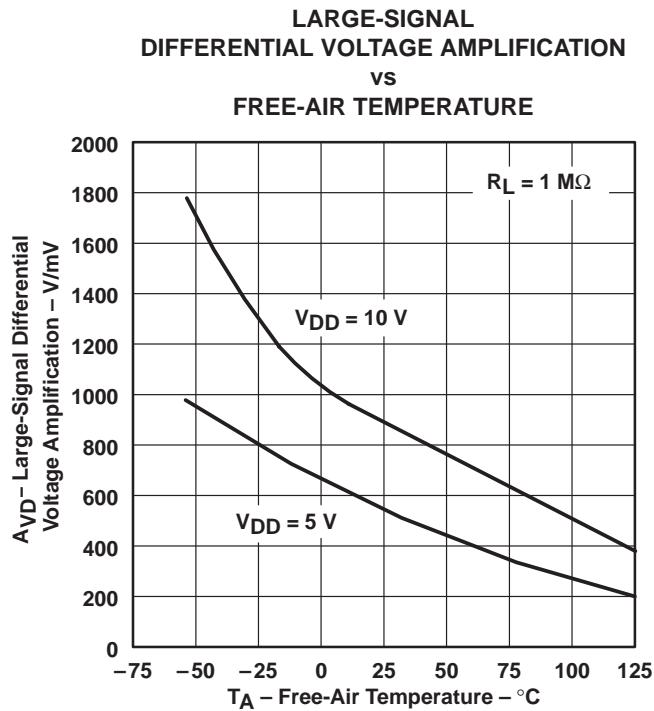
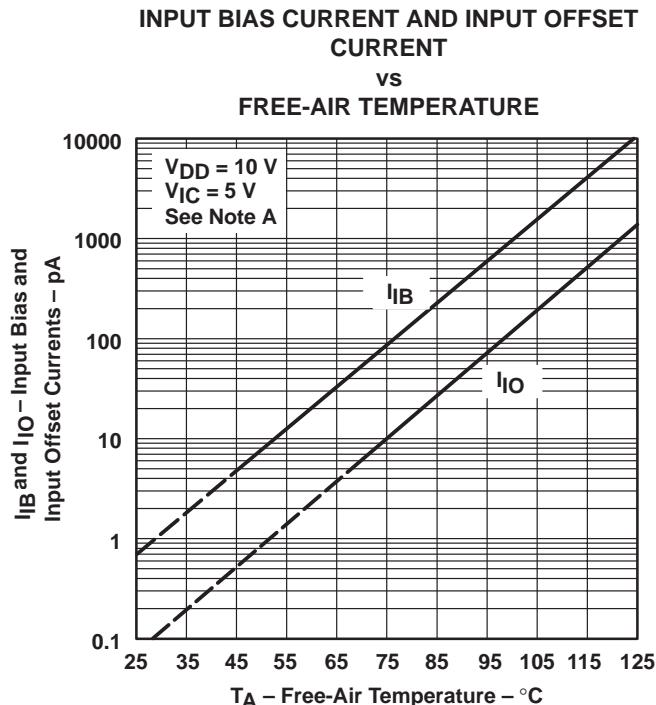


Figure 81

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

### TYPICAL CHARACTERISTICS (LOW-BIAS MODE)†



NOTE A: The typical values of input bias current and input offset current below 5 pA were determined mathematically.

Figure 82

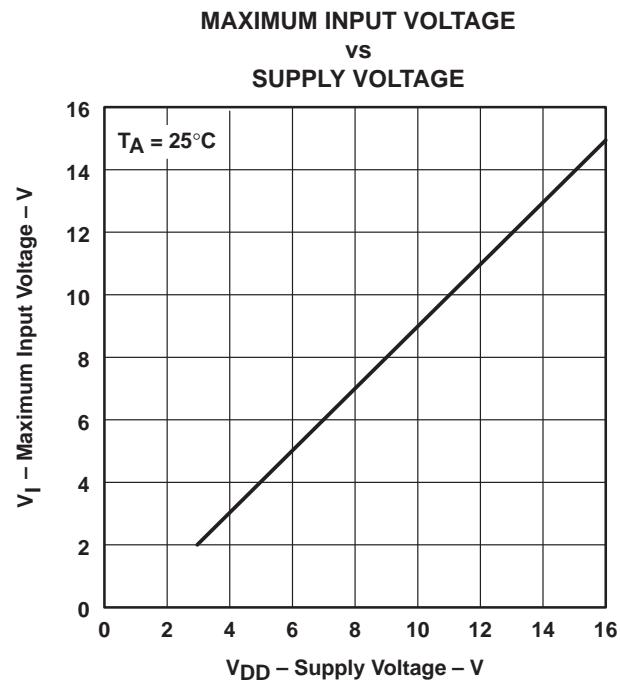


Figure 83

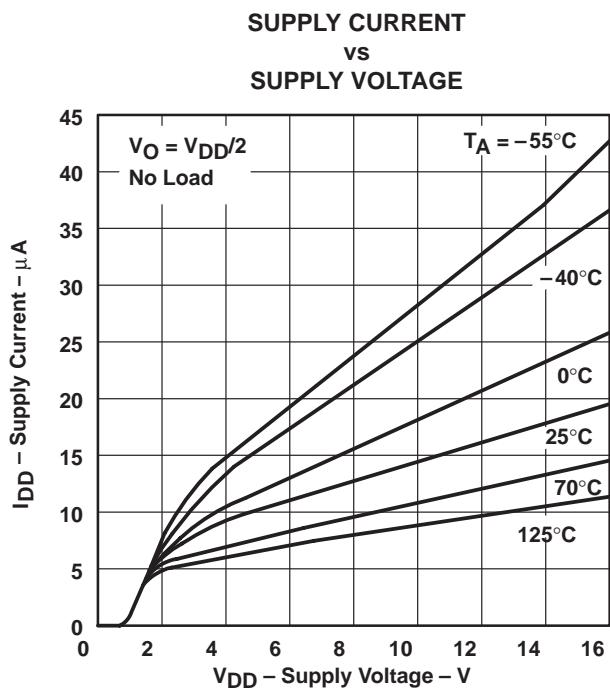


Figure 84

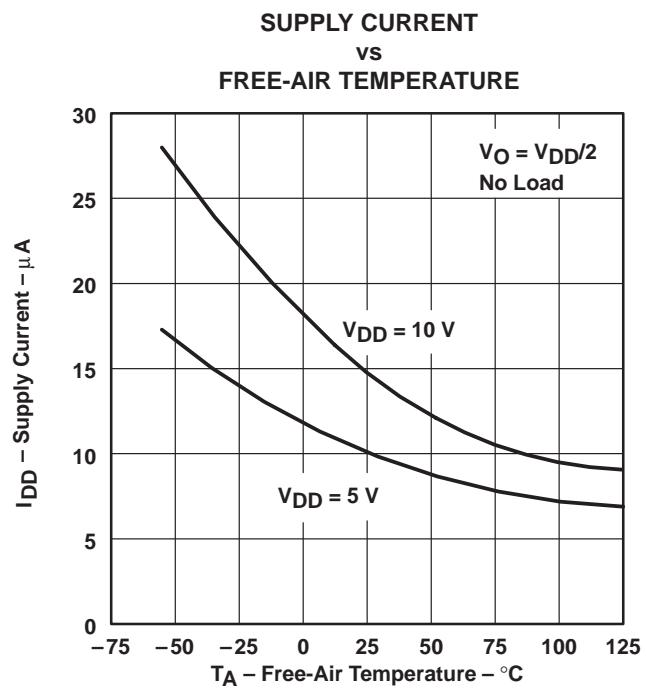


Figure 85

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (LOW-BIAS MODE)†**

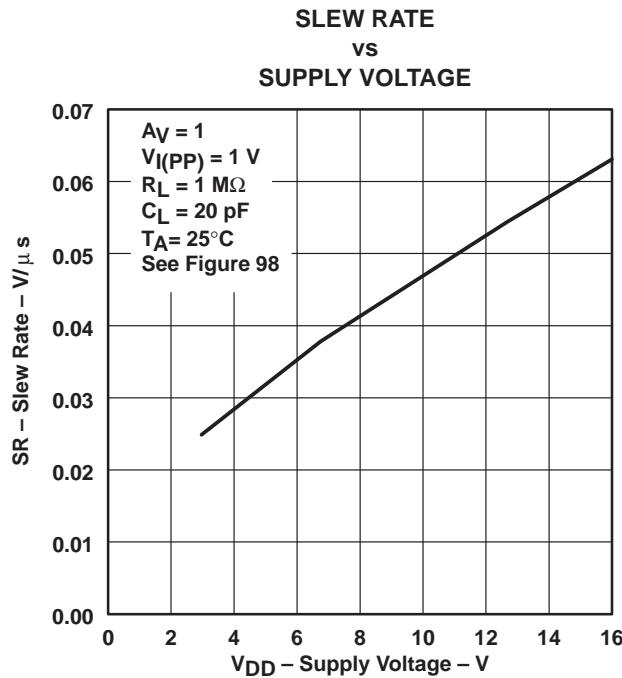


Figure 86

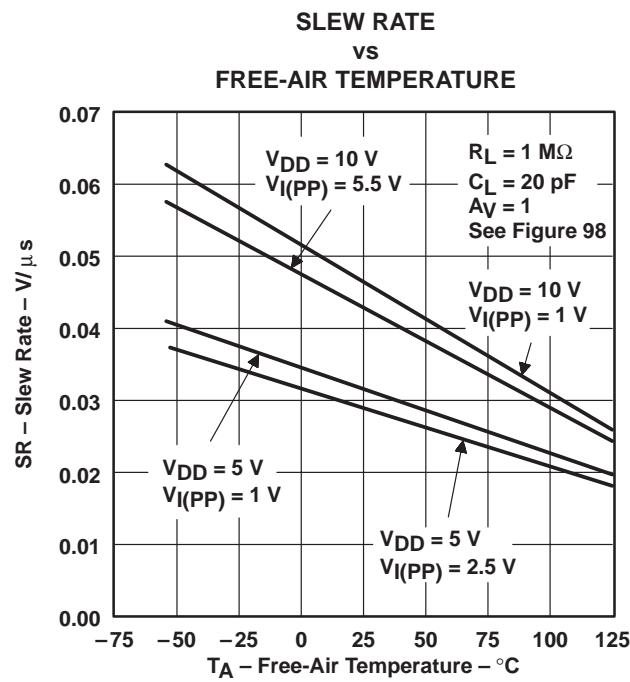


Figure 87

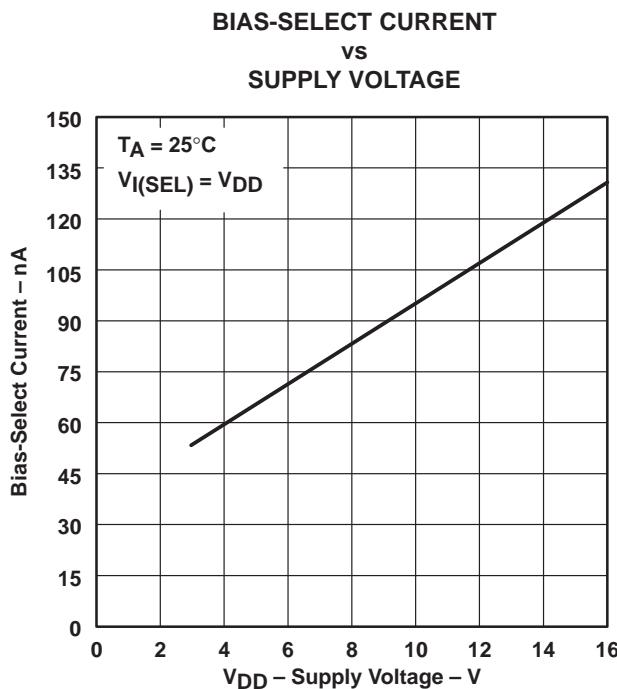


Figure 88

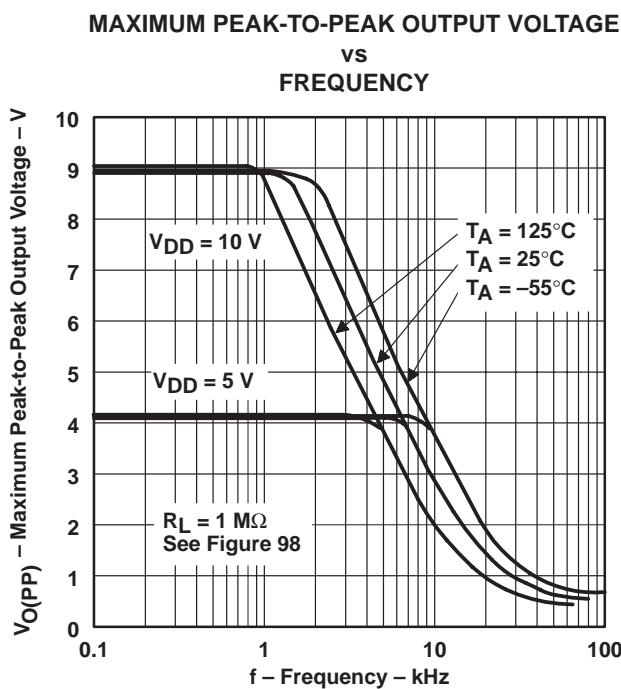


Figure 89

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

### TYPICAL CHARACTERISTICS (LOW-BIAS MODE)†

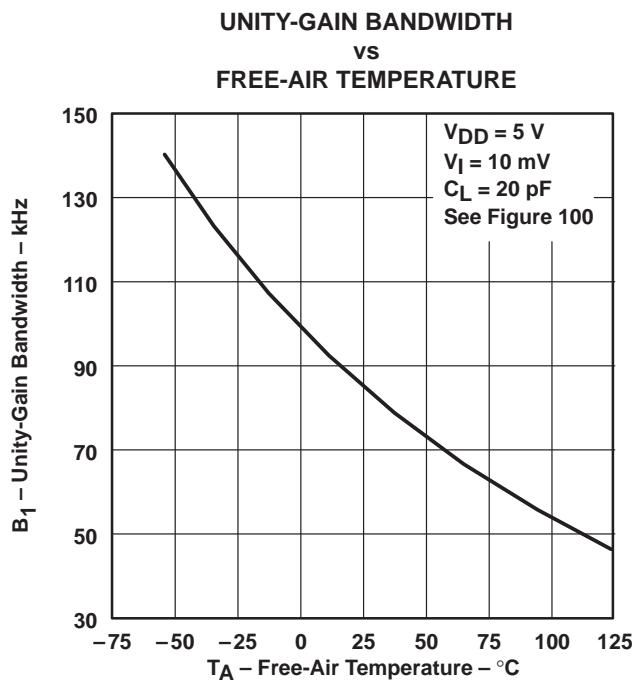


Figure 90

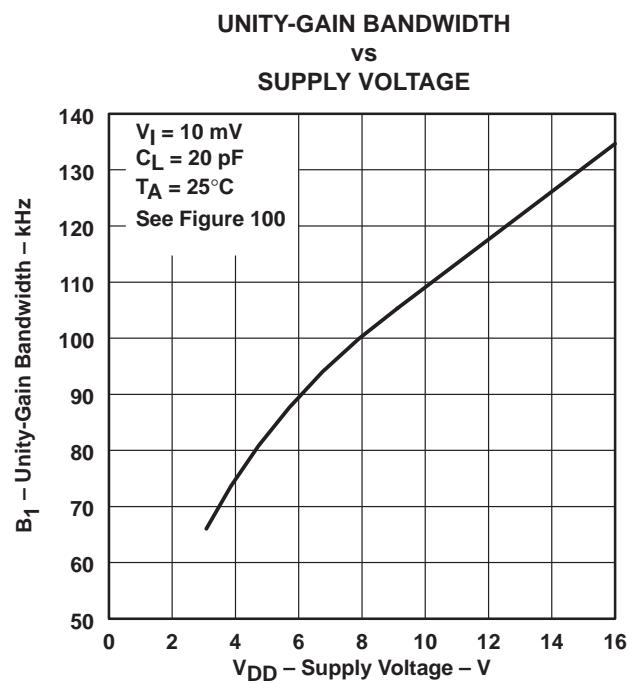


Figure 91

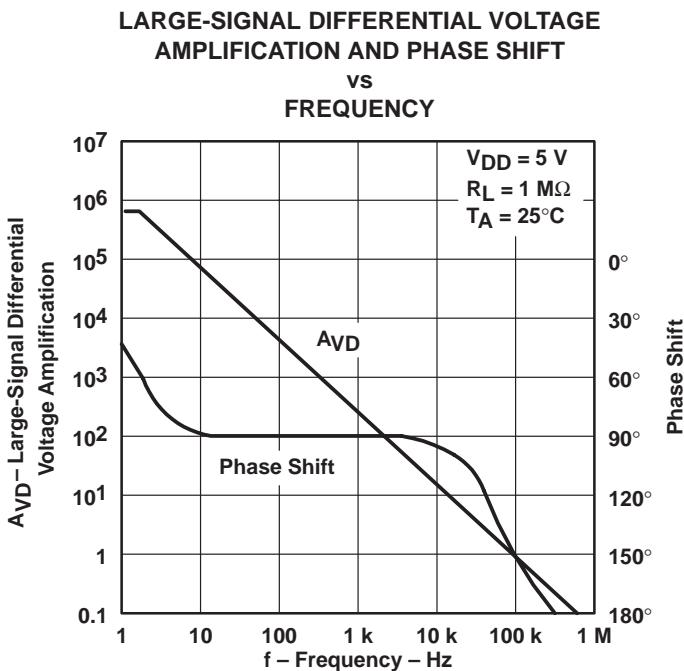


Figure 92

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**TYPICAL CHARACTERISTICS (LOW-BIAS MODE)†**

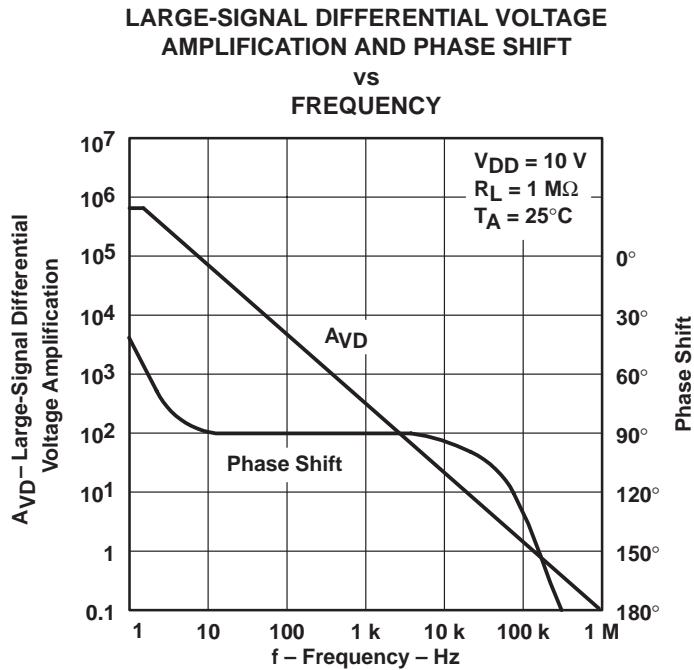


Figure 93

**PHASE MARGIN  
vs  
SUPPLY VOLTAGE**

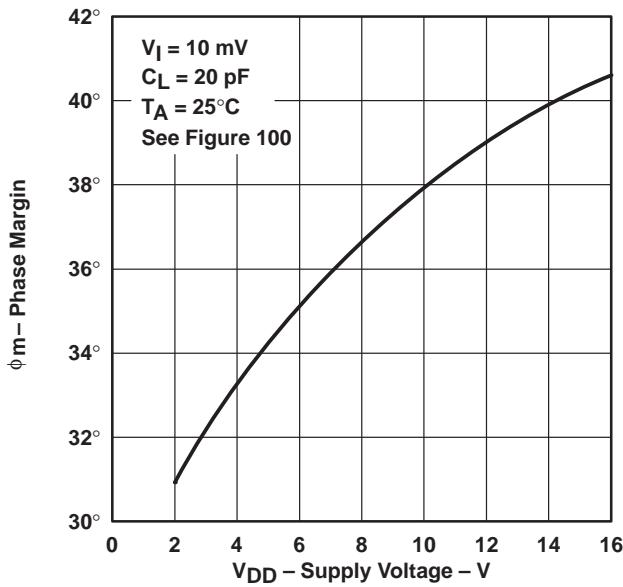


Figure 94

**PHASE MARGIN  
vs  
FREE-AIR TEMPERATURE**

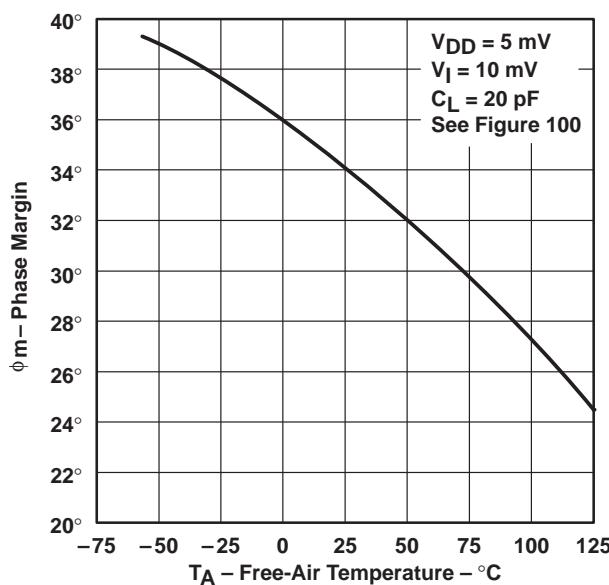
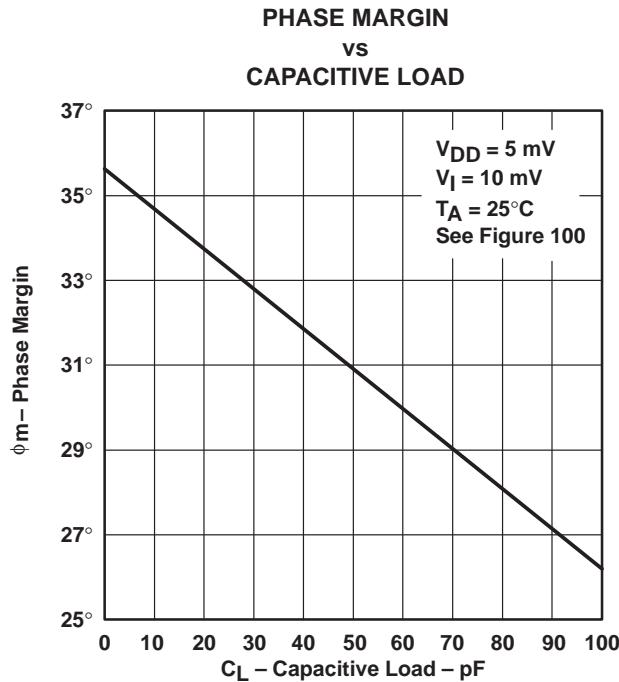


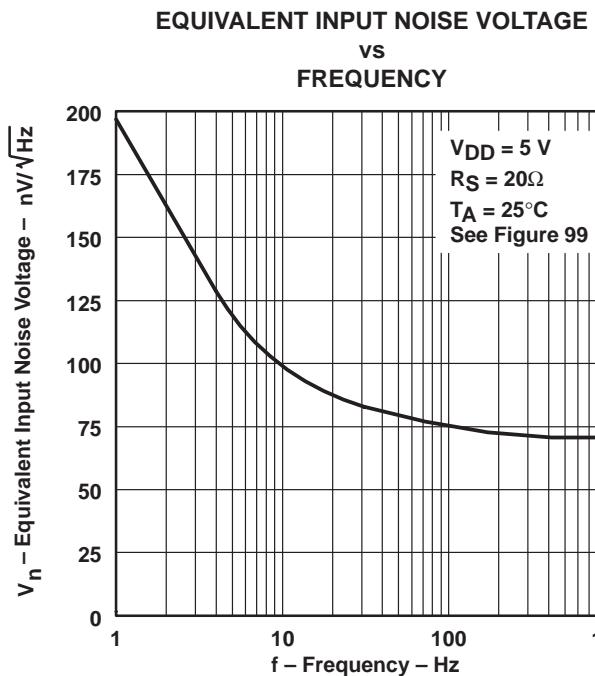
Figure 95

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

**TYPICAL CHARACTERISTICS (LOW-BIAS MODE)†**



**Figure 96**



**Figure 97**

† Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

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**PARAMETER MEASUREMENT INFORMATION**

**single-supply versus split-supply test circuits**

Because the TLC271 is optimized for single-supply operation, circuit configurations used for the various tests often present some inconvenience since the input signal, in many cases, must be offset from ground. This inconvenience can be avoided by testing the device with split supplies and the output load tied to the negative rail. A comparison of single-supply versus split-supply test circuits is shown below. The use of either circuit gives the same result.

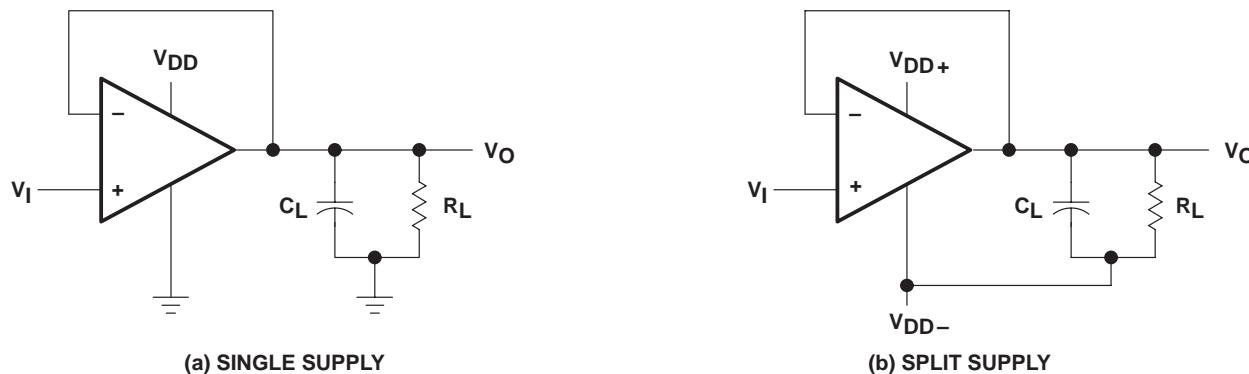


Figure 98. Unity-Gain Amplifier

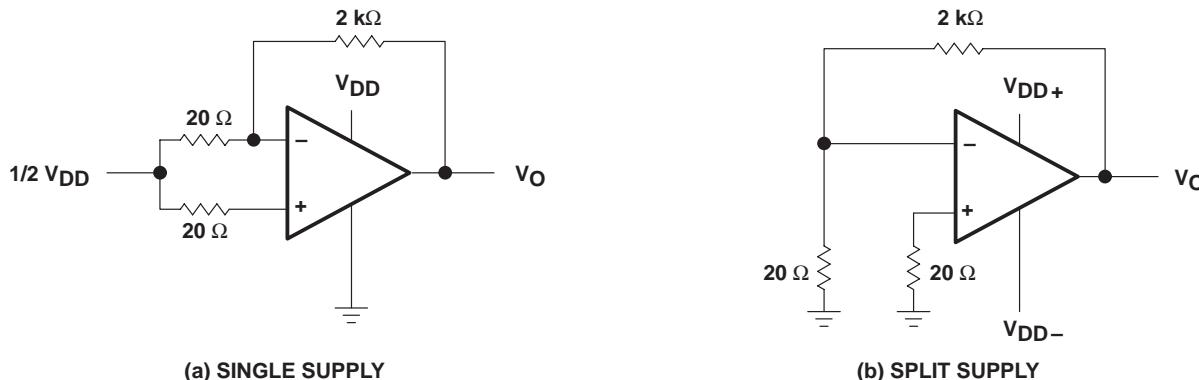


Figure 99. Noise-Test Circuit

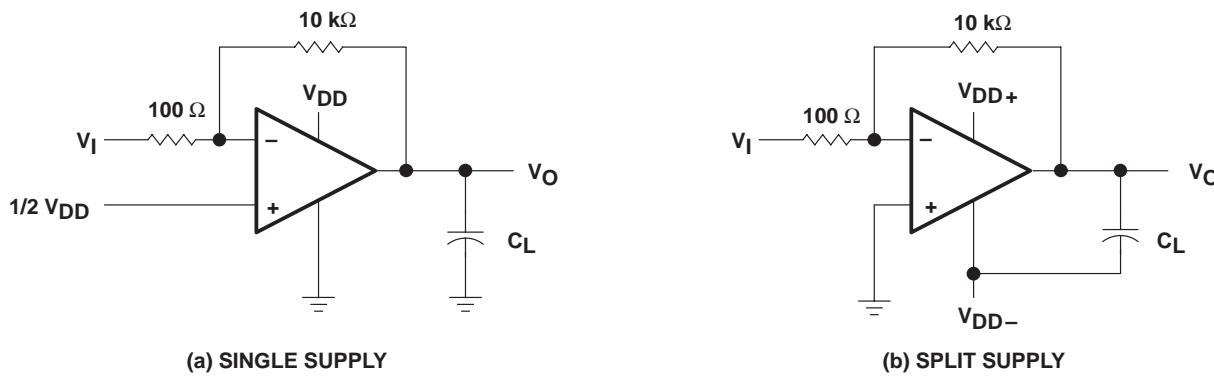


Figure 100. Gain-of-100 Inverting Amplifier

## PARAMETER MEASUREMENT INFORMATION

### **input bias current**

Because of the high input impedance of the TLC271 operational amplifiers, attempts to measure the input bias current can result in erroneous readings. The bias current at normal room ambient temperature is typically less than 1 pA, a value that is easily exceeded by leakages on the test socket. Two suggestions are offered to avoid erroneous measurements:

1. Isolate the device from other potential leakage sources. Use a grounded shield around and between the device inputs (see Figure 101). Leakages that would otherwise flow to the inputs are shunted away.
2. Compensate for the leakage of the test socket by actually performing an input bias current test (using a picoammeter) with no device in the test socket. The actual input bias current can then be calculated by subtracting the open-socket leakage readings from the readings obtained with a device in the test socket.

One word of caution: many automatic testers as well as some bench-top operational amplifier testers use the servo-loop technique with a resistor in series with the device input to measure the input bias current (the voltage drop across the series resistor is measured and the bias current is calculated). This method requires that a device be inserted into the test socket to obtain a correct reading; therefore, an open-socket reading is not feasible using this method.

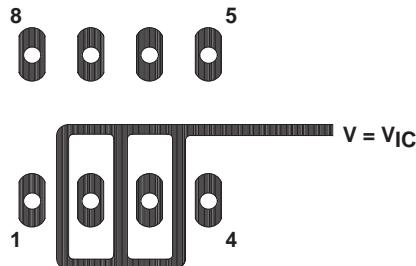


Figure 101. Isolation Metal Around Device inputs (JG and P packages)

### **low-level output voltage**

To obtain low-supply-voltage operation, some compromise is necessary in the input stage. This compromise results in the device low-level output being dependent on both the common-mode input voltage level as well as the differential input voltage level. When attempting to correlate low-level output readings with those quoted in the electrical specifications, these two conditions should be observed. If conditions other than these are to be used, please refer to the Typical Characteristics section of this data sheet.

### **input offset voltage temperature coefficient**

Erroneous readings often result from attempts to measure temperature coefficient of input offset voltage. This parameter is actually a calculation using input offset voltage measurements obtained at two different temperatures. When one (or both) of the temperatures is below freezing, moisture can collect on both the device and the test socket. This moisture results in leakage and contact resistance which can cause erroneous input offset voltage readings. The isolation techniques previously mentioned have no effect on the leakage since the moisture also covers the isolation metal itself, thereby rendering it useless. It is suggested that these measurements be performed at temperatures above freezing to minimize error.

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## PARAMETER MEASUREMENT INFORMATION

### full-power response

Full-power response, the frequency above which the amplifier slew rate limits the output voltage swing, is often specified two ways: full-linear response and full-peak response. The full-linear response is generally measured by monitoring the distortion level of the output while increasing the frequency of a sinusoidal input signal until the maximum frequency is found above which the output contains significant distortion. The full-peak response is defined as the maximum output frequency, without regard to distortion, above which full peak-to-peak output swing cannot be maintained.

Because there is no industry-wide accepted value for significant distortion, the full-peak response is specified in this data sheet and is measured using the circuit of Figure 98. The initial setup involves the use of a sinusoidal input to determine the maximum peak-to-peak output of the device (the amplitude of the sinusoidal wave is increased until clipping occurs). The sinusoidal wave is then replaced with a square wave of the same amplitude. The frequency is then increased until the maximum peak-to-peak output can no longer be maintained (Figure 102). A square wave is used to allow a more accurate determination of the point at which the maximum peak-to-peak output is reached.

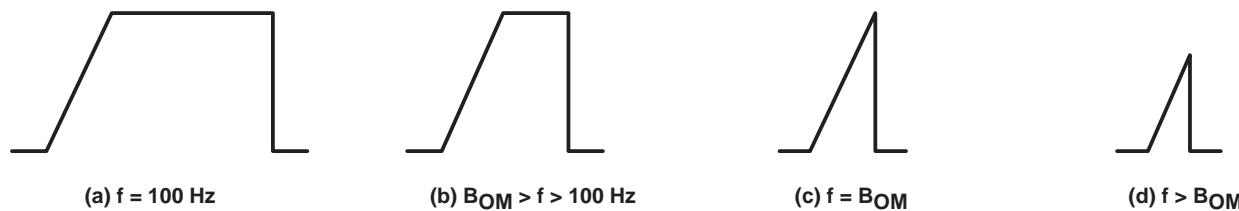


Figure 102. Full-Power-Response Output Signal

### test time

Inadequate test time is a frequent problem, especially when testing CMOS devices in a high-volume, short-test-time environment. Internal capacitances are inherently higher in CMOS than in bipolar and BiFET devices, and require longer test times than their bipolar and BiFET counterparts. The problem becomes more pronounced with reduced supply levels and lower temperatures.

## APPLICATION INFORMATION

### single-supply operation

While the TLC271 performs well using dual power supplies (also called balanced or split supplies), the design is optimized for single-supply operation. This includes an input common mode voltage range that encompasses ground as well as an output voltage range that pulls down to ground. The supply voltage range extends down to 3 V (C-suffix types), thus allowing operation with supply levels commonly available for TTL and HCMOS; however, for maximum dynamic range, 16-V single-supply operation is recommended.

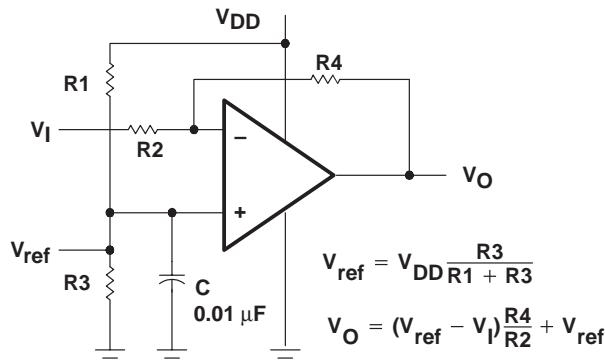


Figure 103. Inverting Amplifier With Voltage Reference

## APPLICATION INFORMATION

### single-supply operation (continued)

Many single-supply applications require that a voltage be applied to one input to establish a reference level that is above ground. A resistive voltage divider is usually sufficient to establish this reference level (see Figure 103). The low input bias current consumption of the TLC271 permits the use of very large resistive values to implement the voltage divider, thus minimizing power consumption.

The TLC271 works well in conjunction with digital logic; however, when powering both linear devices and digital logic from the same power supply, the following precautions are recommended:

1. Power the linear devices from separate bypassed supply lines (see Figure 104); otherwise, the linear device supply rails can fluctuate due to voltage drops caused by high switching currents in the digital logic.
2. Use proper bypass techniques to reduce the probability of noise-induced errors. Single capacitive decoupling is often adequate; however, RC decoupling may be necessary in high-frequency applications.

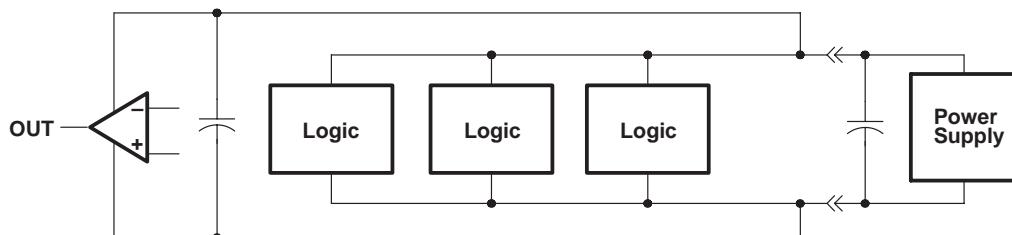
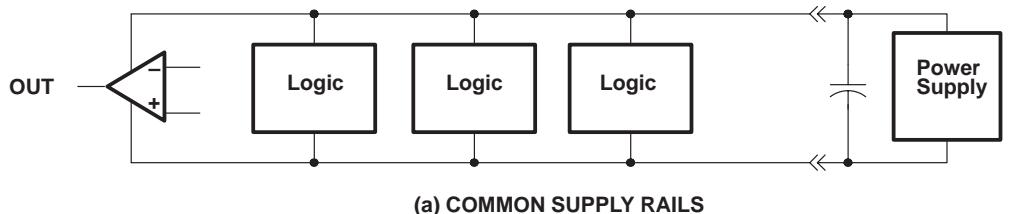


Figure 104. Common Versus Separate Supply Rails

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## APPLICATION INFORMATION

### input offset voltage nulling

The TLC271 offers external input offset null control. Nulling of the input offset voltage may be achieved by adjusting a 25-kΩ potentiometer connected between the offset null terminals with the wiper connected as shown in Figure 105. The amount of nulling range varies with the bias selection. In the high-bias mode, the nulling range allows the maximum offset voltage specified to be trimmed to zero. In low-bias and medium-bias modes, total nulling may not be possible.

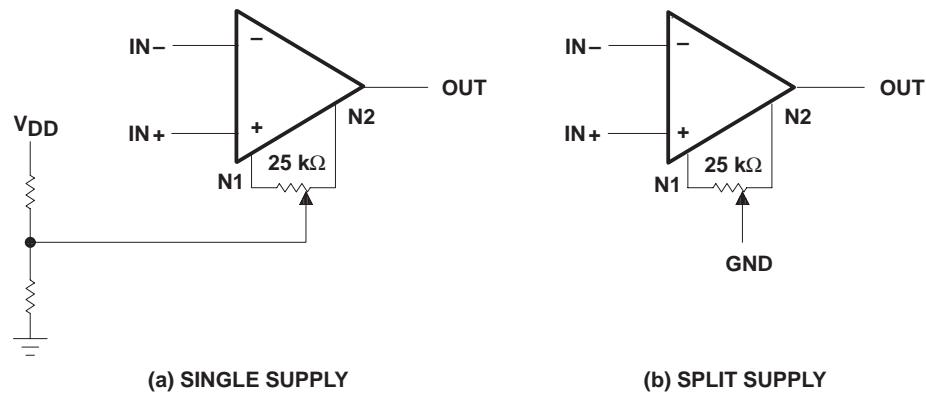


Figure 105. Input Offset Voltage Null Circuit

### bias selection

Bias selection is achieved by connecting the bias select pin to one of the three voltage levels (see Figure 106). For medium-bias applications, R is recommended that the bias select pin be connected to the mid-point between the supply rails. This is a simple procedure in split-supply applications, since this point is ground. In single-supply applications, the medium-bias mode necessitates using a voltage divider as indicated. The use of large-value resistors in the voltage divider reduces the current drain of the divider from the supply line. However, large-value resistors used in conjunction with a large-value capacitor requires significant time to charge up to the supply midpoint after the supply is switched on. A voltage other than the midpoint may be used if it is within the voltages specified in the table of Figure 106.

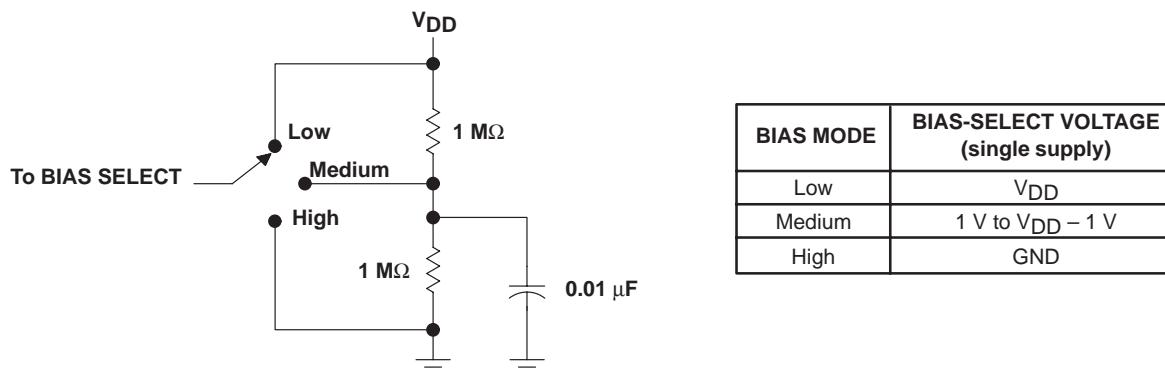


Figure 106. Bias Selection for Single-Supply Applications

## APPLICATION INFORMATION

### input characteristics

The TLC271 is specified with a minimum and a maximum input voltage that, if exceeded at either input, could cause the device to malfunction. Exceeding this specified range is a common problem, especially in single-supply operation. Note that the lower range limit includes the negative rail, while the upper range limit is specified at  $V_{DD} - 1$  V at  $T_A = 25^\circ\text{C}$  and at  $V_{DD} - 1.5$  V at all other temperatures.

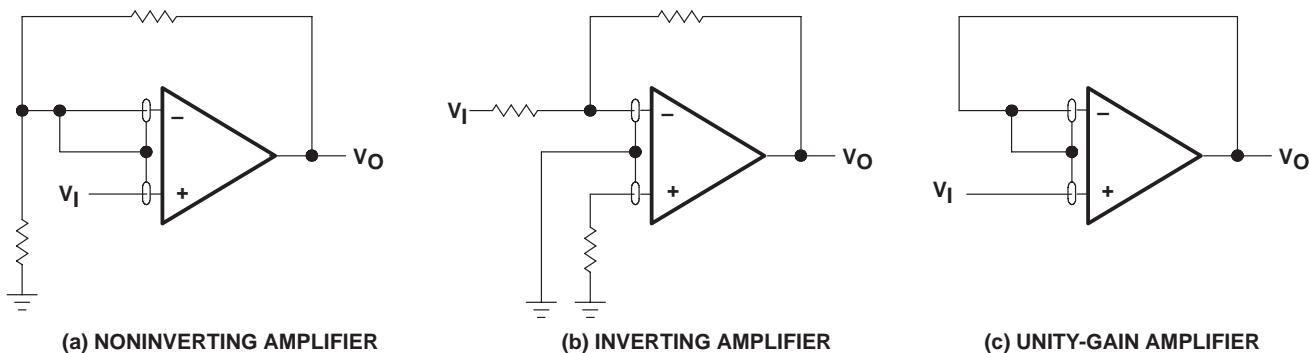
The use of the polysilicon-gate process and the careful input circuit design gives the TLC271 very good input offset voltage drift characteristics relative to conventional metal-gate processes. Offset voltage drift in CMOS devices is highly influenced by threshold voltage shifts caused by polarization of the phosphorus dopant implanted in the oxide. Placing the phosphorus dopant in a conductor (such as a polysilicon gate) alleviates the polarization problem, thus reducing threshold voltage shifts by more than an order of magnitude. The offset voltage drift with time has been calculated to be typically 0.1  $\mu\text{V}/\text{month}$ , including the first month of operation.

Because of the extremely high input impedance and resulting low bias current requirements, the TLC271 is well suited for low-level signal processing; however, leakage currents on printed circuit boards and sockets can easily exceed bias current requirements and cause a degradation in device performance. It is good practice to include guard rings around inputs (similar to those of Figure 101 in the Parameter Measurement Information section). These guards should be driven from a low-impedance source at the same voltage level as the common-mode input (see Figure 107).

The inputs of any unused amplifiers should be tied to ground to avoid possible oscillation.

### noise performance

The noise specifications in operational amplifier circuits are greatly dependent on the current in the first-stage differential amplifier. The low input bias current requirements of the TLC271 results in a very low noise current, which is insignificant in most applications. This feature makes the devices especially favorable over bipolar devices when using values of circuit impedance greater than 50  $\text{k}\Omega$ , since bipolar devices exhibit greater noise currents.



**Figure 107. Guard-Ring Schemes**

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## APPLICATION INFORMATION

### feedback

Operational amplifier circuits almost always employ feedback, and since feedback is the first prerequisite for oscillation, a little caution is appropriate. Most oscillation problems result from driving capacitive loads and ignoring stray input capacitance. A small-value capacitor connected in parallel with the feedback resistor is an effective remedy (see Figure 108). The value of this capacitor is optimized empirically.

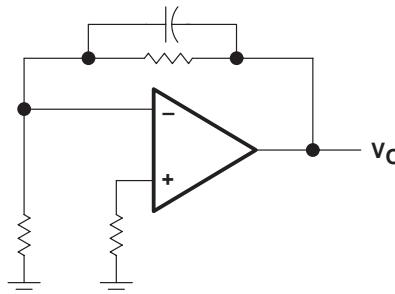


Figure 108. Compensation for Input Capacitance

### electrostatic discharge protection

The TLC271 incorporates an internal electrostatic-discharge (ESD) protection circuit that prevents functional failures at voltages up to 2000 V as tested under MIL-STD-883C, Method 3015.2. Care should be exercised, however, when handling these devices as exposure to ESD may result in the degradation of the device parametric performance. The protection circuit also causes the input bias currents to be temperature dependent and have the characteristics of a reverse-biased diode.

### latch-up

Because CMOS devices are susceptible to latch-up due to their inherent parasitic thyristors, the TLC271 inputs and output were designed to withstand -100-mA surge currents without sustaining latchup; however, techniques should be used to reduce the chance of latch-up whenever possible. Internal protection diodes should not by design be forward biased. Applied input and output voltage should not exceed the supply voltage by more than 300 mV. Care should be exercised when using capacitive coupling on pulse generators. Supply transients should be shunted by the use of decoupling capacitors (0.1  $\mu$ F typical) located across the supply rails as close to the device as possible.

The current path established if latch-up occurs is usually between the positive supply rail and ground and can be triggered by surges on the supply lines and/or voltages on either the output or inputs that exceed the supply voltage. Once latch-up occurs, the current flow is limited only by the impedance of the power supply and the forward resistance of the parasitic thyristor and usually results in the destruction of the device. The chance of latch-up occurring increases with increasing temperature and supply voltages.

### output characteristics

The output stage of the TLC271 is designed to sink and source relatively high amounts of current (see Typical Characteristics). If the output is subjected to a short-circuit condition, this high current capability can cause device damage under certain conditions. Output current capability increases with supply voltage.

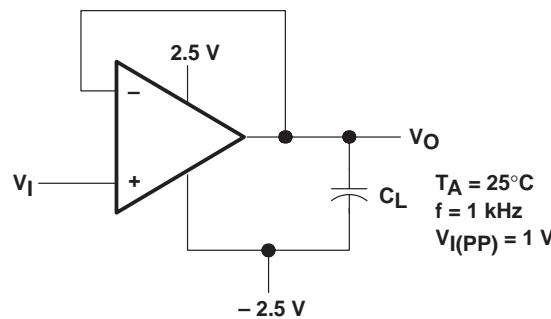
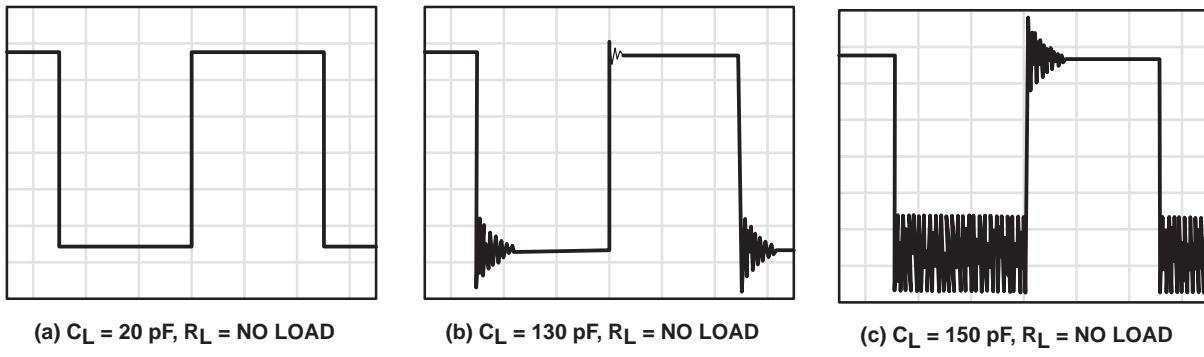


Figure 109. Test Circuit for Output Characteristics

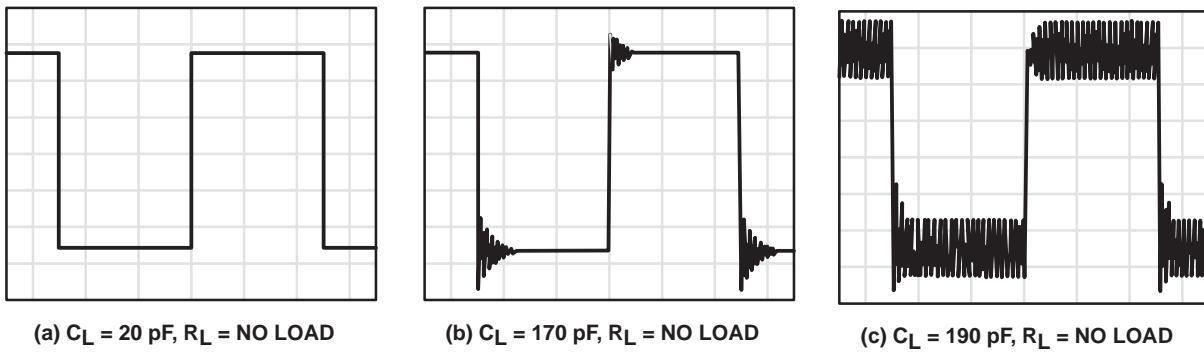
## APPLICATION INFORMATION

### output characteristics (continued)

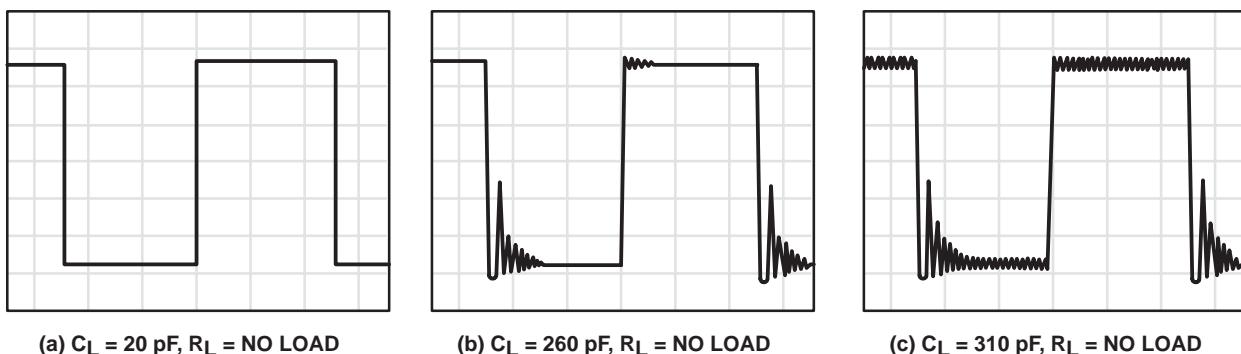
All operating characteristics of the TLC271 were measured using a 20-pF load. The devices drive higher capacitive loads; however, as output load capacitance increases, the resulting response pole occurs at lower frequencies, thereby causing ringing, peaking, or even oscillation (see Figures 110, 111, and 112). In many cases, adding some compensation in the form of a series resistor in the feedback loop alleviates the problem.



**Figure 110. Effect of Capacitive Loads in High-Bias Mode**



**Figure 111. Effect of Capacitive Loads in Medium-Bias Mode**



**Figure 112. Effect of Capacitive Loads in Low-Bias Mode**

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## APPLICATION INFORMATION

### output characteristics (continued)

Although the TLC271 possesses excellent high-level output voltage and current capability, methods are available for boosting this capability, if needed. The simplest method involves the use of a pullup resistor ( $R_P$ ) connected from the output to the positive supply rail (see Figure 113). There are two disadvantages to the use of this circuit. First, the NMOS pulldown transistor, N4 (see equivalent schematic) must sink a comparatively large amount of current. In this circuit, N4 behaves like a linear resistor with an on-resistance between approximately  $60\ \Omega$  and  $180\ \Omega$ , depending on how hard the operational amplifier input is driven. With very low values of  $R_P$ , a voltage offset from 0 V at the output occurs. Secondly, pullup resistor  $R_P$  acts as a drain load to N4 and the gain of the operational amplifier is reduced at output voltage levels where N5 is not supplying the output current.

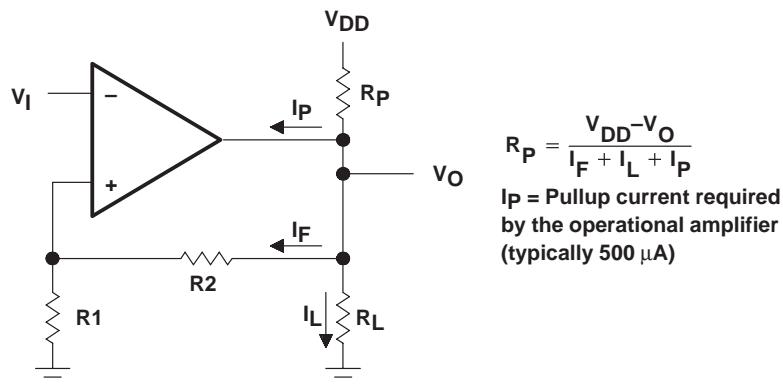
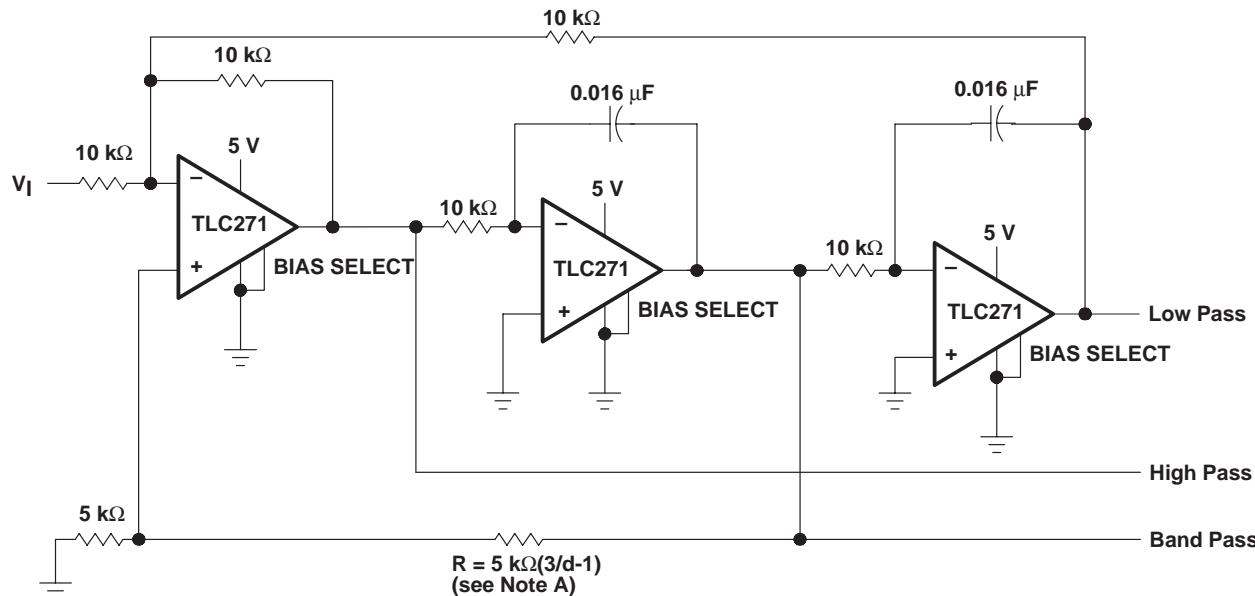


Figure 113. Resistive Pullup to Increase  $V_{OH}$

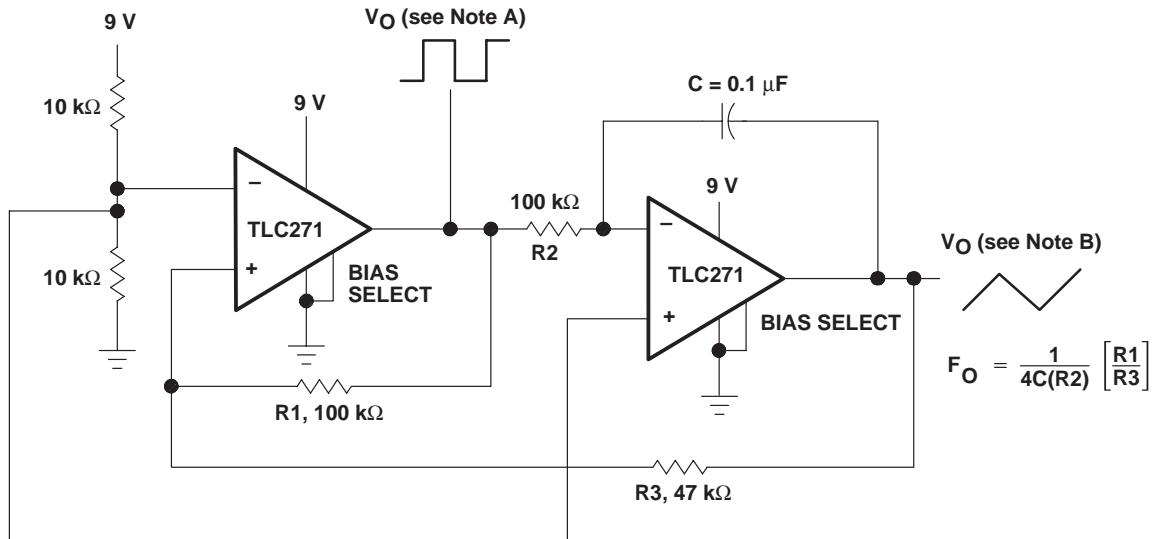


NOTE B:  $d$  = damping factor,  $I/O$

Figure 114. State-Variable Filter

## APPLICATION INFORMATION

### output characteristics (continued)



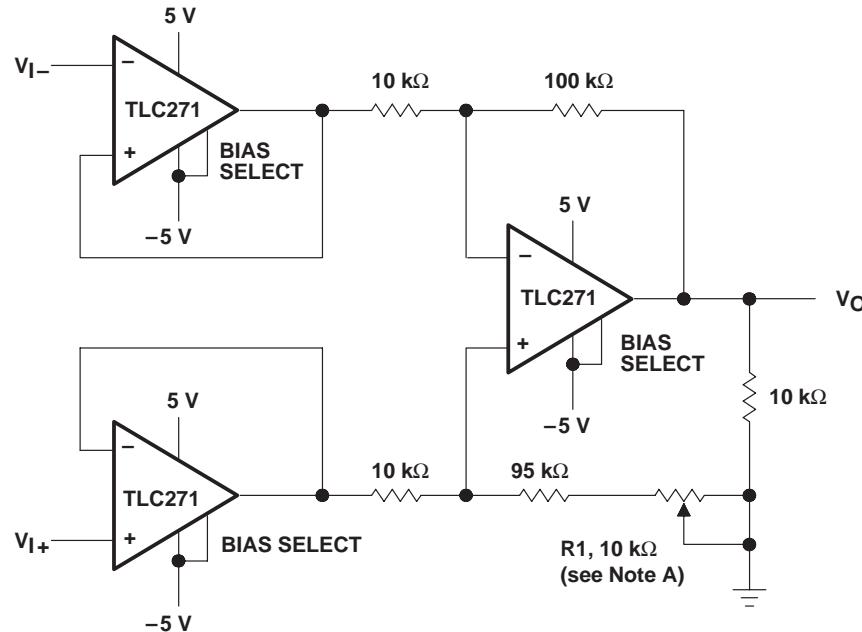
NOTES: A.  $V_{O(PP)} = 8$  V  
 B.  $V_{O(PP)} = 4$  V

**Figure 115. Single-Supply Function Generator**

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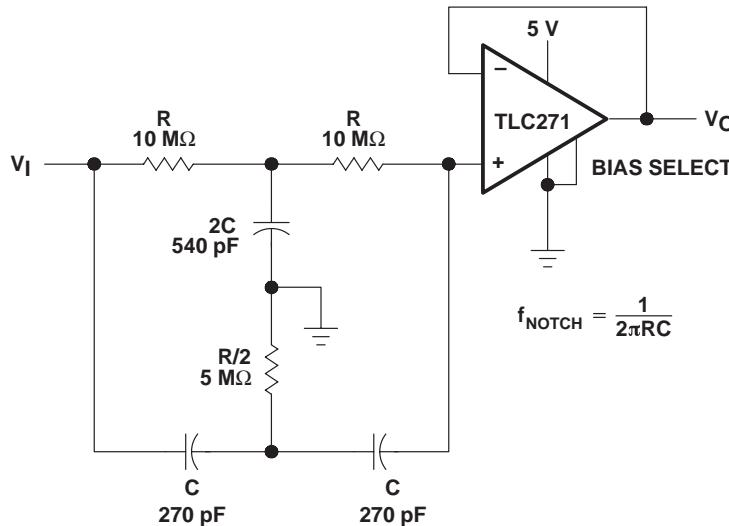
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**APPLICATION INFORMATION (HIGH-BIAS MODE)**



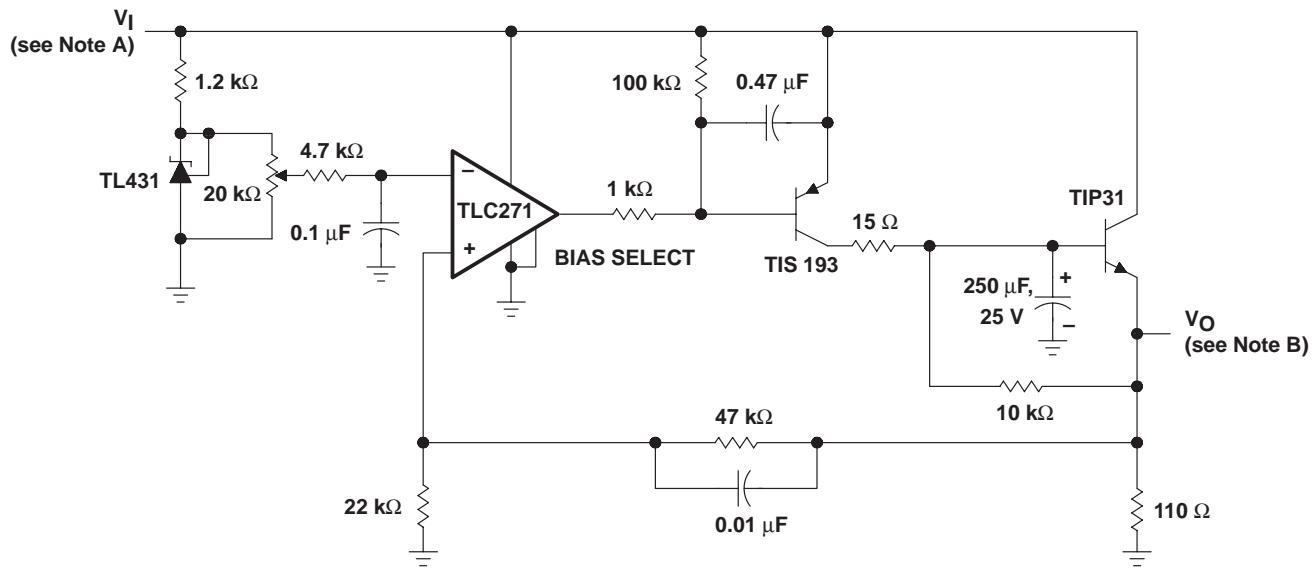
NOTE A: CMRR adjustment must be noninductive.

**Figure 116. Low-Power Instrumentation Amplifier**



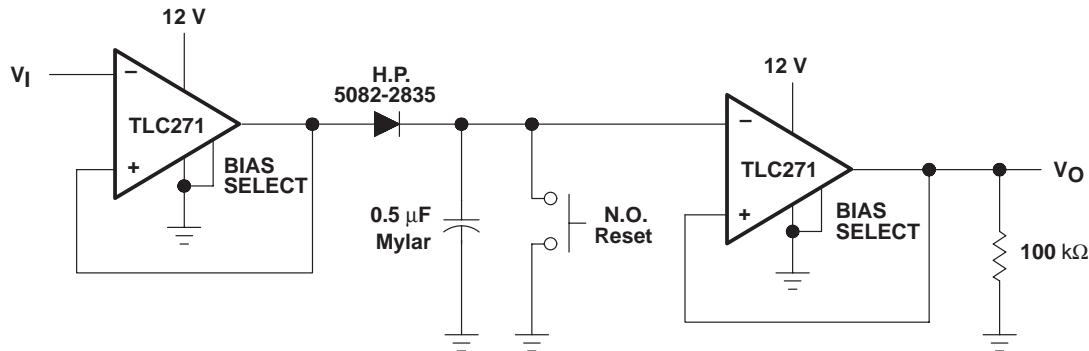
**Figure 117. Single-Supply Twin-T Notch Filter**

### APPLICATION INFORMATION (HIGH-BIAS MODE)



NOTES:  
A.  $V_I = 3.5$  to  $15\text{ V}$   
B.  $V_O = 2.0\text{ V}$ ,  $0$  to  $1\text{ A}$

**Figure 118. Logic-Array Power Supply**

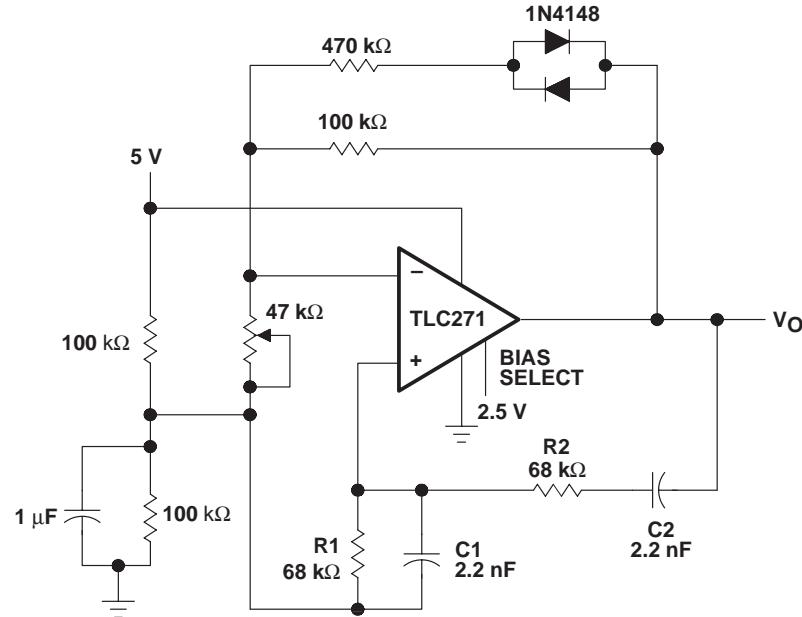


**Figure 119. Positive-Peak Detector**

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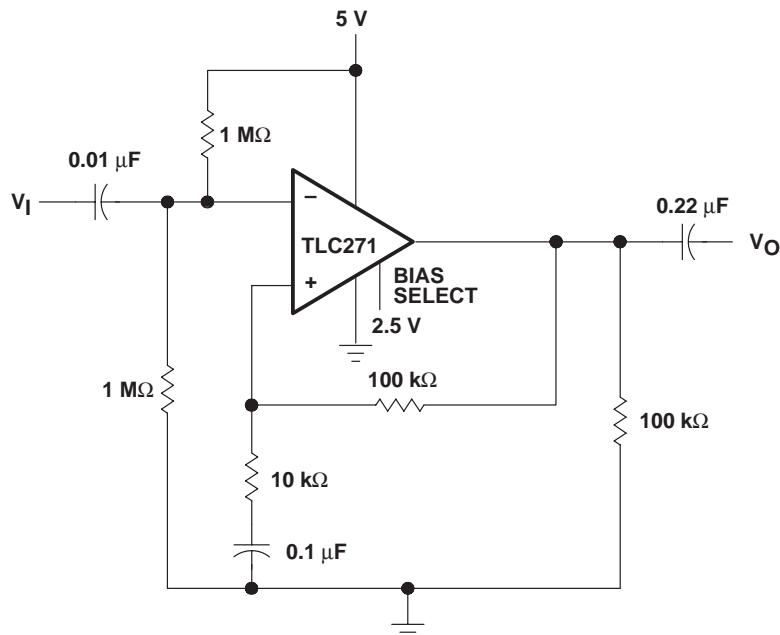
**APPLICATION INFORMATION (MEDIUM-BIAS MODE)**



NOTES: A.  $V_{O(PP)} = 2 \text{ V}$

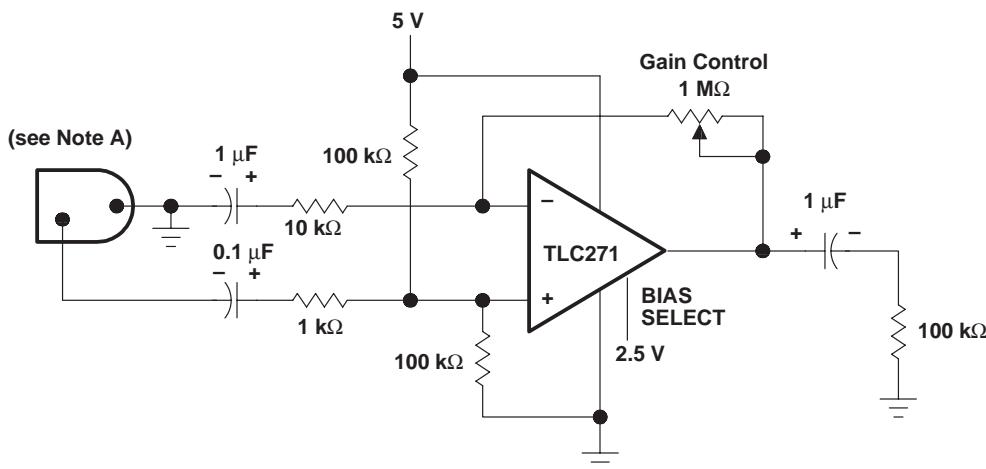
$$\text{B. } f_0 = \frac{1}{2\pi\sqrt{R1R2C1C2}}$$

**Figure 120. Wein Oscillator**



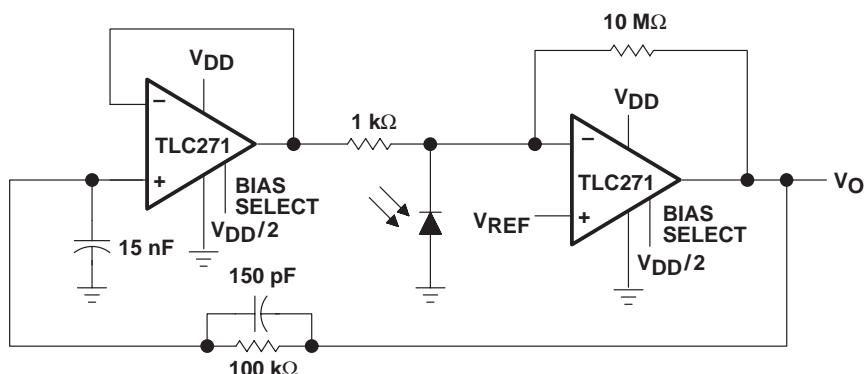
**Figure 121. Single-Supply AC Amplifier**

## APPLICATION INFORMATION (MEDIUM-BIAS MODE)



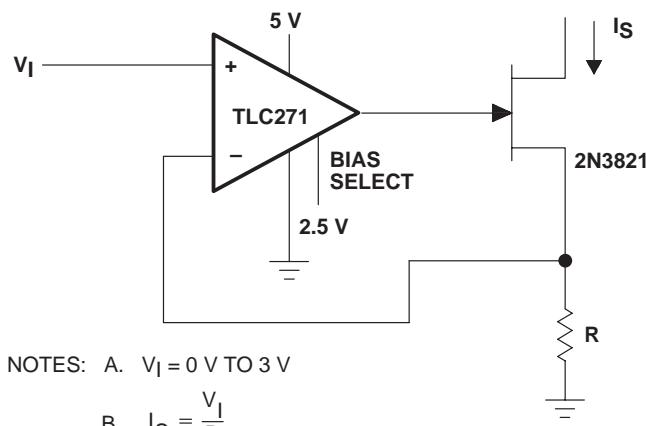
NOTE A: Low to medium impedance dynamic mike

**Figure 122. Microphone Preamplifier**



NOTES: A. NOTES:  $V_{DD} = 4 \text{ V to } 15 \text{ V}$   
B.  $V_{ref} = 0 \text{ V to } V_{DD} - 2 \text{ V}$

**Figure 123. Photo-Diode Amplifier With Ambient Light Rejection**



NOTES: A.  $V_I = 0 \text{ V TO } 3 \text{ V}$

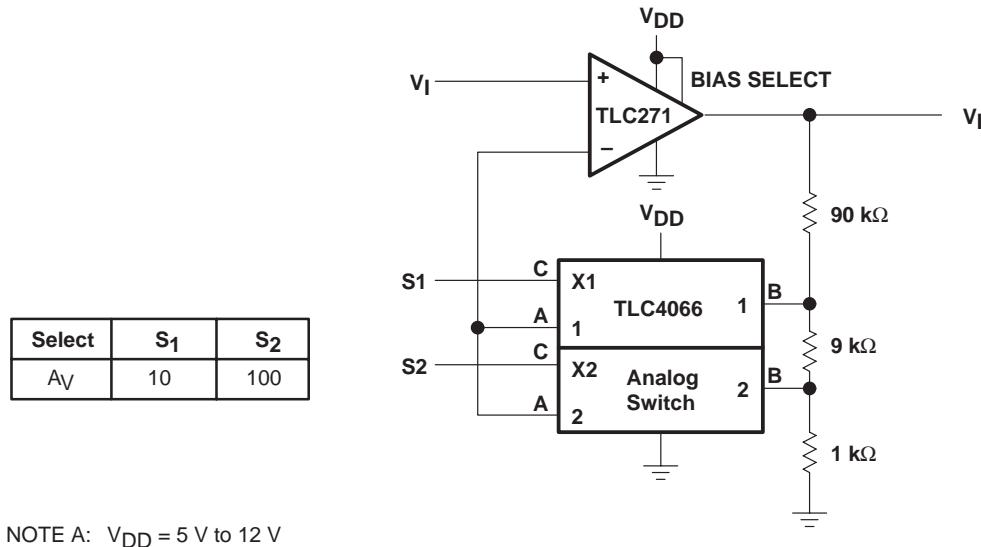
$$\text{B. } I_S = \frac{V_I}{R}$$

**Figure 124. Precision Low-Current Sink**

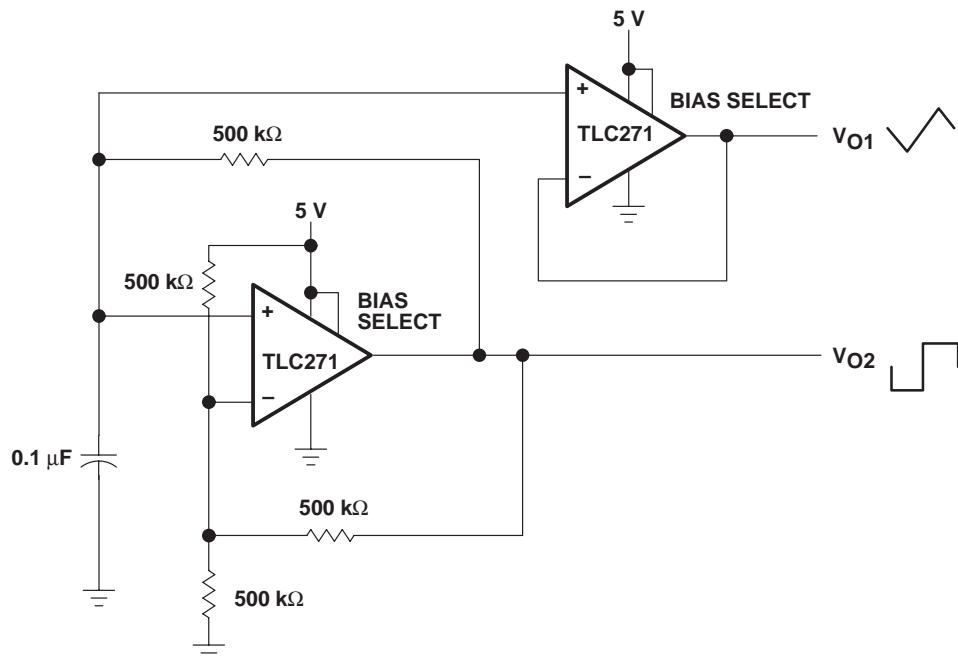
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**APPLICATION INFORMATION (LOW-BIAS MODE)**

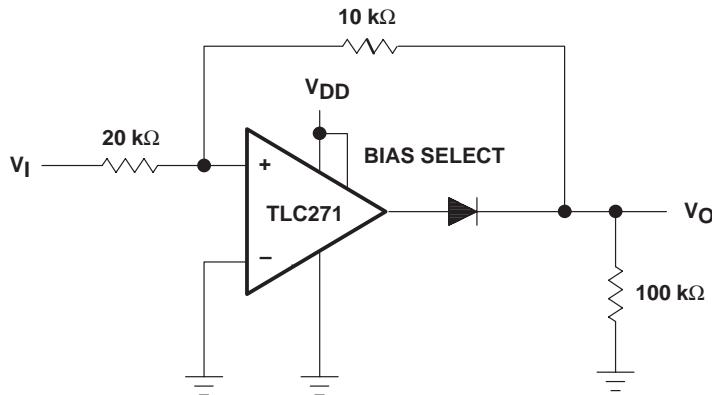


**Figure 125. Amplifier With Digital Gain Selection**



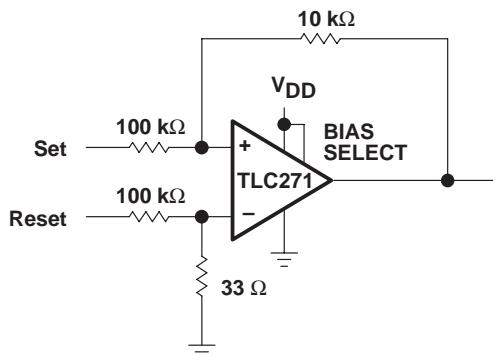
**Figure 126. Multivibrator**

### APPLICATION INFORMATION (LOW-BIAS MODE)



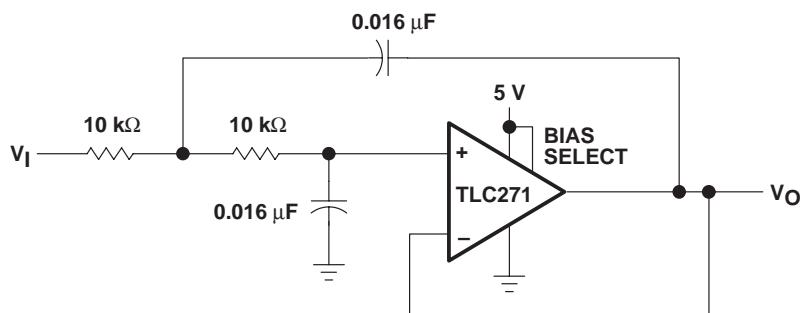
NOTE A:  $V_{DD} = 5\text{ V}$  to  $16\text{ V}$

**Figure 127. Full-Wave Rectifier**



NOTE A:  $V_{DD} = 5\text{ V}$  to  $16\text{ V}$

**Figure 128. Set/Reset Flip-Flop**



NOTE A: Normalized to  $F_C = 1\text{ kHz}$  and  $R_L = 10\text{ k}\Omega$

**Figure 129. Two-Pole Low-Pass Butterworth Filter**

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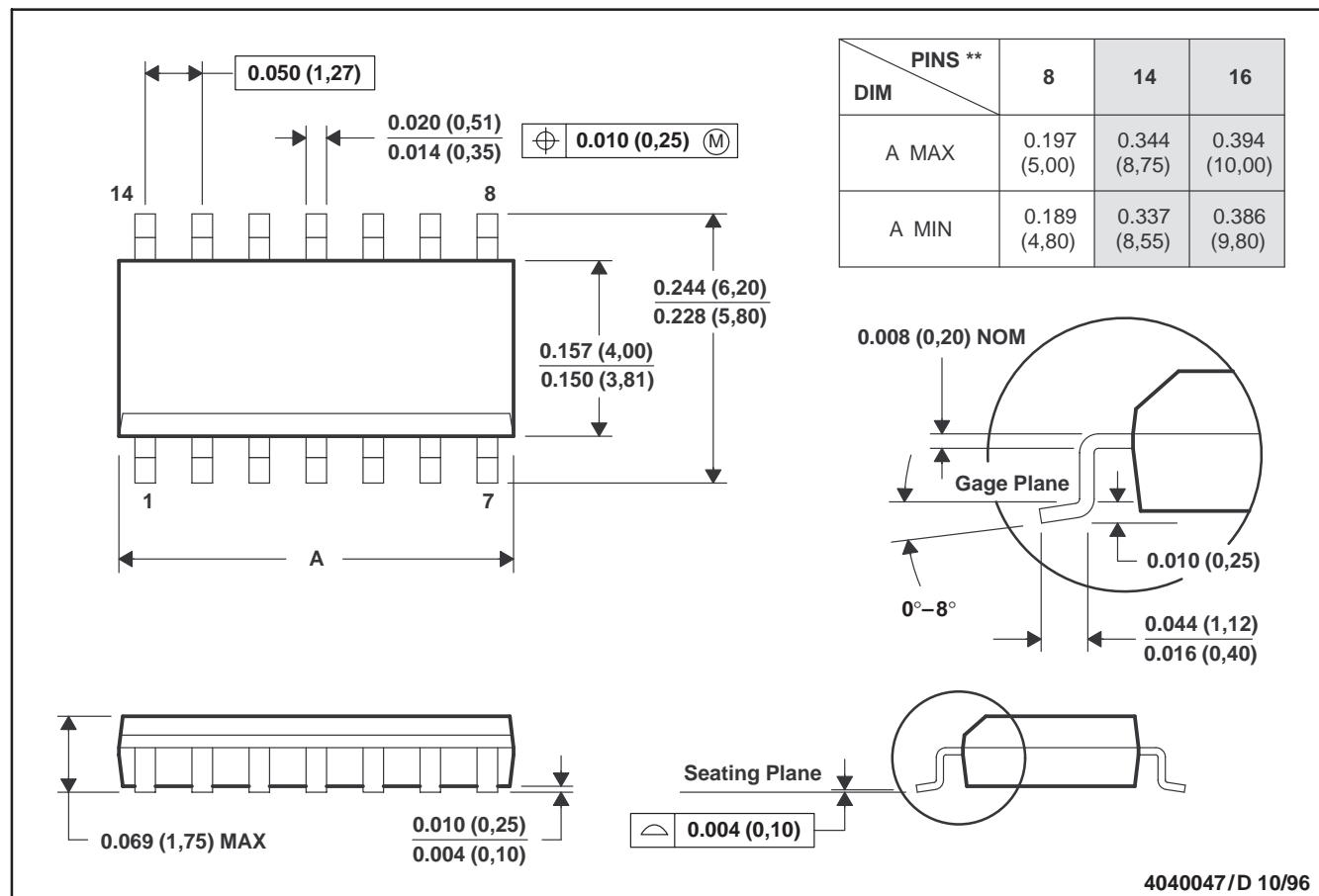
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**MECHANICAL INFORMATION**

**D (R-PDSO-G\*\*)**

14 PIN SHOWN

**PLASTIC SMALL-OUTLINE PACKAGE**



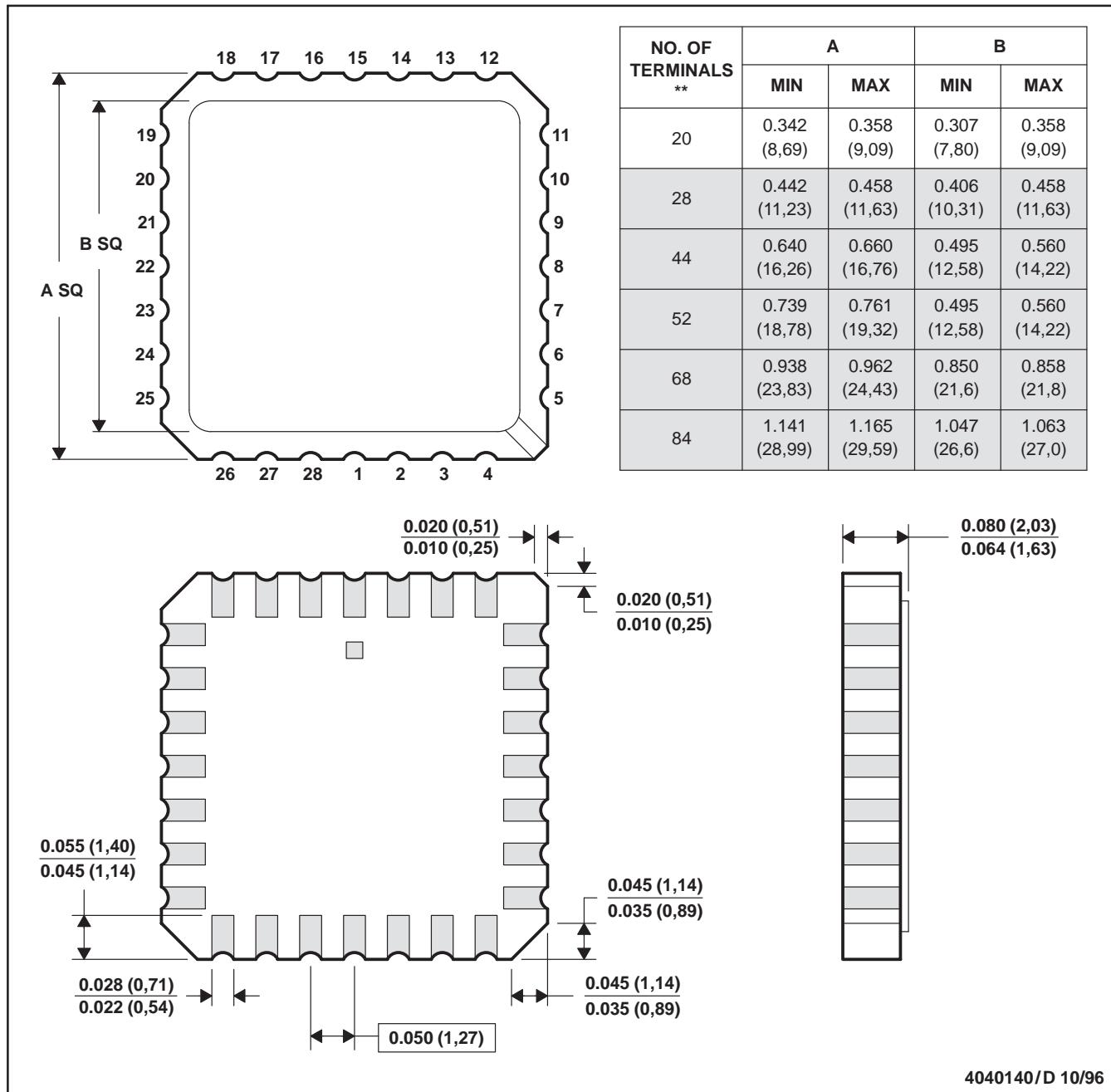
- NOTES: A. All linear dimensions are in inches (millimeters).  
 B. This drawing is subject to change without notice.  
 C. Body dimensions do not include mold flash or protrusion, not to exceed 0.006 (0.15).  
 D. Falls within JEDEC MS-012

## MECHANICAL INFORMATION

**FK (S-CQCC-N\*\*)**

28 TERMINAL SHOWN

**LEADLESS CERAMIC CHIP CARRIER**



- NOTES: A. All linear dimensions are in inches (millimeters).  
 B. This drawing is subject to change without notice.  
 C. This package can be hermetically sealed with a metal lid.  
 D. The terminals are gold plated.  
 E. Falls within JEDEC MS-004

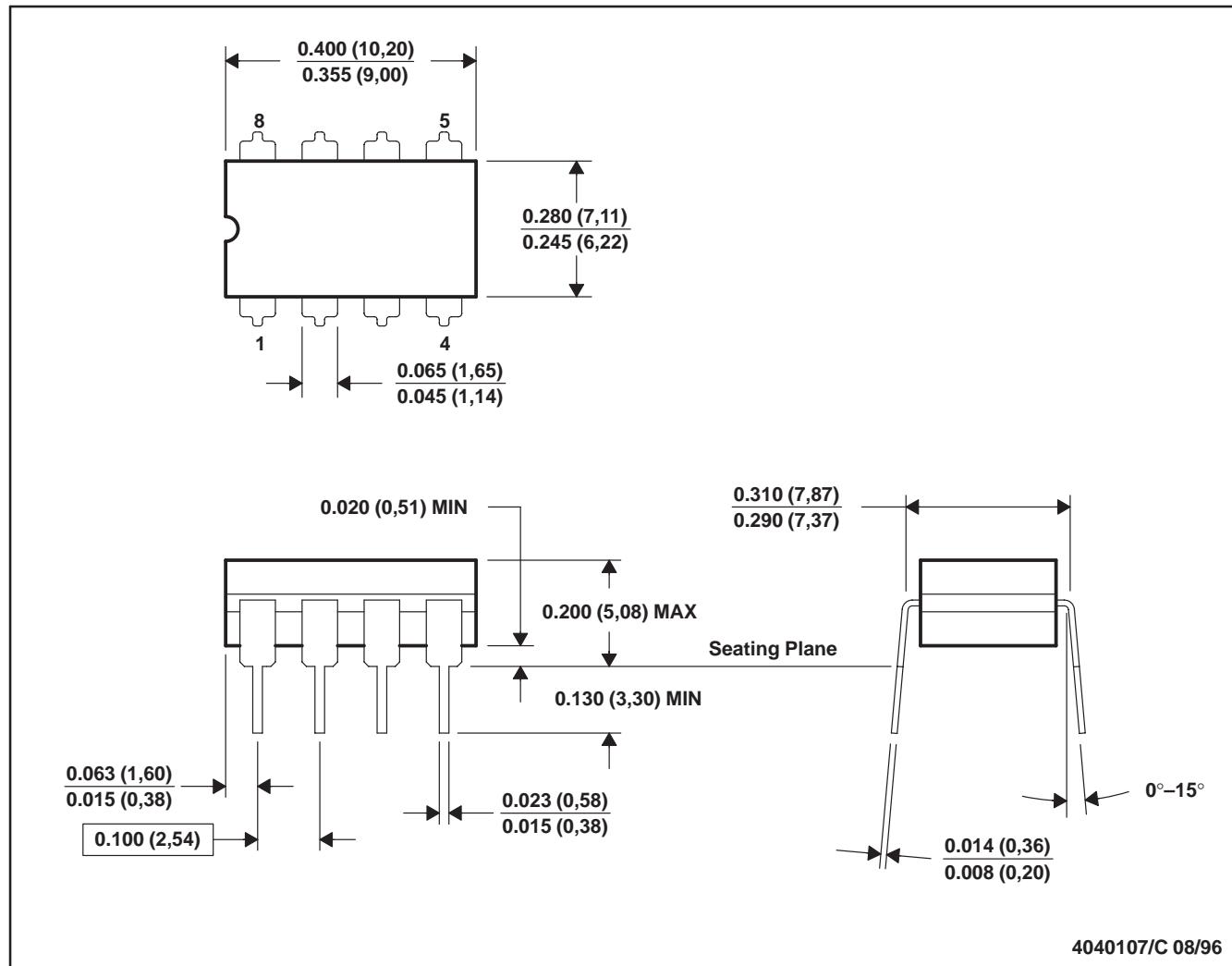
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**MECHANICAL INFORMATION**

**JG (R-GDIP-T8)**

**CERAMIC DUAL-IN-LINE PACKAGE**

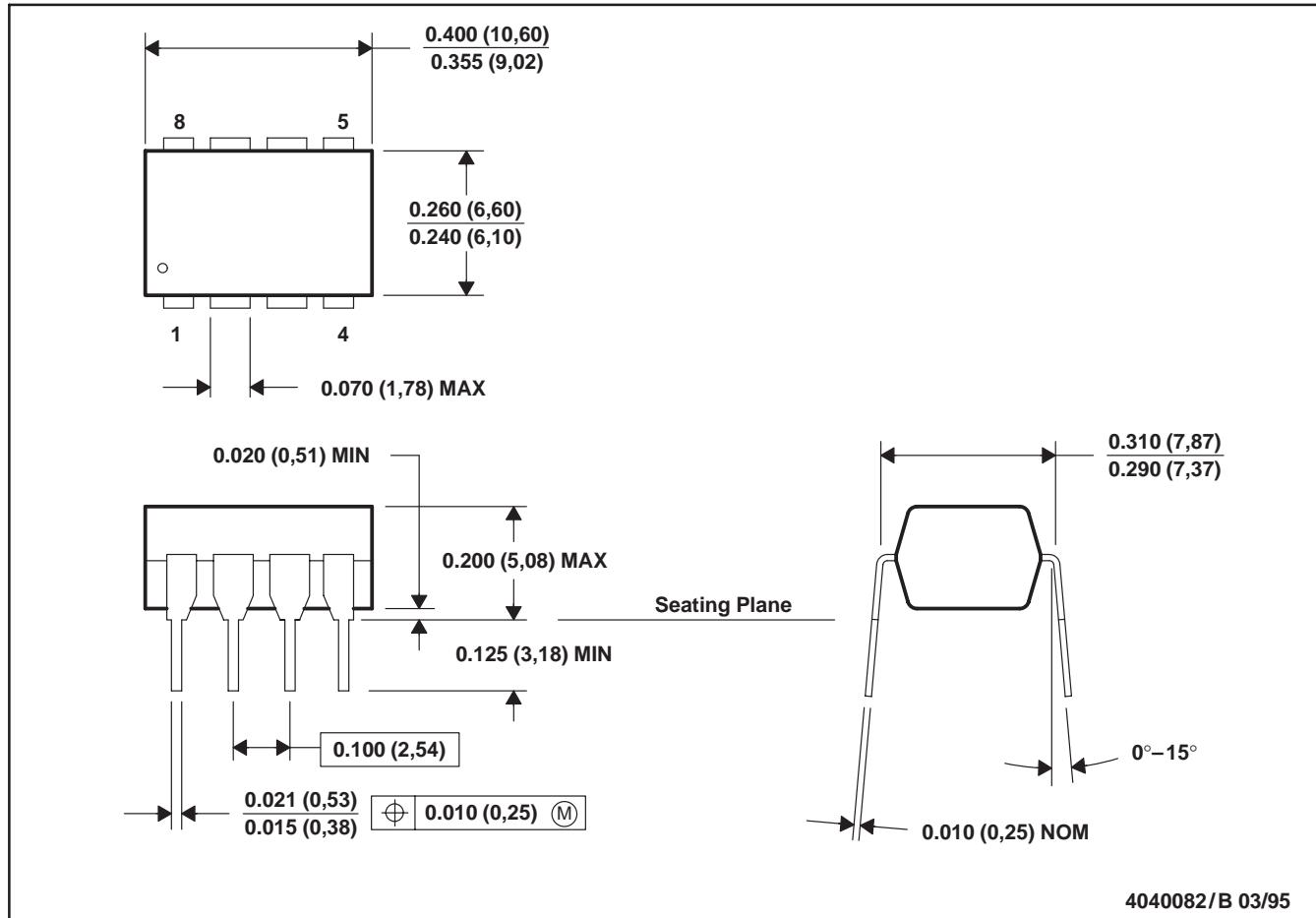


- NOTES:
- All linear dimensions are in inches (millimeters).
  - This drawing is subject to change without notice.
  - This package can be hermetically sealed with a ceramic lid using glass frit.
  - Index point is provided on cap for terminal identification only on press ceramic glass frit seal only.
  - Falls within MIL-STD-1835 GDIP1-T8

## MECHANICAL INFORMATION

P (R-PDIP-T8)

PLASTIC DUAL-IN-LINE PACKAGE



- NOTES:
- A. All linear dimensions are in inches (millimeters).
  - B. This drawing is subject to change without notice.
  - C. Falls within JEDEC MS-001

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