_General Description

The MAX481, MAX483, MAX485, MAX487–MAX491, and MAX1487 are low-power transceivers for RS-485 and RS-422 communication. Each part contains one driver and one receiver. The MAX483, MAX487, MAX488, and MAX489 feature reduced slew-rate drivers that minimize EMI and reduce reflections caused by improperly terminated cables, thus allowing error-free data transmission up to 250kbps. The driver slew rates of the MAX481, MAX485, MAX490, MAX491, and MAX1487 are not limited, allowing them to transmit up to 2.5Mbps.

These transceivers draw between 120μ A and 500μ A of supply current when unloaded or fully loaded with disabled drivers. Additionally, the MAX481, MAX483, and MAX487 have a low-current shutdown mode in which they consume only 0.1 μ A. All parts operate from a single 5V supply.

Drivers are short-circuit current limited and are protected against excessive power dissipation by thermal shutdown circuitry that places the driver outputs into a high-impedance state. The receiver input has a fail-safe feature that guarantees a logic-high output if the input is open circuit.

The MAX487 and MAX1487 feature quarter-unit-load receiver input impedance, allowing up to 128 MAX487/ MAX1487 transceivers on the bus. Full-duplex communications are obtained using the MAX488–MAX491, while the MAX481, MAX483, MAX485, MAX487, and MAX1487 are designed for half-duplex applications.

Applications

Low-Power RS-485 Transceivers

Low-Power RS-422 Transceivers

Level Translators

Transceivers for EMI-Sensitive Applications

Industrial-Control Local Area Networks

_Features

- In µMAX Package: Smallest 8-Pin SO
- Slew-Rate Limited for Error-Free Data Transmission (MAX483/487/488/489)
- 0.1µA Low-Current Shutdown Mode (MAX481/483/487)
- Low Quiescent Current: 120µA (MAX483/487/488/489) 230µA (MAX1487) 300µA (MAX481/485/490/491)
- -7V to +12V Common-Mode Input Voltage Range
- Three-State Outputs
- 30ns Propagation Delays, 5ns Skew (MAX481/485/490/491/1487)
- Full-Duplex and Half-Duplex Versions Available
- Operate from a Single 5V Supply
- Allows up to 128 Transceivers on the Bus (MAX487/MAX1487)
- Current-Limiting and Thermal Shutdown for Driver Overload Protection

Ordering Information

PART	TEMP. RANGE	PIN-PACKAGE
MAX481CPA	0°C to +70°C	8 Plastic DIP
MAX481CSA	0°C to +70°C	8 SO
MAX481CUA	0°C to +70°C	8 μΜΑΧ
MAX481C/D	0°C to +70°C	Dice*

Ordering Information continued at end of data sheet. * Contact factory for dice specifications.

Selection Table

PART NUMBER	HALF/FULL DUPLEX	DATA RATE (Mbps)	SLEW-RATE LIMITED	LOW-POWER SHUTDOWN	RECEIVER/ DRIVER ENABLE	QUIESCENT CURRENT (µA)	NUMBER OF TRANSMITTERS ON BUS	PIN COUNT
MAX481	Half	2.5	No	Yes	Yes	300	32	8
MAX483	Half	0.25	Yes	Yes	Yes	120	32	8
MAX485	Half	2.5	No	No	Yes	300	32	8
MAX487	Half	0.25	Yes	Yes	Yes	120	128	8
MAX488	Full	0.25	Yes	No	No	120	32	8
MAX489	Full	0.25	Yes	No	Yes	120	32	14
MAX490	Full	2.5	No	No	No	300	32	8
MAX491	Full	2.5	No	No	Yes	300	32	14
MAX1487	Half	2.5	No	No	Yes	230	128	8

Maxim Integrated Products 1

For free samples & the latest literature: http://www.maxim-ic.com, or phone 1-800-998-8800

ABSOLUTE MAXIMUM RATINGS

Supply(Voltage(Vol)) = 10V
Supply Voltage (V _{CC})12V
Control Input Voltage (RE, DE)0.5V to (V _{CC} + 0.5V)
Driver Input Voltage (DI)0.5V to (V _{CC} + 0.5V)
Driver Output Voltage (A, B)8V to +12.5V
Receiver Input Voltage (A, B)8V to +12.5V
Receiver Output Voltage (RO)0.5V to (V _{CC} +0.5V)
Continuous Power Dissipation ($T_A = +70^{\circ}C$)
8-Pin Plastic DIP (derate 9.09mW/°C above +70°C) 727mW

8-Pin Plastic DIP (derate 9.09mW/°C above +70°C)727mW 14-Pin Plastic DIP (derate 10.00mW/°C above +70°C) ...800mW 8-Pin SO (derate 5.88mW/°C above +70°C)......471mW

14-Pin SO (derate 8.33mW/°C above +70°C)	6	67mW
8-Pin µMAX (derate 4.1mW/°C above +70°C)	8	30mW
8-Pin CERDIP (derate 8.00mW/°C above +70°C)		
14-Pin CERDIP (derate 9.09mW/°C above +70°C)	7	27mW
Operating Temperature Ranges		
		7000

MAX4C/MAX1487C_ A	0°C to +70°C
MAX4E/MAX1487E_ A	40°C to +85°C
MAX4MJ_/MAX1487MJA	55°C to +125°C
Storage Temperature Range	65°C to +160°C
Lead Temperature (soldering, 10sec).	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC ELECTRICAL CHARACTERISTICS

 $(V_{CC} = 5V \pm 5\%, T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Differential Driver Output (no load)	Vod1					5	V
Differential Driver Output		R = 50Ω (RS-422)		2			V
(with load)	V _{OD2}	R = 27Ω (RS-485), Figure 4		1.5		5	
Change in Magnitude of Driver Differential Output Voltage for Complementary Output States	ΔV _{OD}	R = 27Ω or 50Ω , Figure 4				0.2	V
Driver Common-Mode Output Voltage	Voc	R = 27Ω or 50Ω , Figure 4				3	V
Change in Magnitude of Driver Common-Mode Output Voltage for Complementary Output States	ΔV _{OD}	R = 27Ω or 50Ω , Figure 4				0.2	V
Input High Voltage	VIH	DE, DI, RE		2.0			V
Input Low Voltage	VIL	DE, DI, RE				0.8	V
Input Current	lin1	DE, DI, RE				±2	μA
Input Current (A, B)		DE = 0V; V _{CC} = 0V or 5.25V,	V _{IN} = 12V			1.0	mA
	I _{IN2}	IIN2 All devices except MAX487/MAX1487				-0.8	
		MAX487/MAX1487,	$V_{IN} = 12V$			0.25	mA
		$DE = 0V, V_{CC} = 0V \text{ or } 5.25V$	$V_{IN} = -7V$			-0.2	
Receiver Differential Threshold Voltage	Vth	$-7V \le V_{CM} \le 12V$		-0.2		0.2	V
Receiver Input Hysteresis	ΔV_{TH}	$V_{CM} = 0V$			70		mV
Receiver Output High Voltage	Voh	$I_{O} = -4mA$, $V_{ID} = 200mV$		3.5			V
Receiver Output Low Voltage	Vol	$I_{O} = 4mA, V_{ID} = -200mV$				0.4	V
Three-State (high impedance) Output Current at Receiver	I _{OZR}	$0.4V \le V_O \le 2.4V$				±1	μA
Receiver Input Resistance	RIN	$-7V \le V_{CM} \le 12V$, all devices except MAX487/MAX1487		12			kΩ
Receiver input Resistance		-7V ≤ V _{CM} ≤ 12V, MAX487/MA	AX1487	48			kΩ

DC ELECTRICAL CHARACTERISTICS (continued)

(V_{CC} = 5V \pm 5%, T_A = T_{MIN} to T_{MAX}, unless otherwise noted.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS			MIN	TYP	MAX	UNITS
		MAX488/MAX489, DE, DI, RE = 0V or V _{CC}				120	250	
		MAX490/MAX491, DE, DI, RE = 0V or V _C	MAX490/MAX491, DE, DI, \overline{RE} = 0V or V _{CC}			300	500	
No. Logal Coursely Course at		MAX481/MAX485,	$DE = V_{CC}$			500	900	
No-Load Supply Current (Note 3)	ICC	$\overline{RE} = 0V \text{ or } V_{CC}$	DE = 0V			300	500	μA
		$\frac{MAX1487}{RE} = 0V \text{ or } V_{CC}$	DE = V _{CC}			300	500	
			DE = 0V			230	400	
		$\frac{MAX483}{MAX487},}{\overline{RE}} = 0V \text{ or } V_{CC}$	DE = 5V	MAX483		350	650	
			DE = 5V	MAX487		250	400	
			DE = OV			120	250	
Supply Current in Shutdown	ISHDN	MAX481/483/487, DE	$=$ 0V, $\overline{RE} = V$	'CC		0.1	10	μA
Driver Short-Circuit Current, $V_O = High$	IOSD1	-7V ≤ V _O ≤12V (Note 4)			35		250	mA
Driver Short-Circuit Current, Vo = Low	I _{OSD2}	-7V ≤ V _O ≤12V (Note 4)			35		250	mA
Receiver Short-Circuit Current	IOSR	$0V \le V_O \le V_{CC}$			7		95	mA

SWITCHING CHARACTERISTICS-MAX481/MAX485, MAX490/MAX491, MAX1487

$(V_{CC} = 5V \pm 5\%, T_A = T_{MIN} t$	o T _{MAX} , unless otherwise	noted.) (Notes 1, 2)
---	---------------------------------------	----------------------

PARAMETER	SYMBOL	CONDITIONS			TYP	MAX	UNITS
Driver Input to Output	t _{PLH}	Figures 6 and 8, $R_{DIFF} = 54\Omega$,		10	30	60	ns
	t _{PHL}	$C_{L1} = C_{L2} = 100 pF$	-	10	30	60	115
Driver Output Skew to Output	t SKEW	Figures 6 and 8, RD	$IFF = 54\Omega$, $C_{L1} = C_{L2} = 100 pF$		5	10	ns
		Figures 6 and 8,	MAX481, MAX485, MAX1487	3	15	40	
Driver Rise or Fall Time	t _R , t _F	$R_{DIFF} = 54\Omega$,	MAX490C/E, MAX491C/E	5	15	25	ns
		$C_{L1} = C_{L2} = 100 pF$	MAX490M, MAX491M	3	15	40]
Driver Enable to Output High	tzh	Figures 7 and 9, C	L = 100pF, S2 closed		40	70	ns
Driver Enable to Output Low	tzL	Figures 7 and 9, C	L = 100pF, S1 closed		40	70	ns
Driver Disable Time from Low	tLZ	Figures 7 and 9, C	L = 15pF, S1 closed		40	70	ns
Driver Disable Time from High	t _{HZ}	Figures 7 and 9, C	Figures 7 and 9, C _L = 15pF, S2 closed		40	70	ns
	tplh, tphl		MAX481, MAX485, MAX1487	20	90	200)
Receiver Input to Output			MAX490C/E, MAX491C/E	20	90	150	ns
			MAX490M, MAX491M	20	90	200	1
t _{PLH} - t _{PHL} Differential Receiver Skew	tskd	Figures 6 and 10, I C _{L1} = C _{L2} = 100pI			13		ns
Receiver Enable to Output Low	tzL	Figures 5 and 11, 0	C _{RL} = 15pF, S1 closed		20	50	ns
Receiver Enable to Output High	tzH	Figures 5 and 11, 0	C _{RL} = 15pF, S2 closed		20	50	ns
Receiver Disable Time from Low	tLZ	Figures 5 and 11, C _{RL} = 15pF, S1 closed			20	50	ns
Receiver Disable Time from High	t _{HZ}	Figures 5 and 11, C _{RL} = 15pF, S2 closed			20	50	ns
Maximum Data Rate	fmax			2.5			Mbps
Time to Shutdown	t _{SHDN}	MAX481 (Note 5)		50	200	600	ns



MAX481/MAX483/MAX485/MAX487-MAX491/MAX1487

SWITCHING CHARACTERISTICS—MAX481/MAX485, MAX490/MAX491, MAX1487 (continued)

 $(V_{CC} = 5V \pm 5\%, T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	ΤΥΡ	MAX	UNITS
Driver Enable from Shutdown to Output High (MAX481)	tzh(shdn)	Figures 7 and 9, C _L = 100pF, S2 closed		40	100	ns
Driver Enable from Shutdown to Output Low (MAX481)	tzl(shdn)	Figures 7 and 9, C _L = 100pF, S1 closed		40	100	ns
Receiver Enable from Shutdown to Output High (MAX481)	tzh(shdn)	Figures 5 and 11, C_L = 15pF, S2 closed, A - B = 2V		300	1000	ns
Receiver Enable from Shutdown to Output Low (MAX481)	tzl(shdn)	Figures 5 and 11, C_L = 15pF, S1 closed, B - A = 2V		300	1000	ns

SWITCHING CHARACTERISTICS-MAX483 MAX487/MAX488/MAX489

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX
Driver Input to Output	tplh	Figures 6 and 8, RDIFF = 54Ω ,	250	800	2000
	t _{PHL}	$C_{L1} = C_{L2} = 100 pF$	250	800	2000
Driver Output Skew to Output	t _{SKEW}	Figures 6 and 8, RDIFF = 54 Ω , CL1 = CL2 = 100pF		100	800
Driver Rise or Fall Time	t _R , t _F	Figures 6 and 8, RDIFF = 54Ω , CL1 = CL2 = 100pF	250		2000
Driver Enable to Output High	tzH	Figures 7 and 9, C _L = 100pF, S2 closed	250		2000
Driver Enable to Output Low	tzL	Figures 7 and 9, CL = 100pF, S1 closed	250		2000
Driver Disable Time from Low	t _{LZ}	Figures 7 and 9, C _L = 15pF, S1 closed	300		3000
Driver Disable Time from High	t _{HZ}	Figures 7 and 9, C _L = 15pF, S2 closed	300		3000
	t _{PLH}	Figures 6 and 10, $R_{DIFF} = 54\Omega$,	250		2000
Receiver Input to Output	t _{PHL}	$C_{L1} = C_{L2} = 100 pF$	250		2000
l t _{PLH} - t _{PHL} l Differential Receiver Skew	tskd	Figures 6 and 10, $R_{DIFF} = 54\Omega$, $C_{L1} = C_{L2} = 100pF$		100	
Receiver Enable to Output Low	tzL	Figures 5 and 11, C _{RL} = 15pF, S1 closed		20	50
Receiver Enable to Output High	tzH	Figures 5 and 11, C _{RL} = 15pF, S2 closed		20	50
Receiver Disable Time from Low	t _{LZ}	Figures 5 and 11, C _{RL} = 15pF, S1 closed		20	50
Receiver Disable Time from High	t _{HZ}	Figures 5 and 11, C _{RL} = 15pF, S2 closed		20	50

tPLH, tPHL < 50% of data period

MAX483/MAX487, Figures 7 and 9,

MAX483/MAX487, Figures 7 and 9,

MAX483/MAX487, Figures 5 and 11,

MAX483/MAX487, Figures 5 and 11,

MAX483/MAX487 (Note 5)

 $C_L = 100 pF$, S2 closed

 $C_L = 100 pF$, S1 closed

 $C_L = 15 pF$, S2 closed

 $C_{I} = 15 pF$, S1 closed

fMAX

tSHDN

tzh(shdn)

tzl(SHDN)

tzh(shdn)

tzl(shdn)



UNITS

ns

kbps

ns

ns

ns

ns

ns

600

2000

2000

2500

2500

250

50

200

Maximum Data Rate

Driver Enable from Shutdown to

Driver Enable from Shutdown to

Receiver Enable from Shutdown

Receiver Enable from Shutdown

Time to Shutdown

Output High

Output Low

to Output High

to Output Low

NOTES FOR ELECTRICAL/SWITCHING CHARACTERISTICS

- Note 1: All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.
- Note 2: All typical specifications are given for $V_{CC} = 5V$ and $T_A = +25^{\circ}C$.
- Note 3: Supply current specification is valid for loaded transmitters when DE = 0V.
- Note 4: Applies to peak current. See Typical Operating Characteristics.

(V_{CC} = 5V, T_A = +25°C, unless otherwise noted.)

Note 5: The MAX481/MAX483/MAX487 are put into shutdown by bringing \overline{RE} high and DE low. If the inputs are in this state for less than 50ns, the parts are guaranteed not to enter shutdown. If the inputs are in this state for at least 600ns, the parts are guaranteed to have entered shutdown. See Low-Power Shutdown Mode section.



Typical Operating Characteristics



M/IXI/M

_Pin Description

PIN						
MAX485/	MAX481/MAX483/ MAX485/MAX487/ MAX1487		(488/ (490	MAX489/ MAX491	NAME	FUNCTION
DIP/SO	μΜΑΧ	DIP/SO	μΜΑΧ	DIP/SO		
1	3	2	4	2	RO	Receiver Output: If A > B by 200mV, RO will be high; If A < B by 200mV, RO will be low.
2	4	_	_	3	RE	Receiver Output Enable. RO is enabled when $\overline{\text{RE}}$ is low; RO is high impedance when $\overline{\text{RE}}$ is high.
3	5	_	_	4	DE	Driver Output Enable. The driver outputs, Y and Z, are enabled by bringing DE high. They are high impedance when DE is low. If the driver outputs are enabled, the parts function as line drivers. While they are high impedance, they function as line receivers if $\overline{\text{RE}}$ is low.
4	6	3	5	5	DI	Driver Input. A low on DI forces output Y low and output Z high. Similarly, a high on DI forces output Y high and output Z low.
5	7	4	6	6, 7	GND	Ground
		5	7	9	Y	Noninverting Driver Output
		6	8	10	Z	Inverting Driver Output
6	8	_	_	_	А	Noninverting Receiver Input and Noninverting Driver Output
	_	8	2	12	А	Noninverting Receiver Input
7	1		_	_	В	Inverting Receiver Input and Inverting Driver Output
		7	1	11	В	Inverting Receiver Input
8	2	1	3	14	Vcc	Positive Supply: $4.75V \le V_{CC} \le 5.25V$
		_	_	1, 8, 13	N.C.	No Connect—not internally connected



Figure 1. MAX481/MAX483/MAX485/MAX487/MAX1487 Pin Configuration and Typical Operating Circuit



Figure 2. MAX488/MAX490 Pin Configuration and Typical Operating Circuit



Figure 3. MAX489/MAX491 Pin Configuration and Typical Operating Circuit

Applications Information

The MAX481/MAX483/MAX485/MAX487–MAX491 and MAX1487 are low-power transceivers for RS-485 and RS-422 communications. The MAX481, MAX485, MAX490, MAX491, and MAX1487 can transmit and receive at data rates up to 2.5Mbps, while the MAX483, MAX487, MAX488, and MAX489 are specified for data rates up to 250kbps. The MAX489–MAX491 are full-duplex transceivers while the MAX481, MAX483, MAX485, MAX487, and MAX1487 are half-duplex. In addition, Driver Enable (DE) and Receiver Enable (RE) pins are included on the MAX481, MAX483, MAX487, MAX481, MAX481, MAX483, MAX487, MAX489, MAX491, and MAX1487. When disabled, the driver and receiver outputs are high impedance.

MAX487/MAX1487: 128 Transceivers on the Bus

The 48k Ω , ¹/₄-unit-load receiver input impedance of the MAX487 and MAX1487 allows up to 128 transceivers on a bus, compared to the 1-unit load (12k Ω input impedance) of standard RS-485 drivers (32 transceivers maximum). Any combination of MAX487/MAX1487 and other RS-485 transceivers with a total of 32 unit loads or less can be put on the bus. The MAX481/MAX483/MAX485 and MAX488–MAX491 have standard 12k Ω Receiver Input impedance.



MAX481/MAX483/MAX485/MAX487-MAX491/MAX1487



Test Circuits



Figure 4. Driver DC Test Load



Figure 6. Driver/Receiver Timing Test Circuit

MAX483/MAX487/MAX488/MAX489: Reduced EMI and Reflections

The MAX483 and MAX487–MAX489 are slew-rate limited, minimizing EMI and reducing reflections caused by improperly terminated cables. Figure 12 shows the driver output waveform and its Fourier analysis of a 150kHz signal transmitted by a MAX481, MAX485, MAX490, MAX491, or MAX1487. High-frequency har-



Figure 5. Receiver Timing Test Load



Figure 7. Driver Timing Test Load

monics with large amplitudes are evident. Figure 13 shows the same information displayed for a MAX483, MAX487, MAX488, or MAX489 transmitting under the same conditions. Figure 13's high-frequency harmonics have much lower amplitudes, and the potential for EMI is significantly reduced.





Figure 8. Driver Propagation Delays



Figure 10. Receiver Propagation Delays



Figure 9. Driver Enable and Disable Times (except MAX488 and MAX490)



Figure 11. Receiver Enable and Disable Times (except MAX488 and MAX490)

Function Tables (MAX481/MAX483/MAX485/MAX487/MAX1487)

Table 1. Transmitting

INPUTS			OUTPUTS	
RE	DE	DI	z	Y
Х	1	1	0	1
Х	1	0	1	0
0	0	Х	High-Z	High-Z
1	0	х	High-Z*	High-Z*

X = Don't care

High-Z = High impedance Shutdown mode for MAX481/MAX483/MAX487

Table 2. Receiving

INPUTS			OUTPUT
RE	DE	A-B	RO
0	0	≥ +0.2V	1
0	0	≤ -0.2V	0
0	0	Inputs open	1
1	0	Х	High-Z*

X = Don't care

High-Z = High impedance

Shutdown mode for MAX481/MAX483/MAX487

Switching Waveforms



10





Figure 12. Driver Output Waveform and FFT Plot of MAX481/ MAX485/MAX490/MAX491/MAX1487 Transmitting a 150kHz Signal

Low-Power Shutdown Mode (MAX481/MAX483/MAX487)

A low-power shutdown mode is initiated by bringing both RE high and DE low. The devices will not shut down unless both the driver and receiver are disabled. In shutdown, the devices typically draw only $0.1\mu A$ of supply current.

RE and DE may be driven simultaneously; the parts are guaranteed not to enter shutdown if RE is high and DE is low for less than 50ns. If the inputs are in this state for at least 600ns, the parts are guaranteed to enter shutdown.

For the MAX481, MAX483, and MAX487, the t_{ZH} and t_{ZL} enable times assume the part was not in the low-power shutdown state (the MAX485/MAX488–MAX491 and MAX1487 can not be shut down). The t_{ZH}(SHDN) and t_{ZL}(SHDN) enable times assume the parts were shut down (see *Electrical Characteristics*).

It takes the drivers and receivers longer to become enabled from the low-power shutdown state ($t_{ZH}(SHDN)$), $t_{ZL}(SHDN)$) than from the operating mode (t_{ZH} , t_{ZL}). (The parts are in operating mode if the \overline{RE} , DE inputs equal a logical 0,1 or 1,1 or 0, 0.)



Figure 13. Driver Output Waveform and FFT Plot of MAX483/ MAX487–MAX489 Transmitting a 150kHz Signal

Driver Output Protection

Excessive output current and power dissipation caused by faults or by bus contention are prevented by two mechanisms. A foldback current limit on the output stage provides immediate protection against short circuits over the whole common-mode voltage range (see *Typical Operating Characteristics*). In addition, a thermal shutdown circuit forces the driver outputs into a high-impedance state if the die temperature rises excessively.

Propagation Delay

Many digital encoding schemes depend on the difference between the driver and receiver propagation delay times. Typical propagation delays are shown in Figures 15–18 using Figure 14's test circuit.

The difference in receiver delay times, \mid tpLH - tpHL \mid , is typically under 13ns for the MAX481, MAX485, MAX490, MAX491, and MAX1487 and is typically less than 100ns for the MAX483 and MAX487–MAX489.

The driver skew times are typically 5ns (10ns max) for the MAX481, MAX485, MAX490, MAX491, and MAX1487, and are typically 100ns (800ns max) for the MAX483 and MAX487–MAX489.



Figure 14. Receiver Propagation Delay Test Circuit



Figure 15. MAX481/MAX485/MAX490/MAX491/MAX1487 Receiver t_{PHL}



Figure 17. MAX483, MAX487–MAX489 Receiver tPHL



Figure 16. MAX481/MAX485/MAX490/MAX491/MAX1487 Receiver tpLH



Figure 18. MAX483, MAX487–MAX489 Receiver tPLH



Line Length vs. Data Rate

The RS-485/RS-422 standard covers line lengths up to 4000 feet. For line lengths greater than 4000 feet, see Figure 23.

Figures 19 and 20 show the system differential voltage for the parts driving 4000 feet of 26AWG twisted-pair wire at 110kHz into 120Ω loads.

Typical Applications

The MAX481, MAX483, MAX485, MAX487–MAX491, and MAX1487 transceivers are designed for bidirectional data communications on multipoint bus transmission lines.



Figure 19. MAX481/MAX485/MAX490/MAX491/MAX1487 System Differential Voltage at 110kHz Driving 4000ft of Cable

Figures 21 and 22 show typical network applications circuits. These parts can also be used as line repeaters, with cable lengths longer than 4000 feet, as shown in Figure 23.

To minimize reflections, the line should be terminated at both ends in its characteristic impedance, and stub lengths off the main line should be kept as short as possible. The slew-rate-limited MAX483 and MAX487–MAX489 are more tolerant of imperfect termination.



Figure 20. MAX483, MAX487–MAX489 System Differential Voltage at 110kHz Driving 4000ft of Cable



Figure 21. MAX481/MAX483/MAX485/MAX487/MAX1487 Typical Half-Duplex RS-485 Network





Figure 23. Line Repeater for MAX488-MAX491

Isolated RS-485

For isolated RS-485 applications, see the MAX253 and MAX1480 data sheets.

_Ordering Information (continued)

PART	TEMP. RANGE	PIN-PACKAGE
MAX481EPA	-40°C to +85°C	8 Plastic DIP
MAX481ESA	-40°C to +85°C	8 SO
MAX481MJA	-55°C to +125°C	8 CERDIP
MAX483CPA	0°C to +70°C	8 Plastic DIP
MAX483CSA	0°C to +70°C	8 SO
MAX483CUA	0°C to +70°C	8 μΜΑΧ
MAX483C/D	0°C to +70°C	Dice*
MAX483EPA	-40°C to +85°C	8 Plastic DIP
MAX483ESA	-40°C to +85°C	8 SO
MAX483MJA	-55°C to +125°C	8 CERDIP
MAX485CPA	0°C to +70°C	8 Plastic DIP
MAX485CSA	0°C to +70°C	8 SO
MAX485CUA	0°C to +70°C	8 µMAX
MAX485C/D	0°C to +70°C	Dice*
MAX485EPA	-40°C to +85°C	8 Plastic DIP
MAX485ESA	-40°C to +85°C	8 SO
MAX485MJA	-55°C to +125°C	8 CERDIP
MAX487CPA	0°C to +70°C	8 Plastic DIP
MAX487CSA	0°C to +70°C	8 SO
MAX487CUA	0°C to +70°C	8 µMAX
MAX487C/D	0°C to +70°C	Dice*
MAX487EPA	-40°C to +85°C	8 Plastic DIP
MAX487ESA	-40°C to +85°C	8 SO
MAX487MJA	-55°C to +125°C	8 CERDIP
MAX488CPA	0°C to +70°C	8 Plastic DIP
MAX488CSA	0°C to +70°C	8 SO
MAX488CUA	0°C to +70°C	8 µMAX
MAX488C/D	0°C to +70°C	Dice*
MAX488EPA	-40°C to +85°C	8 Plastic DIP
MAX488ESA	-40°C to +85°C	8 SO
MAX488MJA	-55°C to +125°C	8 CERDIP
MAX489CPD	0°C to +70°C	14 Plastic DIP
MAX489CSD	0°C to +70°C	14 SO
MAX489C/D	0°C to +70°C	Dice*
MAX489EPD	-40°C to +85°C	14 Plastic DIP
MAX489ESD	-40°C to +85°C	14 SO
MAX489MJD	-55°C to +125°C	14 CERDIP

_Ordering Information (continued)

		• •
PART	TEMP. RANGE	PIN-PACKAGE
MAX490CPA	0°C to +70°C	8 Plastic DIP
MAX490CSA	0°C to +70°C	8 SO
MAX490CUA	0°C to +70°C	8 µMAX
MAX490C/D	0°C to +70°C	Dice*
MAX490EPA	-40°C to +85°C	8 Plastic DIP
MAX490ESA	-40°C to +85°C	8 SO
MAX490MJA	-55°C to +125°C	8 CERDIP
MAX491CPD	0°C to +70°C	14 Plastic DIP
MAX491CSD	0°C to +70°C	14 SO
MAX491C/D	0°C to +70°C	Dice*
MAX491EPD	-40°C to +85°C	14 Plastic DIP
MAX491ESD	-40°C to +85°C	14 SO
MAX491MJD	-55°C to +125°C	14 CERDIP
MAX1487CPA	0°C to +70°C	8 Plastic DIP
MAX1487CSA	0°C to +70°C	8 SO
MAX1487CUA	0°C to +70°C	8 µMAX
MAX1487C/D	0°C to +70°C	Dice*
MAX1487EPA	-40°C to +85°C	8 Plastic DIP
MAX1487ESA	-40°C to +85°C	8 SO
MAX1487MJA	-55°C to +125°C	8 CERDIP

* Contact factory for dice specifications.

____Chip Topographies







Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

Printed USA

16

- ____Maxim Integrated Products, 120 San Gabriel Drive, Sunnyvale, CA 94086 (408) 737-7600
- © 1996 Maxim Integrated Products

MAXIM is a registered trademark of Maxim Integrated Products.

This datasheet has been downloaded from:

www.DatasheetCatalog.com

Datasheets for electronic components.